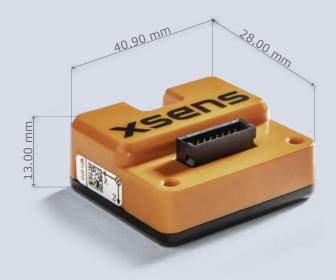
MTi-670

- Small, IP52 rated GNSS/INS
- 0.2 deg roll/pitch & sub-meter level position accuracy
- Connects to external GNSS receiver

The MTi-670 is a GNSS/INS with a small form-factor design for deep integration into your application. Building on the proven MTi 600-series technology it enables a robust and easy to use sub-meter level positioning and orientation tracking. If features a interface to an external GNSS receiver so you can efficiently design your application. It is designed for easy integration and seamless interfacing with other equipment. The MTi-670 is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms.



Sensor Fusion Performance

Roll, Pitch	0,2 deg RMS
Yaw/Heading	0.8 deg RMS
Position	<1m CEP
Velocity	0.05m/c.RMS

Gyroscope

Standard full range	2000 deg/s
In-run bias stability	8 deg/h
Bandwidth (-3dB)	520 Hz
Noise Density	$0.007~\text{o/s/}\sqrt{\text{Hz}}$
g-sensitivity (calibr.)	0.001 °/s/g

Accelerometer Standard full range

In-run bias stability	10 (x,y) 15(z) μ <u>ς</u>
Bandwidth (-3dB)	500 Hz
Noise Density	———— 60 μg/√Hz

10 a

Magnetometer

Standard full range	+/- 8 G
Total RMS noise	1 mG
Non-linearity	0.2%
Resolution	0.25 mG

GNSS Receiver

Brand ————————————————————————————————————	External
Model	External
RTCM input port	External

Barometer

Standard full range	300-1250 hPa
Total RMS noise	1.2 Pa
Relative accuracy	+/- 8 Pa (~0.5m)

Mechanical

IP-rating ————	IP51
Operating Temperature ———	-40 to 85 °C
Casing material	PC-ABS
Mounting orientation ————	No restriction, full 360° in all axes
Dimensions —	28x31.50x13 mm
Connector	Main: Phoenix Contact 16 pin, 1.27 mm
	pitch
Weight —————	8.9 g

Electrical

Input voltage	4.5 to 24V
Power consumption (typ)	<1 W

Interfaces / IO

Interfaces	UART, CAN, RS232
Sync Options	SyncIn, SyncOut, ClockSync
Protocols	Xbus, ASCII (NMEA) or CAN
Clock drift	10 ppm (or external)
Output Frequency	2 kHz, 400 Hz SDI
Built-in-self test	Yes

Software Suite

GUI (Windows/Linux)	MT Manager Firmware updater,
	Magnetic Field Mapper
SDK (Example code)	C++, C#, python, Matlab, Nucleo,
	public source code
Drivers	LabVIEW, ROS, GO
Support —	BASE by XSENS: online manuals,
	community and knowledge base

- White label and OEM integration options available
- 3D models available on request
- Available online via Digi-Key, Mouser, Farnell and local distributors



