



USER MANUAL

EVALUATION BOARD FOR WSEN-ISDS

2536030320091

VERSION 1.0

JANUARY 26, 2023

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Revision history

Manual version	Product version	Notes	Date
1.0	1.0	Initial release of the manual	January 2023



Abbreviations

Abbreviation	Description
I ² C	Inter integrated circuit
IMU	Inertial measurement unit
MEMS	Micro electro mechanical system
LSB	Least significant bit
SPI	Serial peripheral interface

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1 General description

1.1 Introduction

The evaluation board of the IMU (Inertial Measurement Unit) 6 axis sensor provides an opportunity to verify the sensor performance and develop a prototype using an extension board e.g. Sensor shield for Arduino (Part No. 2501000101291). It can be directly plugged to sensor shield using the mounted I²C and SPI interface pins. The evaluation board can also be mounted on a bread board using through hole pin header connections. The 6 axis IMU sensor (Part No: 2536030320091) is a 16-bit digital ultra-low-power and high-performance MEMS sensor. It includes 3 axis linear accelerometer and 3 axis gyroscope. The digital host interface offers either I²C or SPI to communicate with the sensor.

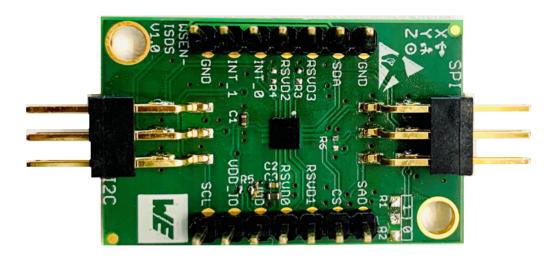


Figure 1: Evaluation board for the IMU 6 axis sensor

1.2 Pin header compatibility

6-pin right angle headers mounted on this evaluation board can be directly plugged into the sensor shield for Arduino or sensor FeatherWing. This serves a plug-and-play solution to quickly take the evaluation board into operation.



Sensor shield for Arduino is a stackable extension board for Arduino UNO and DUE to connect the sensor evaluation boards. More information can be found on our website.



2 Functional description

The acceleration sensor evaluation board supports the standard I²C and SPI communication interface. By default, I²C communication interface is enabled in the evaluation board.

- A positive supply voltage is applied to the sensor through VDD pin and I/O supply voltage for digital interface through VDD_IO pin. The VDD and VDD_IO pins on the board are connected together using 0Ω resistor R6.
- The I²C communication is enabled by connecting *CS* pin to *VDD_IO*. The *CS* pin is connected to *VDD_IO* using 100kΩ resistor R5.
- The 7-bit slave address of the acceleration sensor is 110101xb. LSB of the 7-bit slave address can be modified using the *SAO* pin.

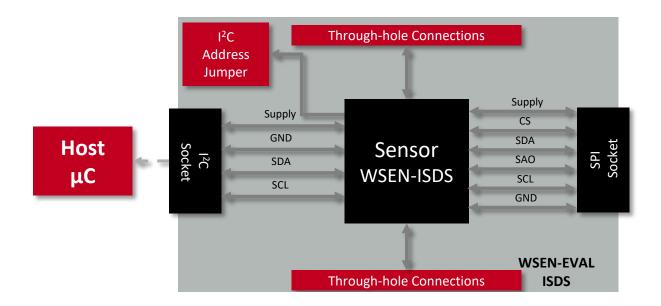


Figure 2: Block diagram of the evaluation board



By default the 7-bit slave address of the acceleration sensor on the evaluation board is 1101011b (0x6B). i.e. SAO pin of the sensor is connected to VDD_IO using $100k\Omega$ resistor ADR.



The 7-bit slave address of the acceleration sensor can be changed to 1101010b (0x6A) by removing $100k\Omega$ resistor ADR from '1' part and mounting 0Ω resistor on the '0' part of the evaluation board. i.e. *SAO* pin is connected to *GND*.





Please refer to the data sheet and user manual of the IMU 6 axis sensor (Part No: 2536030320001) for more information about the electrical properties.

2.1 Evaluation board in operation

2.1.1 I²C connection (CON1)

The pinning of connector CON1 provides I²C communication interface, which fits directly to the sensor shield for Arduino and sensor FeatherWing as mentioned in section 1.2. The I²C communication interface is the default state of the board.

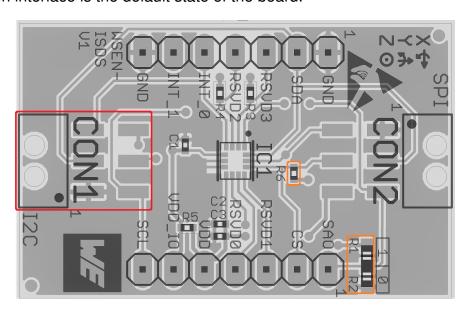
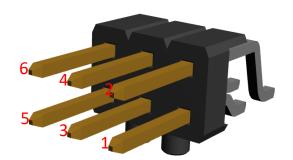


Figure 3: I²C Pin header connection to the external boards



Pin No	I ² C Pins (CON1)
1	GND
2	SCL
3	SDA
4	INT_1
5	INT_0
6	VDD

Table 1: I²C Pin header





R6 shall be populated to enable I²C communication.



Either R1 or R2 shall be populated to define the LSB of sensor's address.



Connecting the sensor evaluation board to the sensor FeatherWing using I²C or SPI interface pins will disable INT_0 and INT_1 interrupt pin functions.

2.1.2 SPI connection (CON2)

The pinning of connector CON2 provides SPI communication interface, which fits directly to the sensor shield for Arduino and sensor FeatherWing as mentioned in section 1.2.

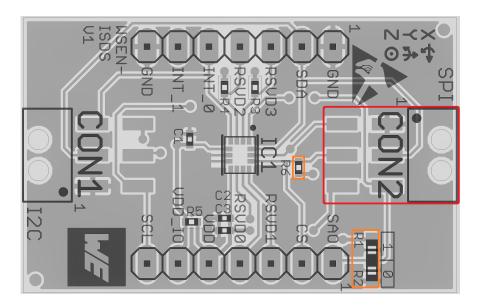
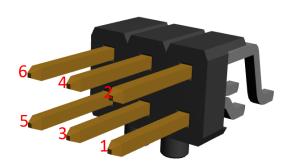


Figure 4: SPI Pin header connection





Pin No	SPI Pins (CON2)
1	GND
2	SCL
3	SDA (MOSI)
4	CS
5	SAO (MISO)
6	VDD

Table 2: SPI Pin header to external boards



SPI communication is enabled by removing the R1, R2, and R6 resistors.

2.1.3 Resistor functionality

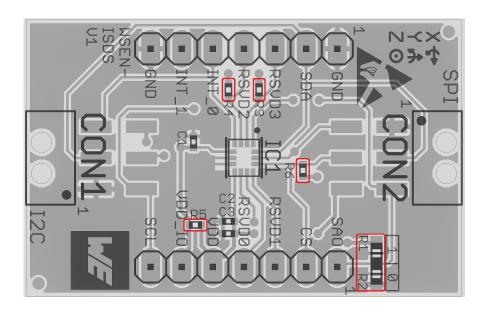


Figure 5: Resistor functionality



Resistor	Description
R1, R2	R1 is by default populated. <i>SAO</i> is connected to the <i>VDD_IO</i> , therefore the I ² C address of sensor is 1101011b. If R2 is assembled the the I ² C address of sensor is 1101010b.
R3, R4	Reserved functionality. Do not remove.
R5	VDD and VDD_IO pins are connected together.
R6	I ² C enabled by default. <i>CS</i> is connected to <i>VDD_IO</i> . To enable SPI communication, remove R1, R2 and R6 resistors.

Table 3: Functionality of the resistors on the evaluation board



Check in your configuration, if the resistors R1, R2 and R6 have to be removed before connecting the evaluation board to a processor.

2.1.4 Through hole connection

Through hole pin headers connection gives direct access to each sensor pin. Please refer to table 4 and 5 for the pin description of P1 and P2 respectively.

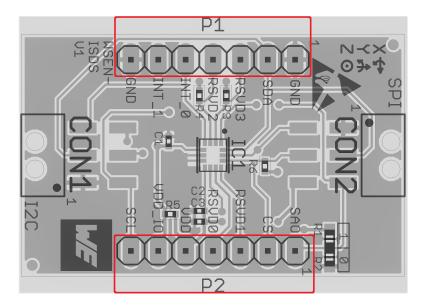


Figure 6: Through hole connection P1 and P2



Pin No.	Evaluation board pins	Description	Input/Output
1	GND	Negative supply voltage	Supply
2	SDA	I ² C serial data, SPI serial data input	Input/Output
3	RSVD3	Reserve functionality. Corresponds to sensor's pin 2	Input/Output
4	RSVD2	Reserve functionality. Corresponds to sensor's pin 3	Input/Output
5	INT_0	Interrupt pin 0	Output
6	INT_1	Interrupt pin 1	Output
7	GND	Negative supply voltage	Supply

Table 4: Pin description of P1

Pin No.	Evaluation board pins	Description	Input/Output
1	SAO	I ² C device address selection, SPI serial data output	Input/output
2	CS	I ² C enable/disable, SPI chip select	Input
3	RSVD1	Reserved functionality. Corresponds to sensor's pin 11	Input/Output
4	RSVD0	Reserved functionality. Corresponds to sensor's pin 10	Input/Output
5	VDD	Positive supply voltage	Supply
6	VDD_IO	Positive supply voltage for I/O pins	Supply
7	SCL	I ² C/SPI serial clock	Input

Table 5: Pin description of P2



3 Evaluation board

3.1 Schematic diagram

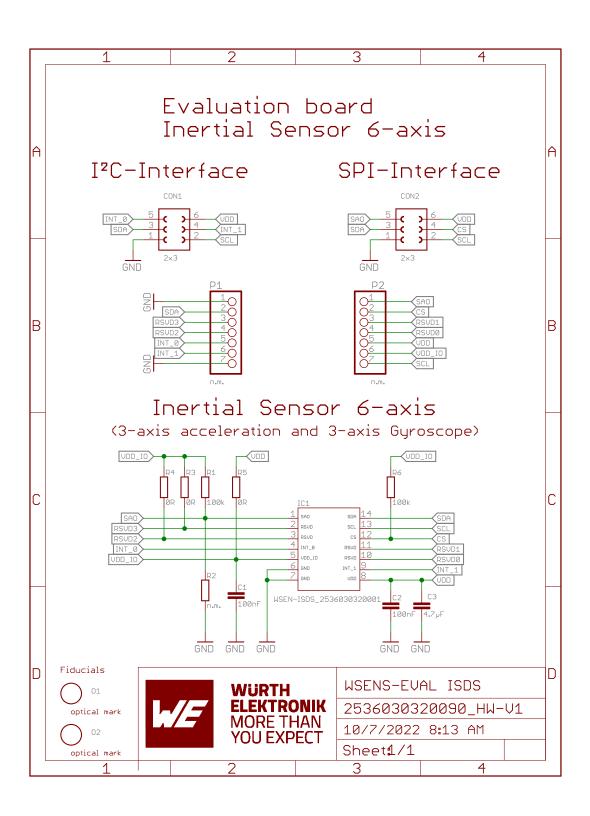


Figure 7: Schematic diagram



3.2 Layout

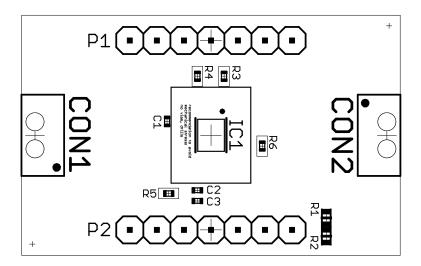
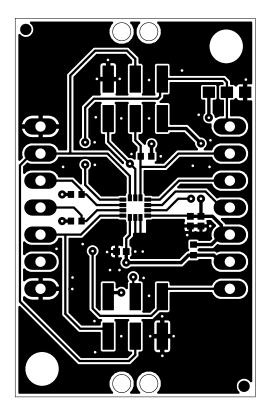


Figure 8: Assembly diagram



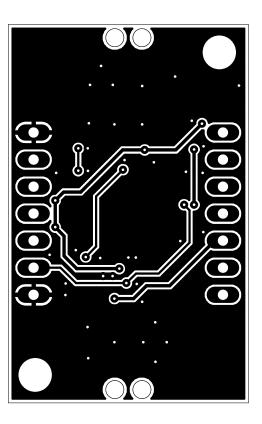


Figure 9: Top (left) and bottom (right) layers



3.3 Bill of materials

Part	Value	Pack	Manufacturer	NR
C1	100 nF	0402	Würth Elektronik eiSos	885012205037
C2	100 nF	0402	Würth Elektronik eiSos	885012205037
C3	4.7 μF	0402	Würth Elektronik eiSos	885012105008
CON1	2x3	THT	Würth Elektronik eiSos	610106249121
CON2	2x3	THT	Würth Elektronik eiSos	610106249121
IC1	WSEN-ISDS	SMT	Würth Elektronik eiSos	2536030320001
P1	n.m.	SMT	n.m.	n.m.
P2	n.m.	SMT	n.m.	n.m.
R1	100 kΩ	0603	Yageo	RC0603FR-10100KL
R2	n.m.	SMT	n.m.	n.m.
R3	0 Ω	0402	Yageo	RC0402FR-070RL
R4	0 Ω	0402	Yageo	RC0402FR-070RL
R5	0 Ω	0402	Yageo	RC0402FR-070RL
R6	100 kΩ	0402	Yageo	RC0402FR-07100KL

Table 6: Bill of materials



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