Pneumatics

Rexroth Bosch Group

4/2 and 4/3 proportional directional valves, direct operated, with electrical position feedback, without/with integrated electronics (OBE)

RE 29061/11.12 Replaces: 05.12



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Component series 2X

Maximum operating pressure 315 bar

Size 6 and 10

Maximum flow:

Type 4WRE and 4WREE

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80 l/min (size 6) 180 l/min (size 10)

Features

- Direct operated proportional directional valve with electrical position feedback and integrated electronics (OBE) with type 4WREE
- Control of flow direction and size
- Operation by means of proportional solenoids with central thread and detachable coil
- For subplate mounting: Porting pattern according to ISO 4401
- Spring-centered control spool
- Control electronics
- Type 4WREE:

integrated electronics (OBE) with voltage or current input (A1 and/or F1)

- Type 4WRE (4/3 version), separate order:
- digital and analog amplifier in Euro-card format
- analog amplifier in modular design
- Type 4WRE...A (4/2 version), separate order:
- analog amplifier in modular design

Information on available spare parts: www.boschrexroth.com/spc

Ordering code

	4WRE		2X/	′ G24	/	\	/	*	-
Without integrated electronics (OBE)	= no cod	le							Further details in the plain text
With integrated		-							Seal material
electronics (OBE)	=						V =		FKM seals ¹⁾
Size 6 Size 10		= 6 = 10							Electronic interface
		= 10				A1 = F1 =		<u> </u>	Command value ±10 V
Control spool symbols	A B	-				F1 =			imand value 4 to 20 mA
	a 0 b					no c	oae	=	Type 4WRE
	<u> і і і і</u>	-							Electrical connection
	F I				K4 =			\ \/i +	Type 4WRE: hout mating connector,
		= E E1-						w onn	to DIN EN 175301-803 ector (solenoid, position arate order, see page 8
							, , ,	-	Type 4WREE:
		= V V1-			K31 :		tina	W	hout mating connector, ith connector according to DIN EN 175201-804 nector – separate order,
		-					9		see page 9
	│X"╠╩╬╽╿╷	↓ = W							Supply voltage
		₩ W1-	•	G24	=				Direct voltage 24 V
			2X	=					20 to 29
						(20 to	29:	: unc	changed installation and
									connection dimensions)
	a 0			Rated fl	ow at v	alve p	ores	sure	differential $\Delta p = 10$ bar
	P T								Size 6
			04 =						4 l/min
			08 =						8 l/min 16 l/min
		= EA	32 =						32 l/min
			52 =						Size 10
			25 =						25 l/min
		147.4	50 =						50 l/min
	╙┻╨╪╫	= WA	75 =						75 l/min

With symbol E1-, V1- and W1-:

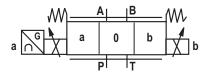
$$\begin{array}{ll} \mathsf{P} \rightarrow \mathsf{A} \text{:} \; \pmb{q}_{\mathsf{V}\,\mathsf{max}} & \mathsf{B} \rightarrow \mathsf{T} \text{:} \; \pmb{q}_{\mathsf{V}}/2 \\ \mathsf{P} \rightarrow \mathsf{B} \text{:} \; \pmb{q}_{\mathsf{V}}/2 & \mathsf{A} \rightarrow \mathsf{T} \text{:} \; \pmb{q}_{\mathsf{V}\,\mathsf{max}} \end{array}$$

In the zero position, spools W and WA have a connection from A to T and B to T with approx. 3 % of the relevant nominal cross-section.

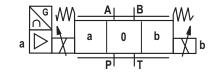
¹⁾ Design SO660 with NBR seals at the valve connection surface

Symbols

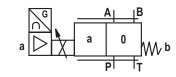
Proportional directional valve without integrated electronics Type 4WRE...



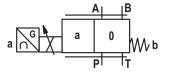
Proportional directional valve with integrated electronics Type 4WREE...



Type 4WREE...A...



Type 4WRE...**A**...



Function, section

Type 4WRE ...-2X/...

The 4/2 and 4/3 proportional directional valves are designed as direct operated devices in plate design. Operation is effected by proportional solenoids with central thread and detachable coil. The solenoids are controlled by external electronics.

Set-up:

The valve basically consists of:

- Housing (1) with connection surface
- Control spool (2) with compression springs (3 and 4) and spring plate (5 and 6)

The PG fitting (11) must not be opened. Mechanical ad-

justment of the adjustment nut located below is prohibit-

- Solenoids (7 and 8) with central thread
- Position transducer (9)

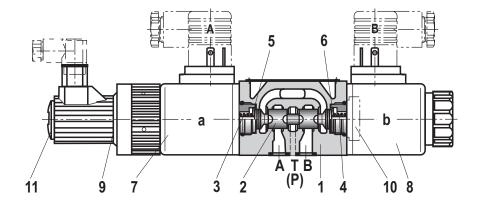
Important note!

ed and damages the valve!

Function:

- With de-energized solenoids (7 and 8), central position of the control spool (2) by compression springs (3 and 4) between spring plates (5 and 6)
- Direct operation of the control spool (2) by controlling a proportional solenoid, e.g. solenoid "b" (8)
 - → Displacement of the control spool (2) to the left proportional to the electric input signal
 - → Connection from P to A and B to T via orifice-type cross-sections with progressive flow characteristic
- Switching off of the solenoid (8)
 - → The compression spring (3) brings the control spool (2) back into the central position

In the de-energized condition, the control spool (2) is held in a mechanical central position by the return springs. With control spool symbol "V", this position does not correspond to the hydraulic central position! When the electric valve control loop is closed, the control spool is positioned in the hydraulic central position.



Valve with 2 spool positions: (Type 4WRE...A...)

The function of this valve design basically corresponds to the valve with three spool positions. The 2 spool position valves are, however, only equipped with solenoid "a" (7). Instead of the 2nd proportional solenoid, there is a plug screw (10).

If Notice!

Due to the design principle, internal leakage is inherent to the valves, which may increase over the life cycle.

Notice!

The tank line must not be allowed to run empty. With corresponding installation conditions, a pre-charge valve (pre-charging pressure approx. 2 bar) is to be installed.

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The valve basically consists of:

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- Control spool (2) with compression springs (3 and 4) and spring plate (5 and 6)
- Solenoids (7 and 8) with central thread
- Position transducer (9)
- Integrated electronics (13)
- Electric zero point adjustment (12) accessible via Pg7

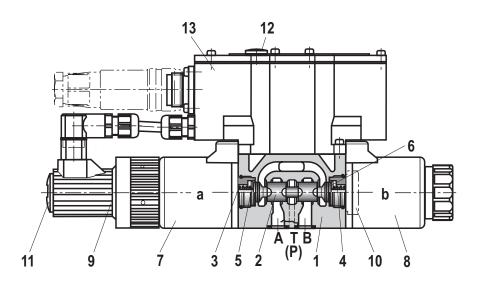
F Important note!

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Technical data (For applications outside these parameters please consult us!)

general				
Sizes		Size	6	10
Weight	– Type 4WRE	kg	2.2	6.3
	– Type 4WREE	kg	2.4	6.5
Installation position			Any, preferably horizontal	l
Ambient temperature range	 Type 4WRE 	°C	-20 to +70	
	– Type 4WREE	°C	-20 to +50	
Storage temperature range		°C	-20 to +80	
MTTF _d values according to EN ISO 13849		Years	150 ¹⁾ (for more information	on see data sheet 08012)

hydraulic (measured with HLP46, $\vartheta_{oil} = 40 \text{ °C} \pm 5 \text{ °C}$ and p = 100 bar)

Maximum operating	– Port A, B, P	bar	3	15
pressure	– Port T	bar	2	10
Rated flow <i>q</i> _{V rated} with <i>L</i>	p = 10 bar	l/min	4, 8, 16, 32	25, 50, 75
Recommended maximu	m flow	l/min	80	180
Hydraulic fluid			See table below	
Hydraulic fluid temperate	ure range	°C	-20 to +80 (preferably +40 to +50)	
Viscosity range mm ² /s			20 to 380 (preferably 30 to 46)	
Maximum admissible degree of contamination of the hydraulic fluid, cleanliness class according to ISO 4406 (c)			Class 20/18/15 ²⁾	
Hysteresis %		≤ 0.1		
Range of inversion %		6 ≤ 0.05		
Response sensitivity %		6 ≤ 0.05		
Zero shift upon change of hydraulic fluid temperature and operating pressure		%/10 K	≤ 0.15	
		%/100 bar	≤ 0.1	

¹⁾ With control spool types E, E1, EA, W, W1, WA; in longitudinal control spool direction, there is sufficient positive overlap without shock/vibration load; observe the installation orientation with regard to the main direction of acceleration.

²⁾ The cleanliness classes specified for the components must be adhered to in hydraulic systems. Effective filtration prevents faults and at the same time increases the service life of the components. For the selection of the filters see www.boschrexroth.com/filter

Hydraulic fluid		Classificatio	on	Suitable sealing materials	Standards
Mineral oils and relate	ed hydrocarbons	HL, HLP		NBR, FKM	DIN 51524
Flame-resistant	 Containing water 	HFC (Fuchs Petrofer Ultra	HYDROTHERM 46M, a Safe 620)	NBR	ISO 12922
 Important information on hydraulic fluids! For more information and data on the use of other hydraulic fluids refer to data sheet 90220 or contact us! There may be limitations regarding the technical valve data (temperature, pressure range, service life, maintenance intervals, etc.)! 		differential per contro at the tank port > 20 s wise, increased cavita	ater-containing: Maximu I edge 175 bar. Pressure % of the pressure differe ation. ed to operation with mine	e pre-loading ntial; other-	
	ne process and operating mee r than the maximum solenoid				

Technical data (For applications outside these parameters please consult us!)

electric				
Size		Size	6	10
Voltage type			Direct voltage	
Solenoid coil	 Cold value at 20 °C 	Ω	2.65	4.55
resistance	- Maximum hot value	Ω	4.05	6.82
Duty cycle		%	100	
Maximum coil temperature ¹⁾ °C		up to 150		
Electrical connection	– Type 4WRE		With connector according to	DIN EN 175301-803 and ISO 4400
see page 8 and 9		Mating connector according to	DIN EN 175301-803 and ISO 4400 ²⁾	
– Type 4WREE		With connector DIN EN 175201-804		
			Mating connector DIN EN 17	5201-804 ²⁾
Protection class of the valve according to EN 60529		IP65 with mating connector n	nounted and locked	

Control electronics

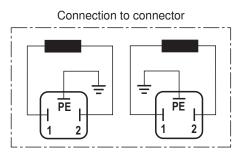
Type 4WRE	4/3 version				
	Amplifier in	Digital	VT-VRPD-2-2X/V0/0 according to RE 30126		
	euro-card format ²⁾	Analog	VT-VRPA2-1-1X/V0	VT-VRPA2-2-1X/V0	
			according to data sheet 30119	according to data sheet 30119	
	Module amplifier ²⁾	Analog	VT-MRPA2-1 according to data sheet 30219	VT-MRPA2-2 according to data sheet 30219	
Type 4WREA	4/2 version				
	Module amplifier ²⁾	Analog	VT-MRPA1-1 according to data sheet 30219	VT-MRPA1-2 according to data sheet 30219	
Type 4WREE			Integrated in the valve, see page 9		
	analog command val	ue module	VT- SWMA-1-1X/ according to data sheet 29902		
	analog command val	ue module	VT-SWMAK-1-1X/ according to data sheet 29903		
	analog command valu	ue card	VT-SWKA-1-1X/ according to	data sheet 30255	
	digital command valu	e card	VT-HACD -1-1X/ according to	data sheet 30143	
Supply voltage	Nominal voltage	VDC	24		
	lower limit value	V	19.4		
	upper limit value	V	35		
Current consumptio	n I _{max}	A	< 2		
of the amplifier	Pulse current	A	3		

¹⁾ Due to the temperatures occurring at the surfaces of the solenoid coils, the European standards ISO 13732-1 and EN ISO 4413 need to be adhered to! Notice: For information on the environmental simulation testing for the areas EMC (electromagnetic compatibility), climate and mechanical load see data sheet 29061-U (declaration on environmental compatibility).

²⁾ Separate order

Electrical connection, mating connectors (dimensions in mm)

Type 4WRE (without integrated electronics)



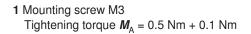
Mating connector CECC 75 301-803-A002FA-H3D08-G according to DIN EN 175301-803 and ISO 4400

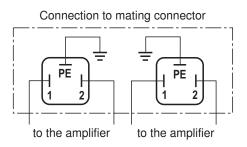
Solenoid **a**, color gray

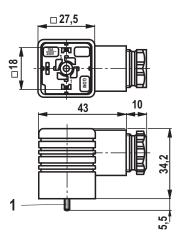
separate order under the Material no. R901017010

Solenoid **b**, color black

separate order under the Material no. R901017011

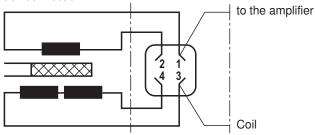




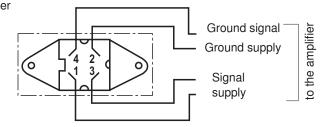


Inductive position transducer

Coil connection



Connection to plug-in connector



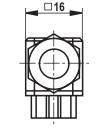
Mating connector 4-pole Pg7-G4W1F

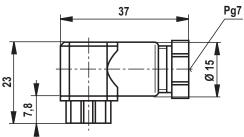
separate order under the Material no. $\ensuremath{\textbf{R900023126}}$

Connection cable:

Recommendation:

up to 50 m cable length type LiYCY 4 x 0.25 mm² Connect shield to PE only on the supply side.

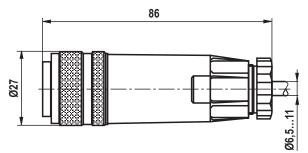




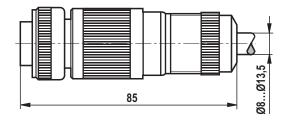
Electrical connection, mating connectors (dimensions in mm)

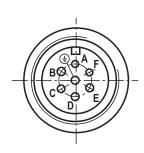
Type 4WREE (with integrated electronics (OBE)

Mating connector according to DIN EN 175201-804 separate order under the Material no. **R900021267** (plastic version) Angular design – separate order under the Material no. **R900217845** Pin assignment see also block diagram page 10



Mating connector according to DIN EN 175201-804 separate order under the Material no. **R900223890** (metal version)





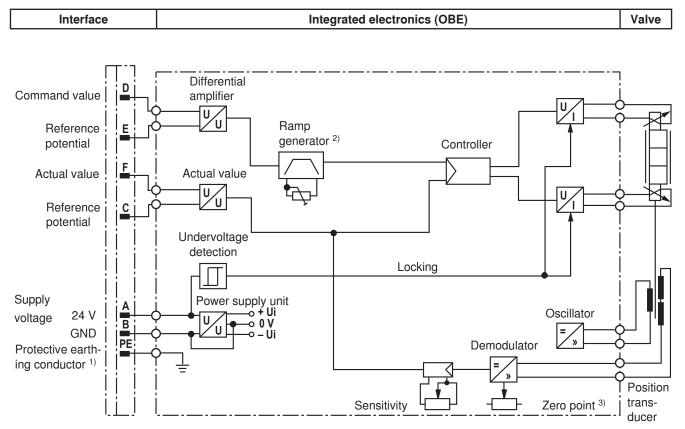
Device connector allocation	Contact	Signal with A1 interface	Signal with F1 interface	
Supply voltage	Α	24 VDC (<i>u</i> (t) = 19.4 to 35 V); <i>I</i> _{max} = 2 A		
	В		0 V	
Reference potential actual value	С	Reference contact F; $R_{e} > 50 \text{ k}\Omega$	Reference contact F; R_{e} < 10 Ω	
Differential amplifier input	D	±10 V command value; $R_{e} > 50 \text{ k}\Omega$	4 to 20 mA command value; $R_{\rm e}$ > 100 Ω	
	E	Reference poter	ntial command value	
Measuring output (actual value)	F	±10 V actual value (limit load 5 mA)	4 to 20 mA actual value, load resistance max. 300 Ω	
	PE	Connected to cooling	element and valve housing	

Command value	: Positive command value 0 to +10 V (or 12 to 20 mA) at D and reference potential at E result in flow from $P \rightarrow A$ and $B \rightarrow T$.
	Negative command value 0 to -10 V (or 12 to 4 mA) at D and reference potential at E result in flow from P \rightarrow B and A \rightarrow T.
	For valves with 1 solenoid on side a (e. g. variant EA and WA), a positive command value 0 to +10 V (or 4 to 20 mA) at D and reference potential at E result in flow from $P \rightarrow B$ and $A \rightarrow T$.
Actual value:	Actual value 0 to +10 V (or 12 to 20 mA) at F and reference potential at C result in flow from P \rightarrow A and B \rightarrow T, actual value 0 to -10 V (or 4 to 12 mA) result in flow from P \rightarrow B and A \rightarrow T.
	With valves with 1 solenoid, a positive actual value 0 to +10 V (or 4 to 20 mA) at F and reference potential at C result in flow from P \rightarrow B and A \rightarrow T.
Connection cab	 le: Recommendation: – up to 25 m cable length type LiYCY 7 x 0.75 mm² – up to 50 m cable length type LiYCY 7 x 1.0 mm²
	External diameter see sketch of mating connector
	Connect chield to DE only on the cumply side

Connect shield to PE only on the supply side.

Integrated electronics (OBE) type 4WREE

Block diagram / pin assignment



Notice: Electric signals taken out via control electronics (e.g. actual value) must not be used for switching off safetyrelevant machine functions!

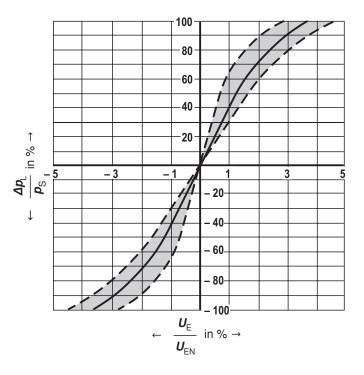
¹⁾ The protective earthing conductor (PE) is connected to cooling ±10 V/4...20 mA actual position element and valve housing! +24 V ²⁾ Ramp can be set from 0 to 2.5 s from the outside, identical for A 0 V T_{up} and T_{down} B E \bigcirc ³⁾ Zero point can be set from the outside E \bigcirc **D** Reference actual position ±10 V/4...20 mA signal input 2) 3) Reference input Symbol () ۲ ۲ xxxx Zero xxxxxxx ۲ xxxxxx æ Material no. Valve type Serial valve no. to the Internal manufacmanufacturing order turing order no. Year of construction, week of construction + country code

Characteristic curves: Type 4WREE (measured with HLP46, $\vartheta_{Oil} = 40 \text{ °C} \pm 5 \text{ °C}$) Size 6 and 10

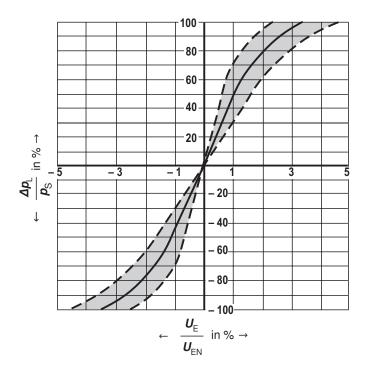
Pressure signal characteristic curve (control spool V),

 $p_{\rm s}$ = 100 bar

Size 6

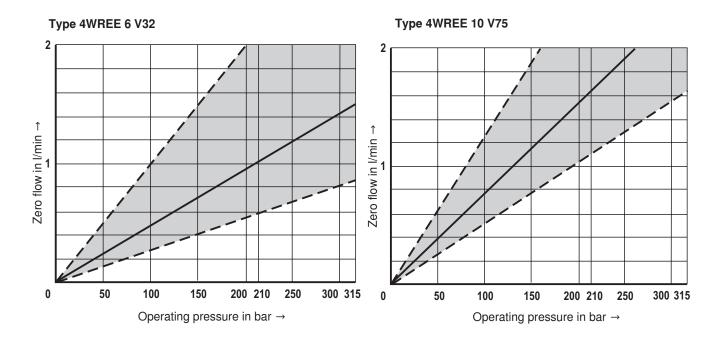


Size 10

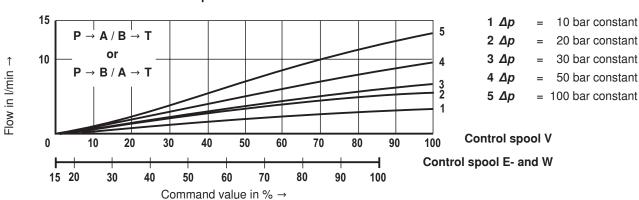


Characteristic curves: Type 4WREE (measured with HLP46, $\vartheta_{Oil} = 40 \text{ °C} \pm 5 \text{ °C}$) Size 6 and 10

Zero flow with central control spool position



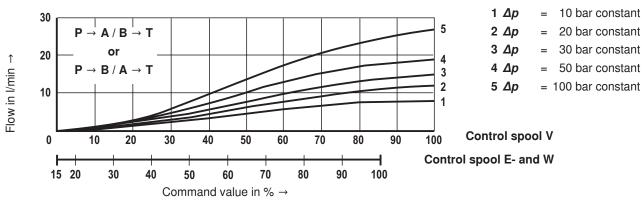
Characteristic curves: Type 4WREE (measured with HLP46, $\vartheta_{Oil} = 40 \text{ °C} \pm 5 \text{ °C}$ and p = 100 bar) Size 6



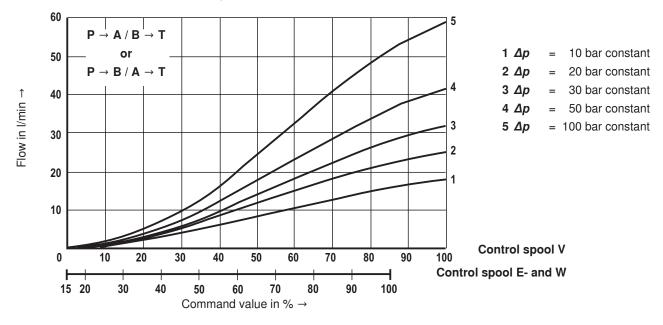
4 l/min rated flow with 10 bar valve pressure differential

Characteristic curves: Type 4WREE (measured with HLP46, $\vartheta_{Oil} = 40 \text{ °C} \pm 5 \text{ °C}$ and p = 100 bar) Size 6

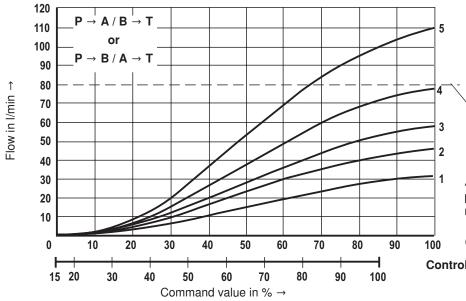
8 l/min rated flow with 10 bar valve pressure differential



16 l/min rated flow with 10 bar valve pressure differential



32 l/min rated flow with 10 bar valve pressure differential



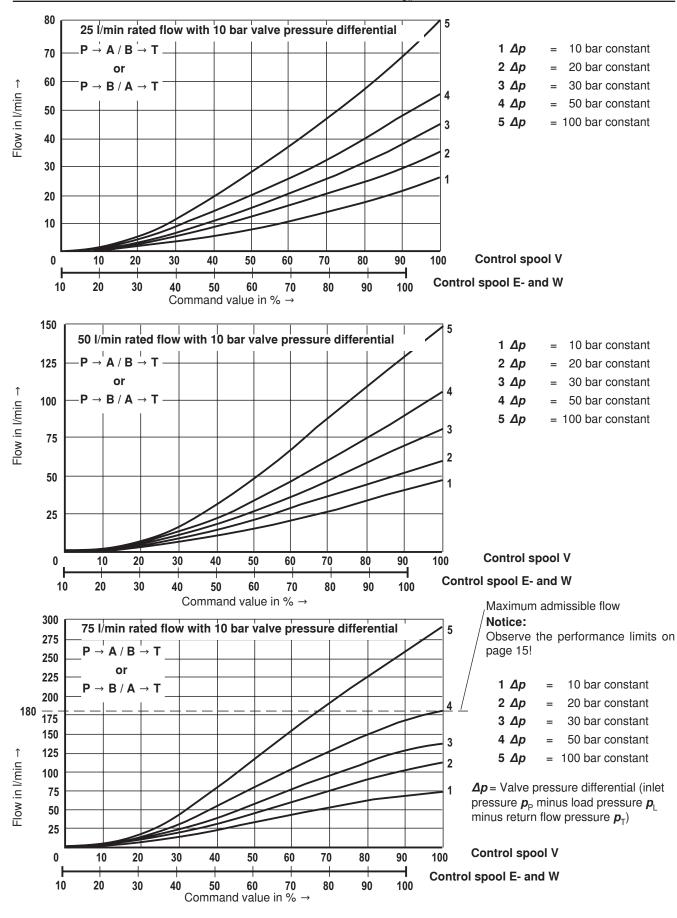
10 bar constant 1 Δp _ 2 Δp 20 bar constant = 3 **∆**p 30 bar constant 4 **∆**p 50 bar constant 5 Δp 100 bar constant = Maximum admissible flow Notice: Observe the performance limits on page 15!

 Δp = Valve pressure differential (inlet pressure $p_{\rm P}$ minus load pressure $p_{\rm L}$ minus return flow pressure $p_{\rm T}$)

Control spool V

Control spool E- and W





4/3 valve version

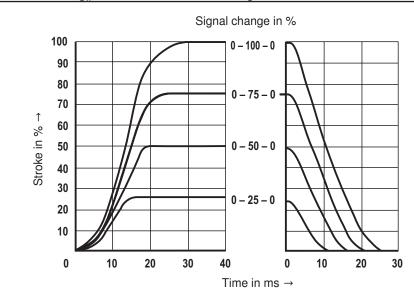
Control spool E

Transition function with stepped electric input signals: Type 4WREE

(measured with HLP46, ϑ_{Oil} = 40 °C ± 5 °C and p_s = 10 bar)

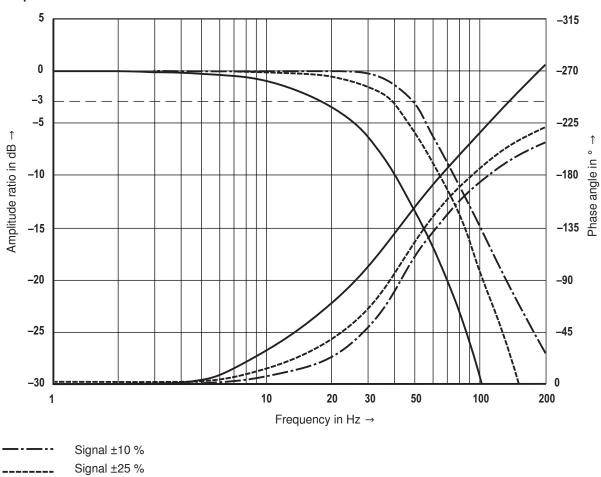
Size 6

Size 6



Frequency response characteristic curves: Type 4WREE (measured with HLP46, ϑ_{Oil} = 40 °C ± 5 °C, p_s = 10 bar)

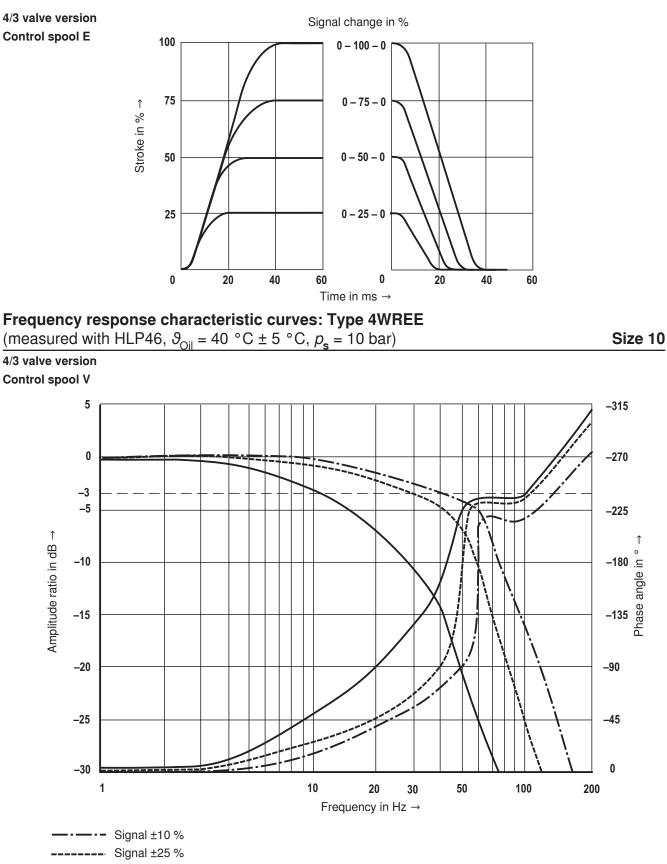
4/3 valve version Control spool V



Signal ±100 %

Transition function with stepped electric input signals: Type 4WREE (measured with HLP46, $\vartheta_{Oil} = 40 \text{ °C} \pm 5 \text{ °C}$ and $p_s = 10 \text{ bar}$)



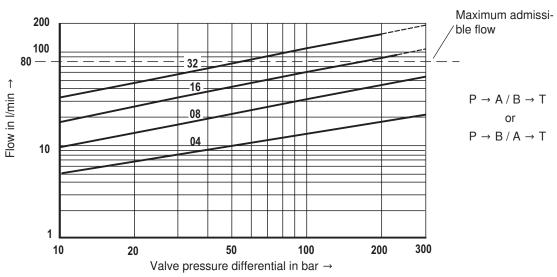


_____ Signal ±100 %

Flow: Type 4WREE (measured with HLP46, $\vartheta_{Oil} = 40 \text{ °C} \pm 5 \text{ °C}$)

Size 6

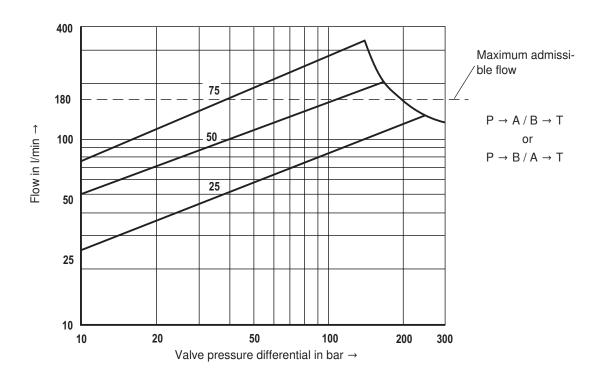
Load function with maximum valve opening Rated flow 4, 8, 16 and 32 l/min Control spool V



Observe the maximum admissible flow of 80 l/min!

Flow: Type 4WREE (measured with HLP46, $\vartheta_{Oil} = 40 \text{ °C} \pm 5 \text{ °C}$)Size 10

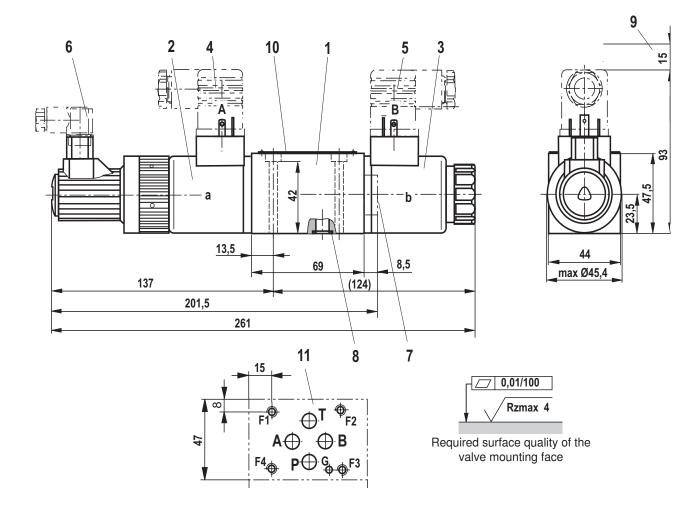
Load function with maximum valve opening Rated flow 25, 50 and 75 l/min Control spool V



Observe the maximum admissible flow of 180 l/min!

Unit dimensions: Type 4WRE (dimensions in mm)

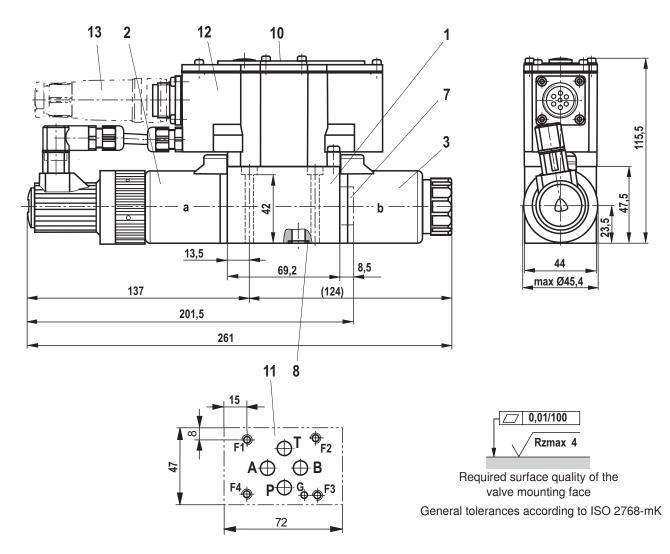




- 1 Valve housing
- 2 Proportional solenoid "a" with inductive position transducer
- 3 Proportional solenoid "b"
- 4 Mating connector "A", color gray, separate order see page 8
- 5 Mating connector "B", color black, separate order see page 8
- 6 Mating connector for inductive position transducer, separate order see page 8
- 7 Plug screw for valve with one solenoid (2 spool positions, version **EA** or **WA**)
- 8 Identical seal rings for ports A, B, P, and T
- 9 Space required to remove the mating connector
- 10 Name plate
- Machined valve mounting face, porting pattern according to ISO 4401-03-02-0-05 (with locating hole) Deviating from the standard:
 without locating hole "G"
 - Ports P, A, B and T with Ø 8 mm

RE 29061/11.12 4WRE; 4WREE

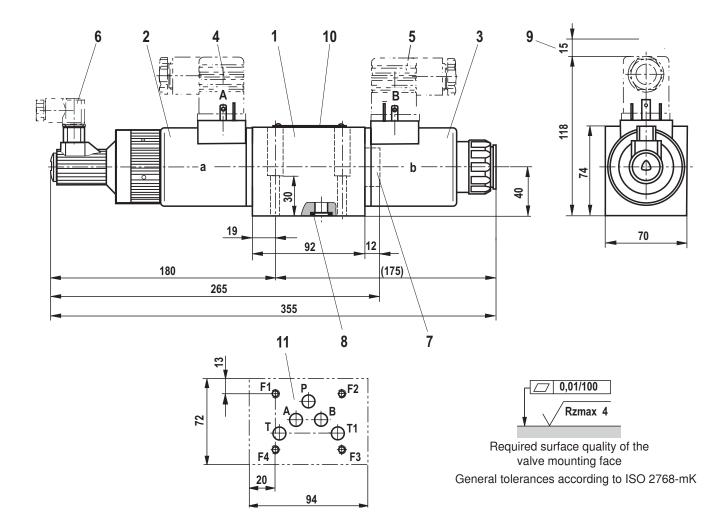
Unit dimensions: Type 4WREE (dimensions in mm)



- 1 Valve housing
- 2 Proportional solenoid "a" with inductive position transducer
- 3 Proportional solenoid "b"
- 7 Plug screw for valve with one solenoid (2 spool positions, version **EA** or **WA**)
- 8 Identical seal rings for ports A, B, P, and T
- 10 Name plate
- Machined valve mounting face, porting pattern according to ISO 4401-03-02-0-05 (with locating hole) Deviating from the standard:
 - without locating hole "G"
 - Ports P, A, B and T with Ø 8 mm
- 12 Integrated electronics (OBE)
- **13** Mating connector, separate order – see page 9

Unit dimensions: Type 4WRE (dimensions in mm)

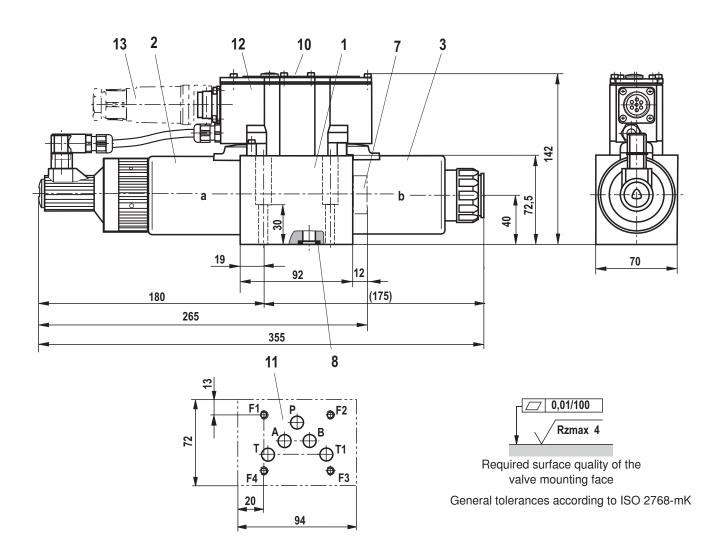
Size 10



- 1 Valve housing
- 2 Proportional solenoid "a" with inductive position transducer
- 3 Proportional solenoid "b"
- 4 Mating connector "A", color gray, separate order see page 8
- 5 Mating connector "B", color black, separate order see page 8
- 6 Mating connector for inductive position transducer, separate order see page 8
- 7 Plug screw for valve with one solenoid (2 spool positions, version **EA** or **WA**)
- 8 Identical seal rings for ports A, B, P, T and T1
- 9 Space required to remove the mating connector
- 10 Name plate
- 11 Machined valve contact surface, porting pattern according to ISO 4401-05-04-0-05 differing from the standard: Connection T1 Ø 11.2 mm

Unit dimensions: Type 4WREE (dimensions in mm)

size 10



- 1 Valve housing
- 2 Proportional solenoid "a" with inductive position transducer
- 3 Proportional solenoid "b"
- 7 Plug screw for valve with one solenoid (2 spool positions, version **EA** or **WA**)
- 8 Identical seal rings for ports A, B, P, T and T1
- 10 Name plate
- 11 Machined valve contact surface, porting pattern according to ISO 4401-05-04-0-05 differing from the standard: Connection T1 Ø 11.2 mm
- 12 Integrated electronics (OBE)
- **13** Mating connector, separate order – see page 9

Unit dimensions

Hexagon socket head cap screws		Material number
Size 6	4x ISO 4762 - M5 x 50 - 10.9-flZn-240h-L Tightening torque $M_A = 7 \text{ Nm} \pm 10 \%$ or 4x ISO 4762 - M5 x 50 - 10.9 Tightening torque $M_A = 8.9 \text{ Nm} \pm 10 \%$	R913000064
Size 10	4x ISO 4762 - M6 x 40 - 10.9-flZn-240h-L Tightening torque M_A = 12.5 Nm ±10 % or 4x ISO 4762 - M6 x 40 - 10.9 Tightening torque M_A = 15.5 Nm ±10 %	R913000058

Notice: This tightening torque of the hexagon socket head cap screws refers to the maximum operating pressure!

Subplates	Data sheet
Size 6	45052
Size 10	45054

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