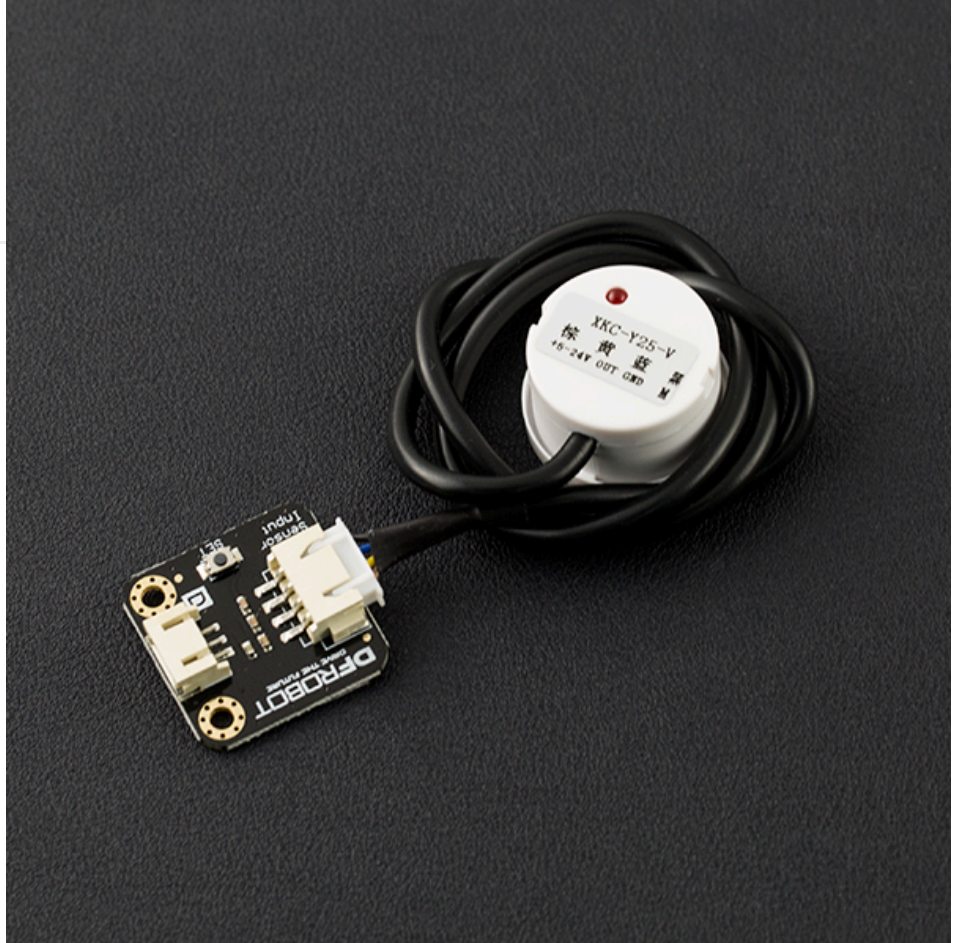


(<https://www.dfrobot.com/product-1493.html>)

Introduction

The non-contact liquid level sensor utilizes advanced signal processing technology by using a powerful chip with high-speed operation capacity to achieve non-contact liquid level detection. Without contacting with a liquid, the module is suitable for hazardous



applications such as detecting toxic substances, strong acid, strong alkali and all kinds of liquid in an airtight container under high pressure. There are no special requirements for the liquid or container and the sensor is easy to use and easy to install. The liquid level sensor is equipped with an interface adapter that makes it compatible with DFRobot "Gravity" interface. There are 4 levels of sensitivity which are set by pressing the **SET** button.

Specification

- Operating Voltage (InVCC) : DC 5 ~ 24 v
- Current consumption: 5 mA
- Output voltage (high level) : InVCC

- Output voltage (low level) : 0V
- Output current: 1 ~ 50 mA
- Response time: 500 ms
- Operating Temperature : 0 ~ 105 °C
- Range for thickness of induction (sensitivity): 0 ~ 13 mm
- Humidity: 5% ~ 100%
- Material: ABS.
- Waterproof performance: IP67
- Dimension : 28 * 28 mm / 1.1 * 1.1 inches

Board Overview

Liquid Level Sensor-XKC-Y25-T12V Pin defination

Num.	Name	Description
1 (Brown)	VCC	InVCC (range: +5V~+24V)
2 (Yellow)	OUT	Liquid level sensor signal output
3 (Blue)	GND	GND
4 (Black)	ADJ	Sensor sensitivity adjusting switch (Adjust the sensor sensitivity, 4 modes in all. Click the SET button on the adapter to set the sensor sensitivity.)

Liquid Level Sensor-XKC-Y25-T12V Pin defination

Num.	Name	Description
Left_1	VCC	InVCC (range: +5V~+24V)
Left_2	OUT	Liquid level sensor signal output
Left_3	GND	GND
Left_4	ADJ	Sensor sensitivity adjusting switch (Adjust the sensor sensitivity, 4 modes in all. Click the SET button on the adapter to set the sensor sensitivity.)
Right_1	OUT	Signal
Right_2	VCC	InVCC
Right_3	GND	GND

Tutorial

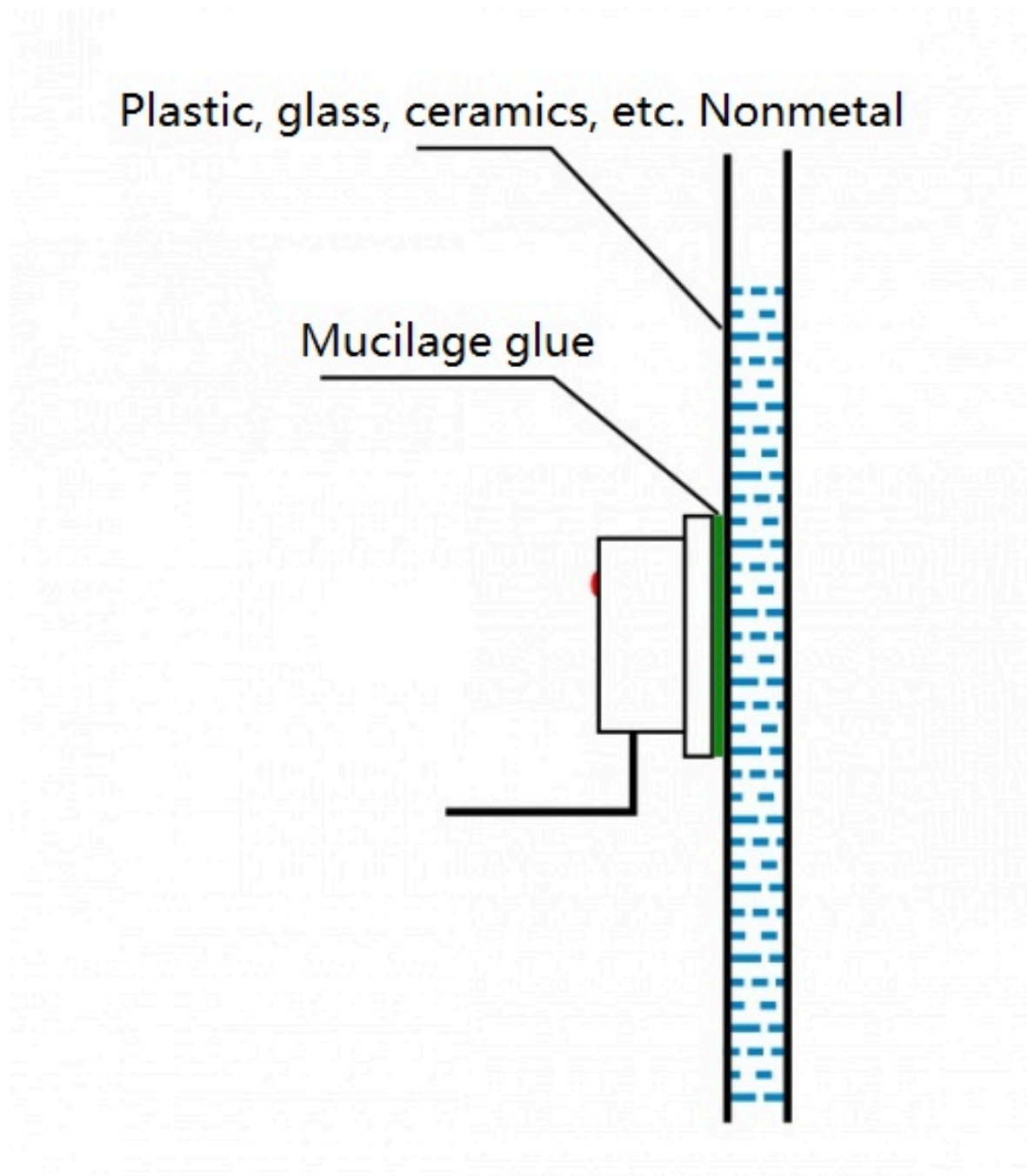
Trouble Shooting

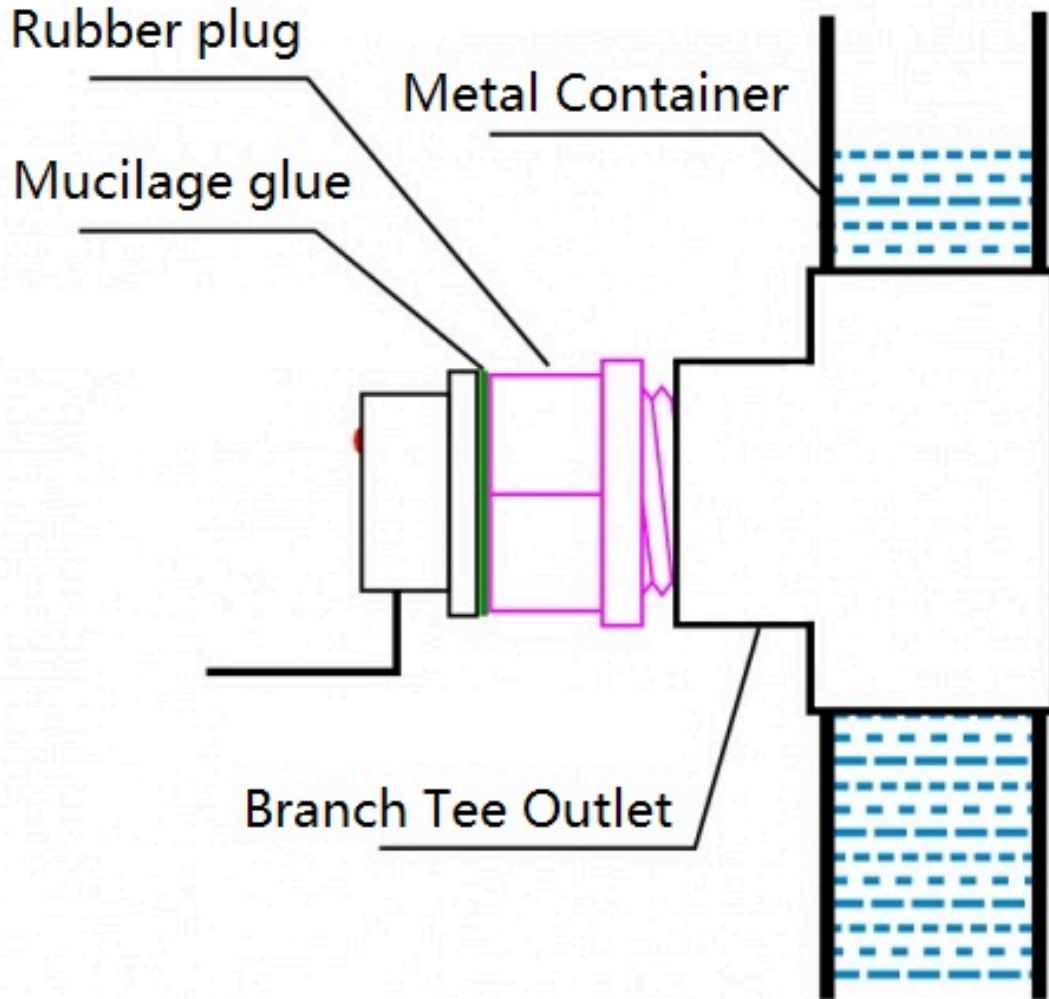
Symptom	Possible Cause	Solution
No reaction when powered on(the indicator keeps off when the liquid level reached the induction point, no reaction when adjusting sensitivity)	1.Power connection problem	Check and connect the power supply properly
	2.The negative and positive are disconnected	Connect the power properly
	3.Power module is damaged	Change the power module
	4.Sensitivity is too low	Increase the sensitivity
The indicator always keeps on	1.Sensitivity is too high	Decrease the sensitivity
	2.There are impurities in the inductor, or other metal objects near the inductor	Clean the inductor, and keep it away from other metal objects
	3.The liquid container is not insulative completely	Change the container or drill mount holes on the container to install the inductor

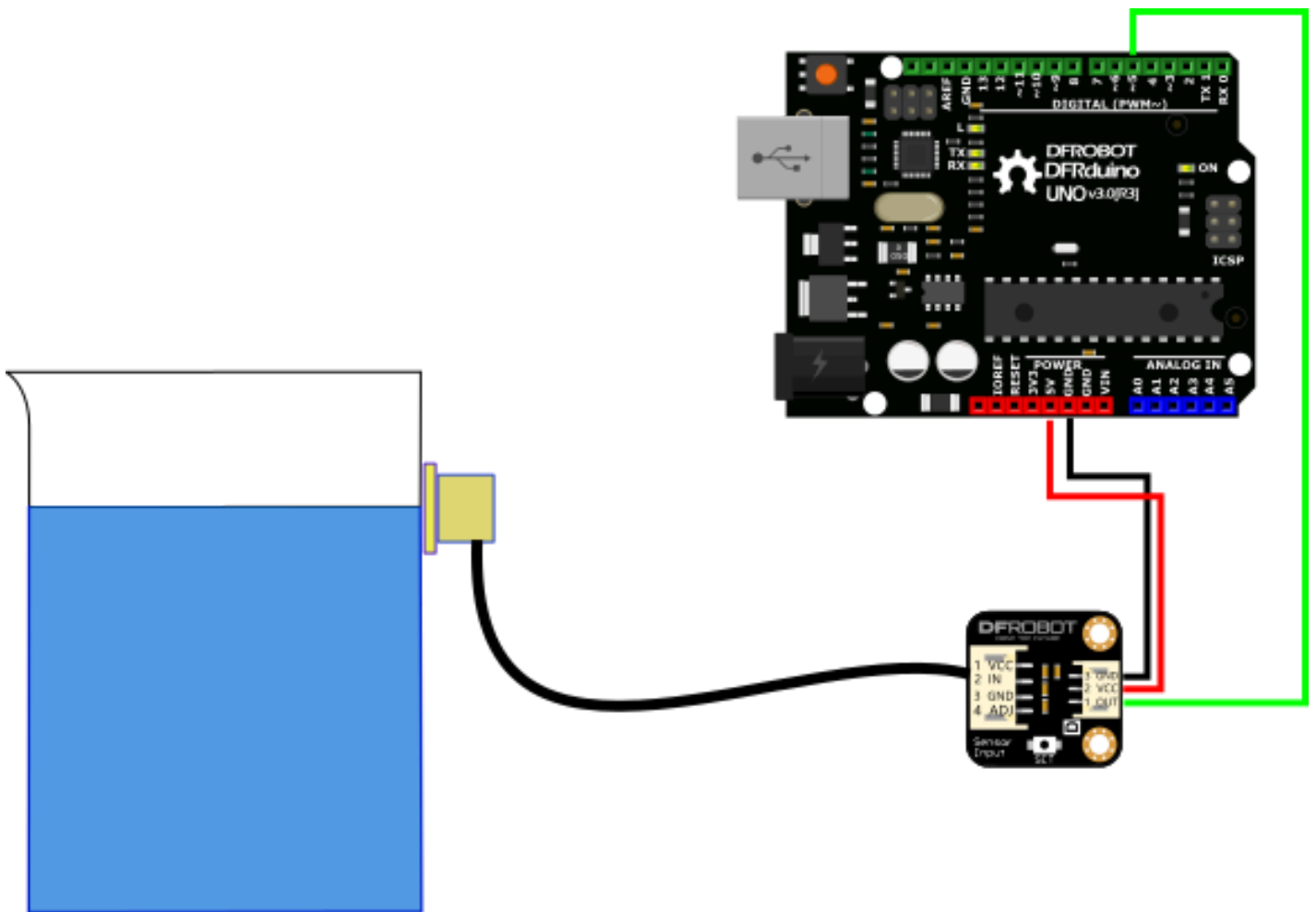
Requirements

- **Hardware**
 - Arduino UNO x1
 - Liquid level sensor x1
- **Software**
 - Arduino IDE V1.6.5 Click to Download Arduino IDE from Arduino® (<https://www.arduino.cc/en/software>)

Connection Diagram







Sample Code

```
/*!
 * @file SEN0204.ino
 * @brief This example is to get liquid level. (Liquid Level Sensor-XKC-Y25-T12V)
 * @copyright Copyright (c) 2010 DFRobot Co.Ltd (http://www.dfrobot.com)
 * @license The MIT License (MIT)
 * @author jackli(Jack.li@dfrobot.com)
 * @version V1.0
 * @date 2016-1-30
 */

int liquidLevel = 0;

void setup()
{
  Serial.begin(9600);
  pinMode(5, INPUT);
}

void loop()
{
  liquidLevel = digitalRead(5);
  Serial.print("liquidLevel= "); Serial.println(liquidLevel, DEC);
  delay(500);
}
```

Expected Results

If the liquid level sensor detects the presence of liquid, it will output HIGH and turn the LED ON. If no liquid is detected it output LOW and turn the LED off.

FAQ

Q&A	Some general Arduino Problems/FAQ/Tips
Q	What is the sensor working principle?
A	<p>Its working principle is to use the water sensing capacitor to detect whether liquid is present. In the absence of liquid near the sensor, there will be a presence of distributed capacitance, and therefore there are some certain static capacitance to ground on the sensor. When the liquid level slowly increases close to the sensor, the parasitic capacitance of the liquid will be coupled to the static capacitance so that the final capacitance value of the sensor becomes larger and the changed capacitance signal is then input to the control IC for signal conversion,. Then converting the changed capacitance into the amount of change in the electrical signal. Lastly, by using a certain algorithm to detect and judge the degree of this change we can determine when the amount of change exceeds a certain threshold that means the liquid level to reach the induction point.</p>
A	<p>For any questions, advice or cool ideas to share, please visit the DFRobot Forum (https://www.dfrobot.com/forum/).</p>

More Documents

- Schematic
(<https://dfimg.dfrobot.com/nobody/wiki/3e3e0a01f68eb20275b2ec507629d4e2.pdf>)
- SVG files
(<https://dfimg.dfrobot.com/nobody/wiki/a7773623b64ebcd3919bd8bb6fc1f3df>).

rar)