

# 2D/3D Profile Sensor

## OPT3013 LASER

Part Number

weCat3D



- Optimized profile quality thanks to HDR function
- Precise measuring range resolution X (> 2000 measuring points)
- Up to 12 million measuring points per second

2D/3D Profile Sensors project a laser line onto the object to be detected and generate an accurate, linearized height profile with an internal camera which is set up at a triangulation angle. Thanks to its uniform, open interface, the weCat3D series can be incorporated by means of the DLL program library or the GigE Vision standard without an additional control unit. Alternatively, weinglor offers its own software packages for implementing your application.

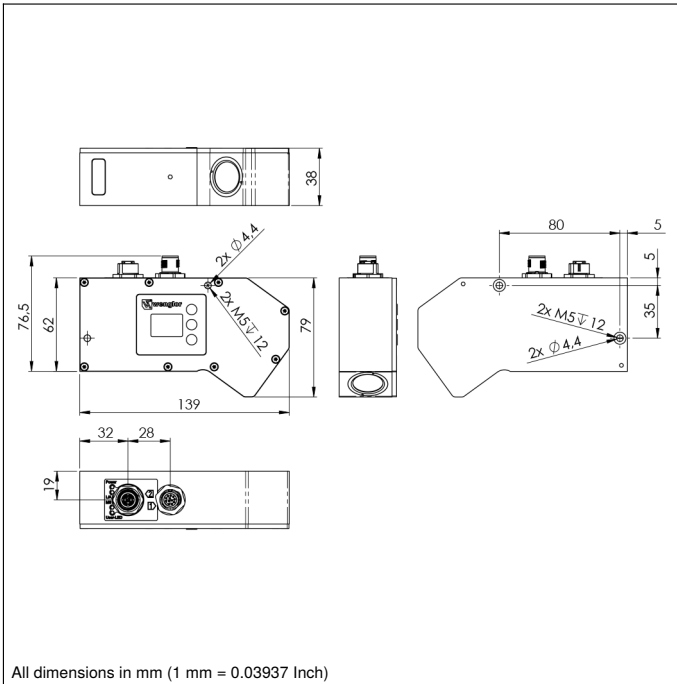


### Technical Data

Optical Data	
Working range Z	83...213 mm
Measuring range Z	130 mm
Visual field width X	50...110 mm
Linearity Deviation	32,5 µm
Resolution Z	3,2...14 µm
Resolution X	26...55 µm
Light Source	Laser, UV/red
Wavelength	375 / 660 nm
Service Life (T = +25 °C)	20000 h
Laser Class (EN 60825-1)	2
Max. Ambient Light	5000 Lux
Electrical Data	
Supply Voltage	18...30 V DC
Current Consumption (U <sub>b</sub> = 24 V)	1500 mA
Measuring Rate	180...6000 /s
Subsampling	350...6000 /s
Temperature Range	0...45 °C
Storage temperature	-20...70 °C
Inputs/Outputs	4
Switching Output Voltage Drop	< 1,5 V
Switching Output/Switching Current	100 mA
Short Circuit Protection	yes
Reverse Polarity Protection	yes
Overload Protection	yes
Interface	Ethernet TCP/IP
Baud Rate	100/1000 Mbit/s
Protection Class	III
Mechanical Data	
Housing Material	Aluminum
Degree of Protection	IP67
Connection	M12 × 1; 12-pin
Type of Connection Ethernet	M12 × 1; 8-pin
Optic Cover	Glass
Weight	600 g
Web server	yes
Configurable as PNP/NPN/Push-Pull	<input checked="" type="checkbox"/>
Switchable to NC/NO	<input checked="" type="checkbox"/>
Connection Diagram No.	<b>1022</b> <b>1034</b>
Control Panel No.	<b>X2</b> <b>A22</b>
Suitable Connection Equipment No.	<b>50</b> <b>87</b>
Suitable Mounting Technology No.	<b>343</b>

### Complementary Products

Control Unit	
Cooling Unit ZLWK002	
Protective Screen Retainer ZLWS002	
Software	
Switch EHSS001	



### Ctrl. Panel



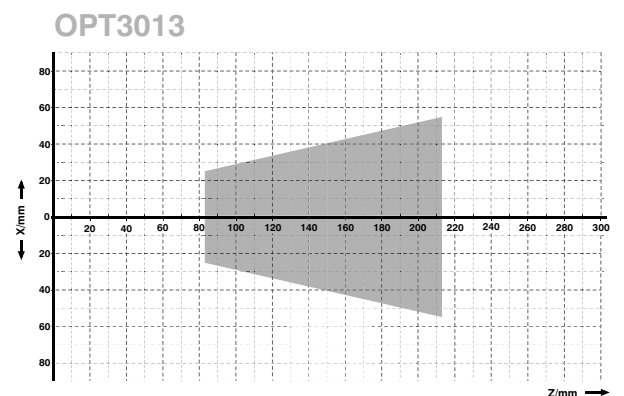
- 20 = Enter Button
- 22 = UP Button
- 23 = Down Button
- 4a = User LED
- 60 = Display
- 68 = Supply Voltage Indicator
- 78 = Module status
- 85 = Link/Act LED



### Legend

+	Supply Voltage +	PT	Platinum measuring resistor	EN <sup>A</sup> RS422	Encoder A/ $\bar{A}$ (TTL)
-	Supply Voltage 0 V	nc	not connected	EN <sup>B</sup> RS422	Encoder B/ $\bar{B}$ (TTL)
~	Supply Voltage (AC Voltage)	U	Test Input	EN <sup>A</sup>	Encoder A
A	Switching Output (NO)	$\bar{U}$	Test Input inverted	EN <sup>B</sup>	Encoder B
$\bar{A}$	Switching Output (NC)	W	Trigger Input	A <sub>MIN</sub>	Digital output MIN
V	Contamination/Error Output (NO)	W-	Ground for the Trigger Input	A <sub>MAX</sub>	Digital output MAX
$\bar{V}$	Contamination/Error Output (NC)	O	Analog Output	A <sub>OK</sub>	Digital output OK
E	Input (analog or digital)	O-	Ground for the Analog Output	SY <sub>in</sub>	Synchronization In
T	Teach Input	BZ	Block Discharge	SY <sub>OUT</sub>	Synchronization OUT
Z	Time Delay (activation)	AWV	Valve Output	OLT	Brightness output
S	Shielding	a	Valve Control Output +	M	Maintenance reserved
RxD	Interface Receive Path	b	Valve Control Output 0 V	rsv	reserved
TxD	Interface Send Path	SY	Synchronization	Wire Colors according to IEC 60757	
RDY	Ready	SY-	Ground for the Synchronization	BK	Black
GND	Ground	E+	Receiver-Line	BN	Brown
CL	Clock	S+	Emitter-Line	RD	Red
E/A	Output/Input programmable	$\pm$	Grounding	OG	Orange
	IO-Link	S <sub>n</sub> R	Switching Distance Reduction	YE	Yellow
PoE	Power over Ethernet	Rx+/-	Ethernet Receive Path	GN	Green
IN	Safety Input	Tx+/-	Ethernet Send Path	BU	Blue
OSSD	Safety Output	Bus	Interfaces-Bus A(+)/B(-)	VT	Violet
Signal	Signal Output	L <sub>a</sub>	Emitted Light disengageable	GY	Grey
Bi_D+/-	Ethernet Gigabit bidirect. data line (A-D)	Mag	Magnet activation	WH	White
EN <sup>0</sup> RS422	Encoder 0-pulse 0-0 (TTL)	RES	Input confirmation	PK	Pink
		EDM	Contactur Monitoring	GNYE	Green/Yellow

### Measuring field X, Z



Z = Working distance  
 X = Measuring Range

