August 2000



LM4752 Stereo 11W Audio Power Amplifier

General Description

The LM4752 is a stereo audio amplifier capable of delivering 11W per channel of continuous average output power to a 4Ω load, or 7W per channel into 8Ω using a single 24V supply at 10% THD+N.

The LM4752 is specifically designed for single supply operation and a low external component count. The gain and bias resistors are integrated on chip, resulting in a 11W stereo amplifier in a compact 7 pin TO220 package. High output power levels at both 20V and 24V supplies and low external component count offer high value for compact stereo and TV applications. A simple mute function can be implemented with the addition of a few external components.

Key Specifications

- Output power at 10% THD+N with 1kHz into 4Ω at V_{CC} = 24V: 11W (typ)
- Output power at 10% THD+N with 1kHz into 8Ω at V_{CC} = 24V: 7W (typ)
- Closed loop gain: 34dB (typ)

Typical Application

 P_O at 10% THD+N @ 1 kHz into 4Ω single-ended TO-263 package at V_{CC} = 12V: 2.5W (typ)



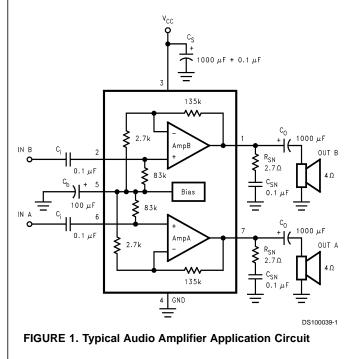
Features

- Drives 4Ω and 8Ω loads
- Internal gain resistors (A_V = 34 dB)
- Minimum external component requirement
- Single supply operation
- Internal current limiting
- Internal thermal protection
- Compact 7-lead TO-220 package
- Low cost-per-watt
- Wide supply range 9V 40V

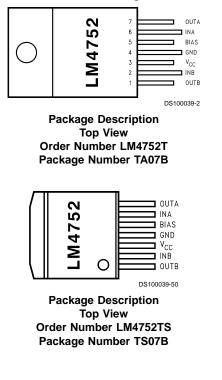
Applications

- Compact stereos
- Stereo TVs
- Mini component stereos
- Multimedia speakers

Connection Diagram



Plastic Package



Absolute Maximum Ratings (Note 2)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

40V
±0.7V
Internally Limited
62.5W
2 kV
150°C
250°C

Storage Temperature

-40°C to 150°C

Operating Ratings

Temperature Range	
$T_{MIN} \leq T_A \leq T_{MAX}$	$-40^{\circ}C \le T_A \le +85^{\circ}C$
Supply Voltage	9V to 32V
θ_{JC}	2°C/W
θ_{JA}	79°C/W

Electrical Characteristics

The following specifications apply to each channel with V_{CC} = 24V, T_A = 25°C unless otherwise specified.

	Parameter	Conditions	LM4752		11.14.
Symbol			Typical (Note 5)	Limit (Note 6)	Units (Limits)
I _{total}	Total Quiescent Power Supply	$V_{INAC} = 0V, V_o = 0V, R_L = \infty$	10.5	20	mA(max)
	Current			7	mA(min)
Po	Output Power (Continuous	$f = 1 \text{ kHz}, \text{ THD+N} = 10\%, \text{ R}_{L} = 8\Omega$	7		W
	Average per Channel)	f = 1 kHz, THD+N = 10%, $R_L = 4\Omega$		10	W(min)
		$V_{CC} = 20V, R_L = 8\Omega$	4		W
		$V_{CC} = 20V, R_{L} = 4\Omega$	7		W
		f = 1 kHz, THD+N = 10%, R _L = 4Ω V _S = 12V, TO-263 Pkg.	2.5		W
THD+N	Total Harmonic Distortion plus Noise	f = 1 kHz, $P_o = 1$ W/ch, $R_L = 8\Omega$	0.08		%
Vosw	Output Swing	$R_L = 8\Omega$, V _{CC} = 20V	15		V
		$R_L = 4\Omega$, V _{CC} = 20V	14		V
X _{talk}	Channel Separation	See Figure 1	55		dB
		f = 1 kHz, $V_o = 4$ Vrms, $R_L = 8\Omega$			
PSRR	Power Supply Rejection Ratio	See Figure 1	50		dB
		$V_{\rm CC}$ = 22V to 26V, R $_{\rm L}$ = 8 Ω			
V _{ODV}	Differential DC Output Offset Voltage	V _{INAC} = 0V	0.09	0.4	V(max)
SR	Slew Rate		2		V/µs
R _{IN}	Input Impedance		83		kΩ
PBW	Power Bandwidth	3 dB BW at $P_o = 2.5W$, $R_L = 8\Omega$	65		kHz
A _{VCL}	Closed Loop Gain (Internally Set)	$R_L = 8\Omega$	34	33	dB(min)
				35	dB(max)
e _{in}	Noise	IHF-A Weighting Filter, $R_L = 8\Omega$ Output Referred	0.2		mVrms
I _o	Output Short Circuit Current Limit	$V_{IN} = 0.5V, R_{L} = 2\Omega$		2	A(min)

Note 1: All voltages are measured with respect to the GND pin (4), unless otherwise specified.

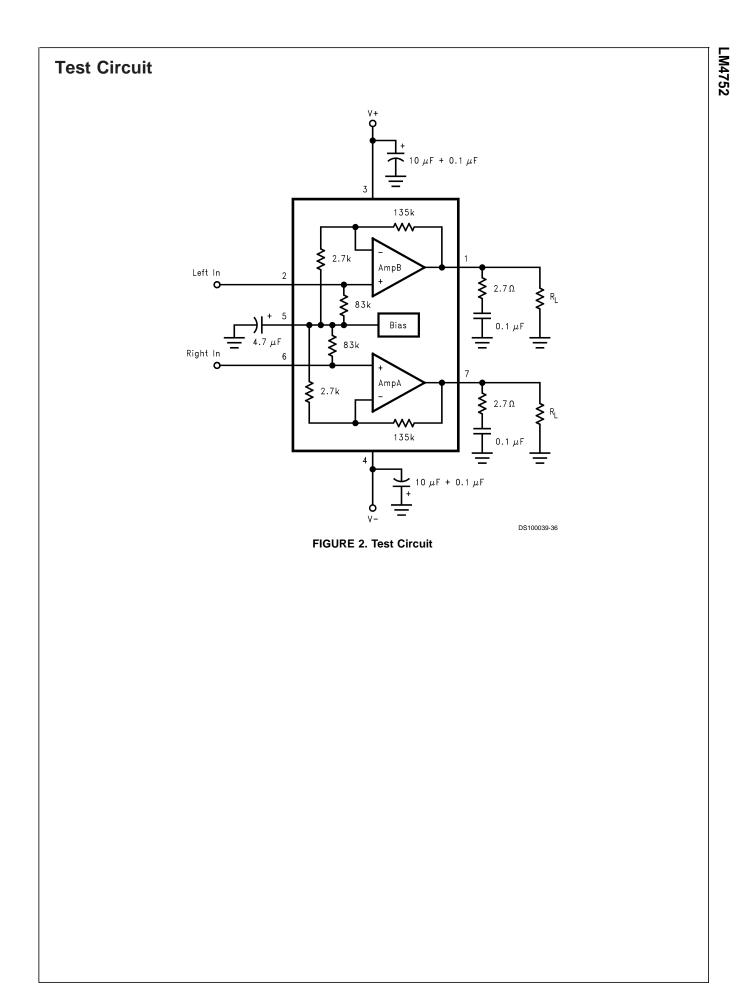
Note 2: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is functional, but do not guarantee specific performance limits. Electrical Characteristics state DC and AC electrical specifications under particular test conditions which guarantee specific performance limits. This assumes that the device is within the Operating Ratings. Specifications are not guaranteed for parameters where no limit is given, however, the typical value is a good indication of device performance.

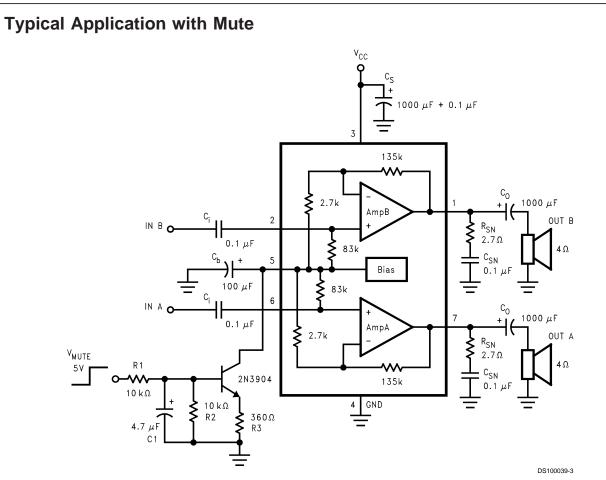
Note 3: For operating at case temperatures above 25°C, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of $\theta_{JC} = 2^{\circ}C/W$ (junction to case). Refer to the section Determining the Maximum Power Dissipation in the Application Information section for more information. Note 4: Human body model, 100 pF discharged through a 1.5 k Ω resistor.

Note 5: Typicals are measured at 25°C and represent the parametric norm.

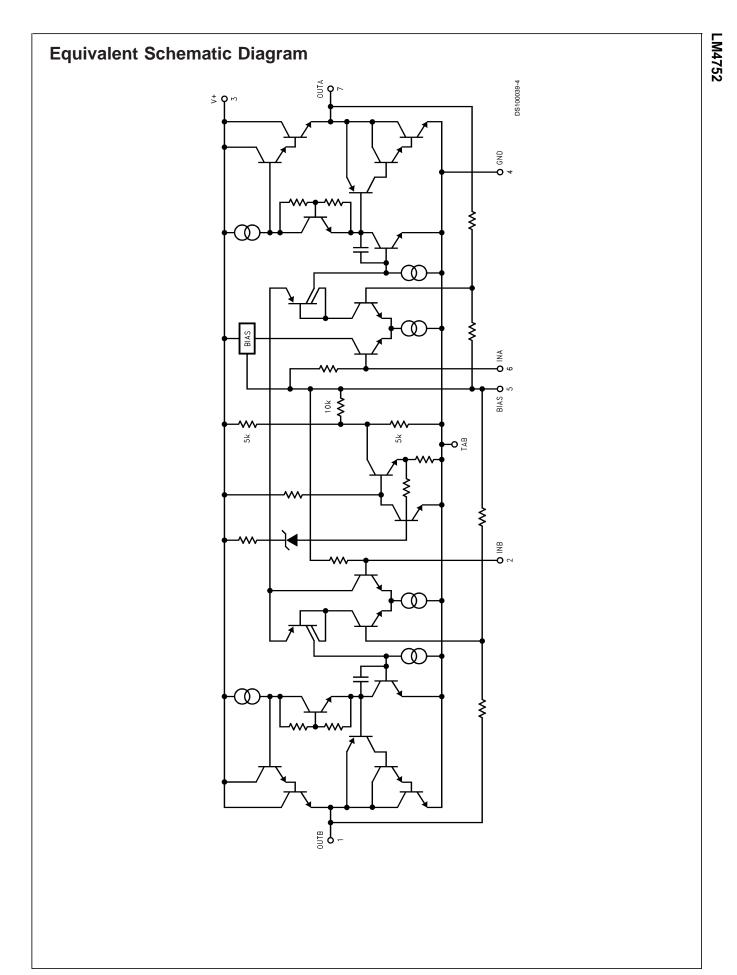
Note 6: Limits are guarantees that all parts are tested in production to meet the stated values.

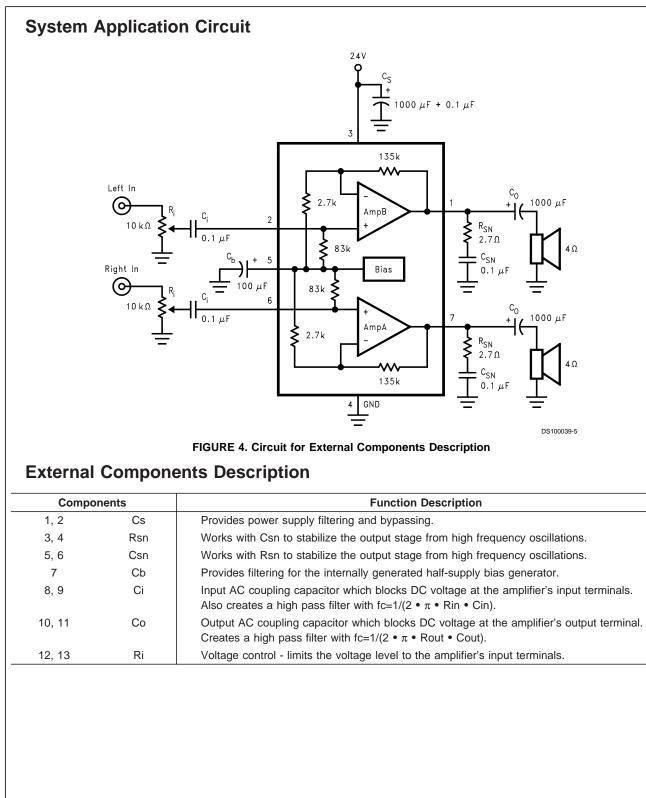
Note 7: The TO-263 Package is not recommended for $V_{\rm S}$ > 16V due to impractical heatsinking limitations.





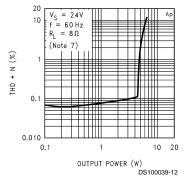




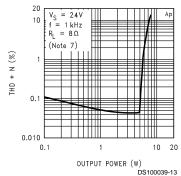


Typical Performance Characteristics

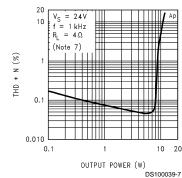
THD+N vs Output Power



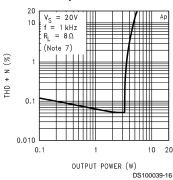
THD+N vs Output Power

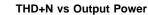


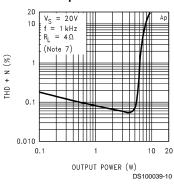
THD+N vs Output Power



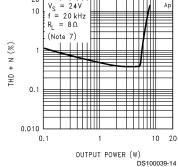
THD+N vs Output Power



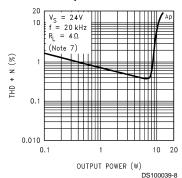




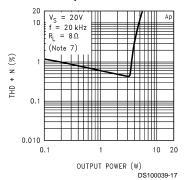
THD+N vs Output Power 20 Vs = 24V



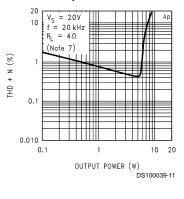
THD+N vs Output Power



THD+N vs Output Power



THD+N vs Output Power





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THD+N vs Output Power

 $V_{S} = 24V$ f = 60 Hz R_L = 4 \Omega

(Note

7)

20

10

0.010

0.1

(%)N+

OUTPUT POWER (W)

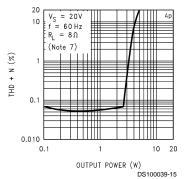
1

Ar

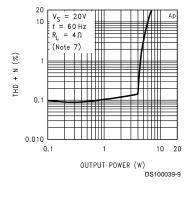
10 20

DS100039-6

THD+N vs Output Power



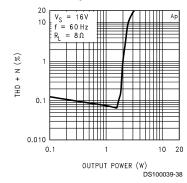
THD+N vs Output Power

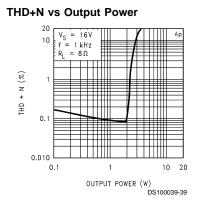




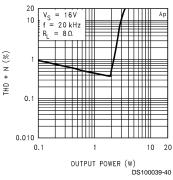
Typical Performance Characteristics (Continued)

THD+N vs Output Power

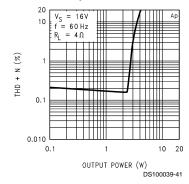




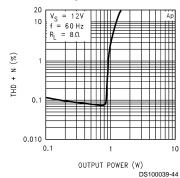
THD+N vs Output Power



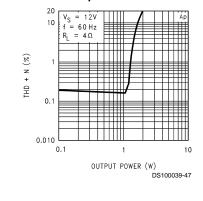
THD+N vs Output Power



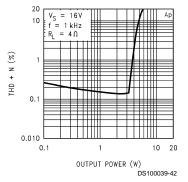
THD+N vs Output Power



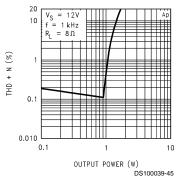
THD+N vs Output Power



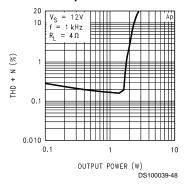




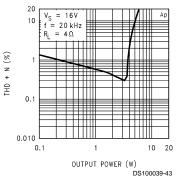
THD+N vs Output Power



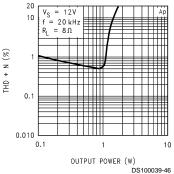
THD+N vs Output Power



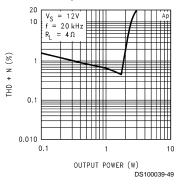
THD+N vs Output Power



THD+N vs Output Power



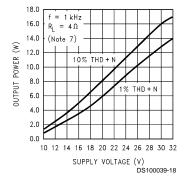
THD+N vs Output Power



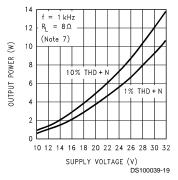
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Typical Performance Characteristics (Continued)

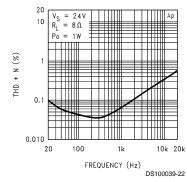
Output Power vs Supply Voltage



Output Power vs Supply Voltage



THD+N vs Frequency





THD+N vs Frequency

P0 = 1W

24

100

1k

FREQUENCY (Hz)

10k 20k

DS100039-21

 $= 4 \Omega$

10

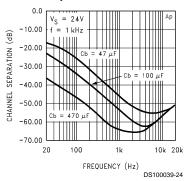
0.1

0.010

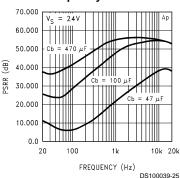
20

(%) N +

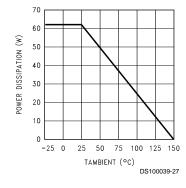
THD



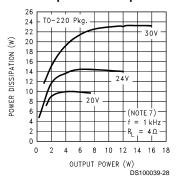
PSRR vs Frequency



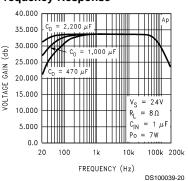




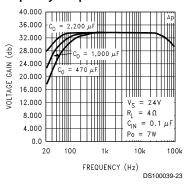
Power Dissipation vs Output Power



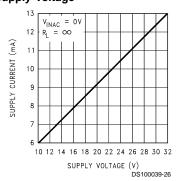
Frequency Response



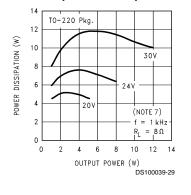




Supply Current vs Supply Voltage

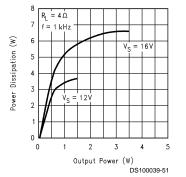


Power Dissipation vs Output Power

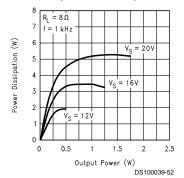


Typical Performance Characteristics (Continued)

Power Dissipation vs Output Power



Power Dissipation vs Output Power



Application Information

CAPACITOR SELECTION AND FREQUENCY RESPONSE

With the LM4752, as in all single supply amplifiers, AC coupling capacitors are used to isolate the DC voltage present at the inputs (pins 2,6) and outputs (pins 1,7). As mentioned earlier in the External Components section these capacitors create high-pass filters with their corresponding input/ output impedances. The Typical Application Circuit shown in Figure 1 shows input and output capacitors of 0.1 µF and 1,000 μ F respectively. At the input, with an 83 k Ω typical input resistance, the result is a high pass 3 dB point occurring at 19 Hz. There is another high pass filter at 39.8 Hz created with the output load resistance of 4Ω . Careful selection of these components is necessary to ensure that the desired frequency response is obtained. The Frequency Response curves in the Typical Performance Characteristics section show how different output coupling capacitors affect the low frequency rolloff.

APPLICATION CIRCUIT WITH MUTE

With the addition of a few external components, a simple mute circuit can be implemented, such as the one shown in *Figure 3*. This circuit works by externally pulling down the half supply bias line (pin 5), effectively shutting down the input stage.

When using an external circuit to pull down the bias, care must be taken to ensure that this line is not pulled down too quickly, or output "pops" or signal feedthrough may result. If the bias line is pulled down too quickly, currents induced in the internal bias resistors will cause a momentary DC voltage to appear across the inputs of each amplifier's internal differential pair, resulting in an output DC shift towards V_{SUPPLY}. An R-C timing circuit should be used to limit the pull-down time such that output "pops" and signal feedthroughs will be minimized. The pull-down timing is a function of a number of factors, including the external mute circuitry, the voltage used to activate the mute, the bias capacitor, the half-supply voltage, and internal resistances used in the half-supply generator. *Table 1* shows a list of recommended values for the external mute circuitry.

TABLE 1. Values for Mute Circuit

V _{MUTE}	R1	R2	C1	R3	Св	V _{cc}
5V	10 kΩ	10 kΩ	4.7 µF	360Ω	100 µF	21V-32V
Vs	20 kΩ	1.2 kΩ	4.7 µF	180Ω	100 µF	15V–32V
Vs	20 kΩ	910Ω	4.7 µF	180Ω	47 µF	22V-32V

OPERATING IN BRIDGE-MODE

Though designed for use as a single-ended amplifier, the LM4752 can be used to drive a load differentially (bridgemode). Due to the low pin count of the package, only the non-inverting inputs are available. An inverted signal must be provided to one of the inputs. This can easily be done with the use of an inexpensive op-amp configured as a standard inverting amplifier. An LF353 is a good low-cost choice. Care must be taken, however, for a bridge-mode amplifier must theoretically dissipate four times the power of a single-ended type. The load seen by each amplifier is effectively half that of the actual load being used, thus an amplifier designed to drive a 4 Ω load in single-ended mode should drive an 8 Ω load when operating in bridge-mode.

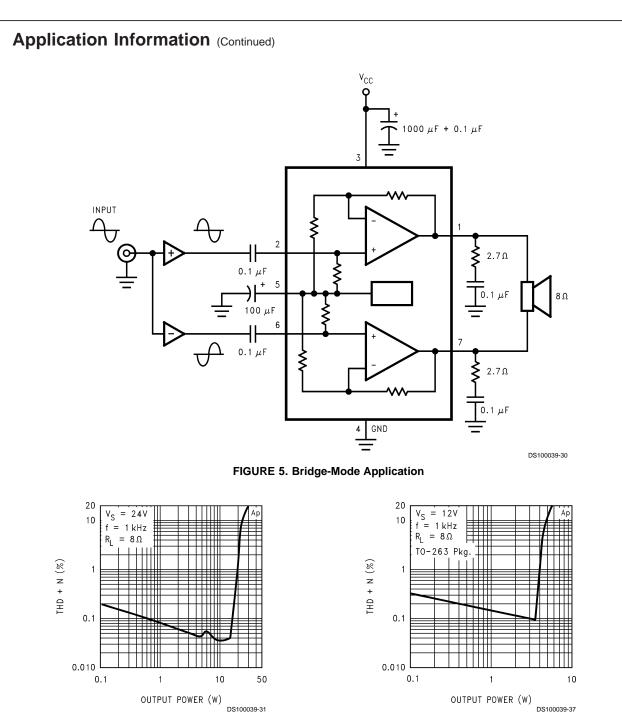


FIGURE 6. THD+N vs. Pout for Bridge-Mode Application

PREVENTING OSCILLATIONS

With the integration of the feedback and bias resistors onchip, the LM4752 fits into a very compact package. However, due to the close proximity of the non-inverting input pins to the corresponding output pins, the inputs should be AC terminated at all times. If the inputs are left floating, the amplifier will have a positive feedback path through high impedance coupling, resulting in a high frequency oscillation. In most applications, this termination is typically provided by the previous stage's source impedance. If the application will require an external signal, the inputs should be terminated to ground with a resistance of 50 k Ω or less on the AC side of the input coupling capacitors.

UNDERVOLTAGE SHUTDOWN

If the power supply voltage drops below the minimum operating supply voltage, the internal under-voltage detection circuitry pulls down the half-supply bias line, shutting down the preamp section of the LM4752. Due to the wide operating supply range of the LM4752, the threshold is set to just under 9V. There may be certain applications where a higher threshold voltage is desired. One example is a design requiring a high operating supply voltage, with large supply and bias capacitors, and there is little or no other circuitry connected to the main power supply rail. In this circuit, when the power is disconnected, the supply and bias capacitors will discharge at a slower rate, possibly resulting in audible output distortion as the decaying voltage begins to clip the out-

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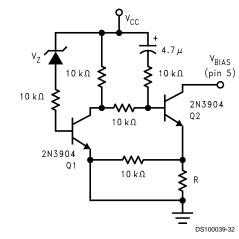
Application Information (Continued)

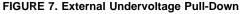
put signal. An external circuit may be used to sense for the desired threshold, and pull the bias line (pin5) to ground to disable the input preamp. *Figure 7* shows an example of such a circuit. When the voltage across the zener diode drops below its threshold, current flow into the base of Q1 is interrupted. Q2 then turns on, discharging the bias capacitor. This discharge rate is governed by several factors, including the bias capacitor value, the bias voltage, and the resistor at the emitter of Q2. An equation for approximating the value of the emitter discharge resistor, R, is given below:

$R = (0.7V) / (C_B \bullet (V_S / 2) / 0.1s)$

Note that this is only a linearized approximation based on a discharge time of 0.1s. The circuit should be evaluated and adjusted for each application.

As mentioned earlier in the **Application Circuit with Mute** section, when using an external circuit to pull down the bias line, the rate of discharge will have an effect on the turn-off induced distortions. Please refer to the **Application Circuit** with **Mute** section for more information.





THERMAL CONSIDERATIONS

Heat Sinking

Proper heatsinking is necessary to ensure that the amplifier will function correctly under all operating conditions. A heatsink that is too small will cause the die to heat excessively and will result in a degraded output signal as the internal thermal protection circuitry begins to operate.

The choice of a heatsink for a given application is dictated by several factors: the maximum power the IC needs to dissipate, the worst-case ambient temperature of the circuit, the junction-to-case thermal resistance, and the maximum junction temperature of the IC. The heat flow approximation equation used in determining the correct heatsink maximum thermal resistance is given below:

 $T_J - T_A = P_{DMAX} \bullet (\theta_{JC} + \theta_{CS} + \theta_{SA})$

where:

P_{DMAX} = maximum power dissipation of the IC

 $T_{I}(^{\circ}C)$ = junction temperature of the IC

 $T_A(^{\circ}C)$ = ambient temperature

 $\theta_{JC}(^{\circ}C/W)$ = junction-to-case thermal resistance of the IC

 $\theta_{\text{CS}}(^{\circ}\text{C/W})$ = case-to-heatsink thermal resistance (typically 0.2 to 0.5 $^{\circ}\text{C/W})$

 $\theta_{SA}(^{\circ}C/W)$ = thermal resistance of heatsink

When determining the proper heatsink, the above equation should be re-written as:

$$\theta_{SA} \leq [(T_J - T_A) / P_{DMAX}] - \theta_{JC} - \theta_{CS}$$

TO-263 HEATSINKING

Surface mount applications will be limited by the thermal dissipation properties of printed circuit board area. The TO-263 package is not recommended for surface mount applications with $V_S > 16V$ due to limited printed circuit board area. There are TO-263 package enhancements, such as clip-on heatsinks and heatsinks with adhesives, that can be used to improve performance.

Standard FR-4 single-sided copper clad will have an approximate Thermal resistance (θ_{SA}) ranging from:

1.5 x 1.5 in. sq.	20–27°C/W	(T _A =28°C, Sine wave
2 x 2 in. sa.	16–23°C/W	testing, 1 oz. Copper)

The above values for θ_{SA} vary widely due to dimensional proportions (i.e. variations in width and length will vary θ_{SA}).

For audio applications, where peak power levels are short in duration, this part will perform satisfactory with less heatsinking/copper clad area. As with any high power design proper bench testing should be undertaken to assure the design can dissipate the required power. Proper bench testing requires attention to worst case ambient temperature and air flow. At high power dissipation levels the part will show a tendency to increase saturation voltages, thus limiting the undistorted power levels.

Determining Maximum Power Dissipation

For a single-ended class AB power amplifier, the theoretical maximum power dissipation point is a function of the supply voltage, V $_{\rm S}$, and the load resistance, R $_{\rm L}$ and is given by the following equation:

(single channel)

$$P_{DMAX}(W) = [V_S^2 / (2 \bullet \pi^2 \bullet R_L)]$$

The above equation is for a single channel class-AB power amplifier. For dual amplifiers such as the LM4752, the equation for calculating the total maximum power dissipated is: (dual channel)

 $\mathsf{P}_{\mathsf{DMAX}}\left(\mathsf{W}\right) = 2 \bullet \left[\mathsf{V}_{\mathsf{S}}^{2} / \left(2 \bullet \pi^{2} \bullet \mathsf{R}_{\mathsf{L}}\right)\right]$

or

 $V_{s}^{2} / (\pi^{2} \bullet R_{I})$

(Bridged Outputs)

$$P_{DMAX}(W) = 4[V_S^2 / (2\pi^2 \bullet R_L)]$$

Heatsink Design Example:

Determine the system parameters:

$V_s = 24V$	Operating Supply Voltage
$R_{L} = 4\Omega$	Minimum load impedance
$T_A = 55^{\circ}C$	Worst case ambient temperature
Device parameter	rs from the datasheet:

T _J = 150°C	Maximum junction temperature
$\theta_{JC} = 2^{\circ}C/W$	Junction-to-case thermal resistance
Calculations:	
2 • P _{DMAX} = 2 •	• $[V_{S}^{2} / (2 \bullet \pi^{2} \bullet R_{L})] = (24V)^{2} / (2 \bullet \pi^{2} \bullet$
	$4\Omega) = 14.6W$
) / P_{DMAX}] - θ_{JC} - θ_{CS} = [(150°C - 55°C)
/ 14.6V	$1 - 2^{\circ}C/W - 0.2^{\circ}C/W = 4.3^{\circ}C/W$

Conclusion: Choose a heatsink with $\theta_{SA} \leq 4.3^{\circ}$ C/W.

Application Information (Continued)

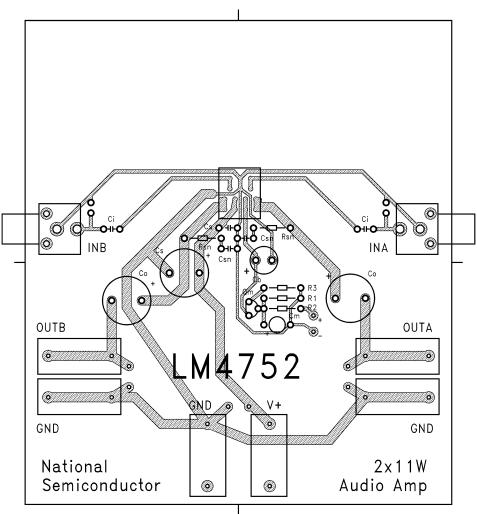
TO-263 HEATSINK DESIGN EXAMPLES: Example 1: (Stereo Single-Ended Output) T_A=30°C Given: T₁=150°C $R_1 = 4\Omega$ $V_{s}=12V$ $\theta_{\rm JC} = 2^{\circ} C/W$ P_{DMAX} from P_D vs P_O Graph: $P_{DMAX} \approx 3.7W$ Calculating P_{DMAX}: $P_{DMAX} = V_{CC}^2 / (\pi^2 R_1) = (12V)^2 / \pi^2(4\Omega)) = 3.65W$ Calculating Heatsink Thermal Resistance: $\theta_{SA} \leq [(T_J - T_A) / P_{DMAX}] - \theta_{JC} - \theta_{CS}$ $\theta_{SA} < 120^{\circ}C / 3.7W - 2.0^{\circ}C/W - 0.2^{\circ}C/W = 30.2^{\circ}C/W$ Therefore the recommendation is to use 1.5 x 1.5 square inch of single-sided copper clad. Example 2: (Stereo Single-Ended Output) Given: T_A=50°C T_J=150°C $R_1 = 4\Omega$ V_S=12V $\theta_{JC} = 2^{\circ}C/W$ P_{DMAX} from P_D vs P_O Graph: $P_{DMAX}\approx 3.7W$ Calculating P_{DMAX}: $P_{DMAX} = V_{CC}^2 / (\pi^2 R_L) = (12V)^2 / (\pi^2 (4\Omega)) = 3.65W$ Calculating Heatsink Thermal Resistance: $\theta_{SA} < [(T_J - T_A) / P_{DMAX}] - \theta_{JC} - \theta_{CS}$ $\theta_{SA} < 100^{\circ}C / 3.7W - 2.0^{\circ}C/W - 0.2^{\circ}C/W = 24.8^{\circ}C/W$ Therefore the recommendation is to use 2.0 x 2.0 square inch of single-sided copper clad. Example 3: (Bridged Output) Given: T_A=50°C T_{.1}=150°C $R_1 = 8\Omega$ $V_{S}=12V$ $\theta_{JC} = 2^{\circ}C/W$ Calculating P_{DMAX}: $P_{DMAX} = 4[V_{CC}^2 / (2\pi^2 R_L)] = 4(12V)^2 / (2\pi^2(8\Omega)) = 3.65W$ Calculating Heatsink Thermal Resistance: $\theta_{SA} \leq [(T_J - T_A) / P_{DMAX}] - \theta_{JC} - \theta_{CS}$ $\theta_{SA} < 100^{\circ}C / 3.7W - 2.0^{\circ}C/W - 0.2^{\circ}C/W = 24.8^{\circ}C/W$ Therefore the recommendation is to use 2.0 x 2.0 square inch of single-sided copper clad.

Layout and Ground Returns

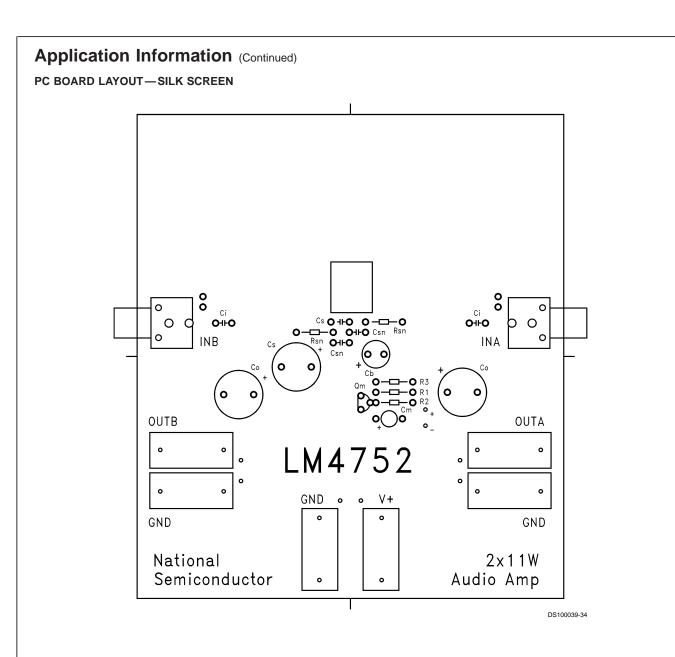
Proper PC board layout is essential for good circuit performance. When laying out a PC board for an audio power amplifer, particular attention must be paid to the routing of the output signal ground returns relative to the input signal and bias capacitor grounds. To prevent any ground loops, the ground returns for the output signals should be routed separately and brought together at the supply ground. The input signal grounds and the bias capacitor ground line should also be routed separately. The 0.1 µF high frequency supply bypass capacitor should be placed as close as possible to the IC.

Application Information (Continued)

PC BOARD LAYOUT—COMPOSITE

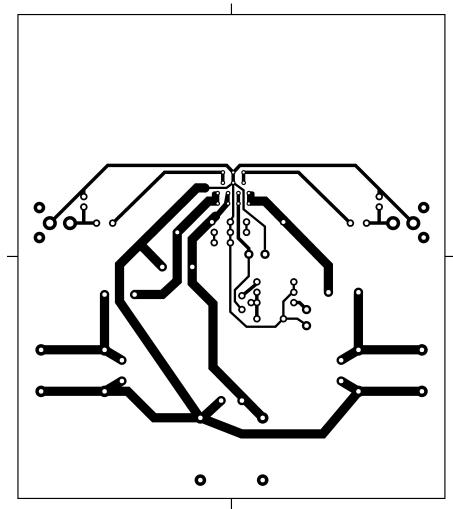


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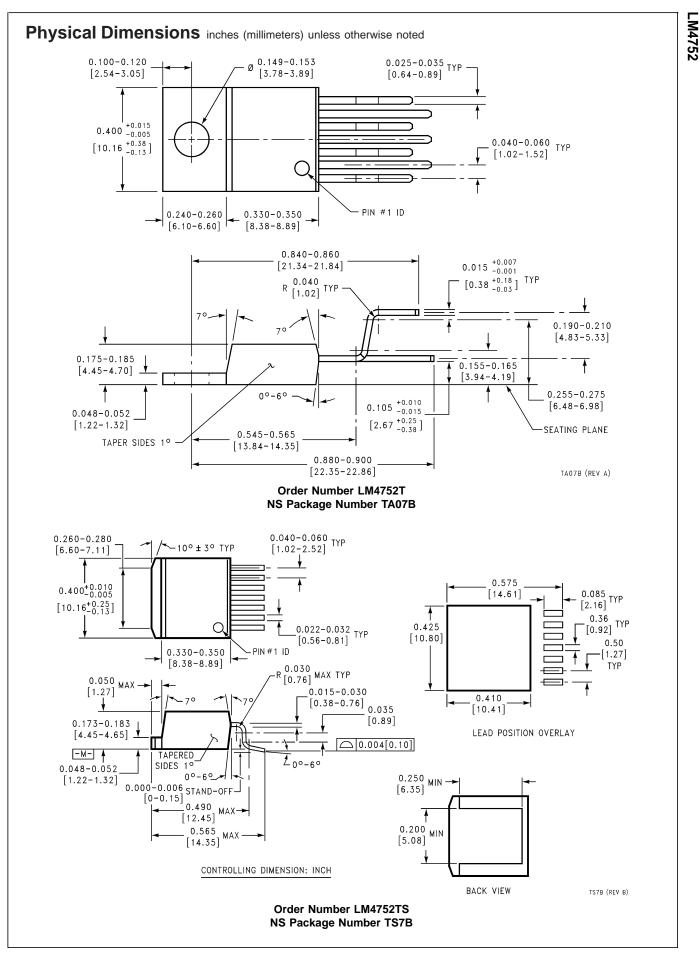


Application Information (Continued)

PC BOARD LAYOUT—SOLDER SIDE



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Physical Dimensions inches (millimeters) unless otherwise noted (Continued)

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