Pneumatics

Service

Rexroth **Bosch Group**

2- and 3-way high response cartridge valves

RE 29135/06.13 Replaces: 10.05

1/20

Types .WRC.../S; .WRCE.../S

Nominal sizes 63 to 160 Component series 1X Maximum operating pressure 420 bar Maximum flow 50000 L/min



Type 2WRCE...-1X/S

Type 3WRCE...-1X/S

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¹⁾ Not for new applications!

For information regarding the available spare parts see: www.boschrexroth.com/spc

Features

е	- High response control valve of cartridge design
1	- Controlled by means of a servo directional valve
2 3	 Feedback of the control spool position by means of an inductive positional transducer
5	 2-way control element of poppet design
9	 3-way control element of spool design
0 1 2 7	 Typical applications, Open or closed loop control of large flows, e.g.: Forging manipulators Press cylinders Pressure casting machines
9	 Control electronics: Integrated or to component type separate order, see page 11

For further information regarding pilot operated valves and external control electronics see:

•	Servo	directional	valves NS6	Data sheet 29564
•	Servo	directional	valves NS10	Data sheet 29583

- Servo directional valves NS16 Data sheet 29591
- Amplifier type VT-SR... Data sheet 29931

Ordering details: type 2WRC(E)



Ordering details: type 3WRC(E) - Not for new applications!



Symbols



Design, function and section: type 2WRC(E)

The valve types 2WRC(E) are 3-stage high response valves. They control the rate and direction of a flow and are primarily used in closed loop control circuits.

Design

They comprise of the following sub-assemblies:

- A pilot control valve (1) as a 2-stage servo directional valve (pilot)
 - With a dry torque motor
 - Low friction jet / flapper amplifier and
 - Mechanical feedback of the spool position
- A main control spool (2) for flow control
- An inductive position transducer (3) whose core (4) is attached to the spool (2) of the third stage
- And integrated control electronics (5) for 2WRCE or separate electronics for the 2WRC version.

Function

Within the integrated control electronics (OBE) the command and actual values are compared and the pilot control valve solenoids are controlled via a currrent proportional the closed loop control deviation.

The pilot control valve asumes a proportional control position and controls the flows into or from control chambers A (6) and B (7), that actuate the main spool (2) by means of the closed loop control valve until the system deviation is 0.

The stroke of the main spool is thus controlled in proportion to the command value. It must be noted herethat the flow also depends on the valve pressure drop.

Valve features

Flow can be passed through the valve from A to B or from B to A.

The poppet spool closes or opens with a command value of approx. 2 %. With smaller command values the valve's closed loop control circuit trys to correct the spool position and thereby presses the spool, with up to the full system pressure, onto its seat and closes the connection leak-free.

The stated switching times are only valid for the closed loop control range of the valve. With command value jumps from the seat to small opening values, additional delay times occur.

The 2 % opening point (= 0.2 V) is factory pre-set. When replacing the pilot control valve or control electronics the opening point can be calibrated by adjusting the position transducer (3) by using the 13A/F nut.

When carrying out an exchange no adjustments to the control

electronics and pilot control valve (= closed loop controller, controller or control electronics), other than the zero calibration at the position controller may be carried out.

Only the filter element can be replaced on the pilot control valve (see data sheet "Servo directional valve")

Due to the diameter differences in the seat area, the spools are not pressure balanced. To compensate for the force differences for spool "K001" 6 %, and for spools "D001" and "S001" 22 % of the system pressure is required as the control pressure, and then by adding reserves for flow forces and dynamics, the recommended minimum control pressure can be obtained (see technical data).



¹⁾ Preferably port B should be connected to the actuator.

Attention: A loss of power at the pilot control valve results in the spool being in an undefined position (2). For preventive measures see data sheet 29135-1 "Preferred settings on the 2WRCE"

Design, function and section: type 3WRC(E) ¹⁾

The valve types 3WRC(E) are 3-stage 3-way high response valves.

They control the rate and direction of a flow and are primarily used in closed loop control circuits.

Design

They comprise of the following sub-assemblies:

- A pilot control valve (1) as a 2-stage servo directional valve (pilot)
 - With a dry torque motor
 - · Low friction jet / flapper amplifier and
 - · Mechanical feedback of the spool position
- A main control spool (2) for flow control
- An inductive position transducer (3) whose core (4) is attached to the spool (2) of the third stage
- And integrated control electronics (5) for 3WRCE or separate electronics for the 3WRC version.

Function

Within the integrated or external electronics, the command and actual values are compared, and accordingly the associated control deviation controls, the pilot valve torque motor via a proportional current.

The pilot control valve assumes a proprtional control position and controls the pilot control flows in/out of the control chambers A (6) and B (7), that controls the main spool (2) via the closed loop circuit until the control deviation is 0.

The stroke of the main spool is thereby closed loop controlled in proportion to the command value. It has, however to be taken into account that the flow is also dependent on the pressure drop.

Attention: A loss of power at the pilot control valve results in the spool being in an undefined position (2). for preventative measures see data sheet 29135-1 "Preferred setting on the 3WRCE"

Valve features

The 0 % opening point (L006 and V001 spools) is factory pre-set. When replacing the pilot control valve or the control electronics the opening point can be calibrated by adjusting the position transducer (3) by using the 13A/F nut.

When carrying out an exchange **no** adjustments to the control electronics and pilot control valve (= closed loop controller, controller or control electronics) may be carried out other than the zero calibration at the position controller.

Only the filter element can be replaced on the pilot control valve (see data sheet "Servo directional valves").



¹⁾ Not for new applications!

²⁾ Please use the variant with P and A exchanged. Please consult us!

Technical data: type 2WRC(E) (for applications outside these parameters, please consult us!)

General						
Nominal size	NS	63	80	100	125	160
Weight	kg	56	114	198	357	635
Pilot control valve nominal size (pilot)	NS	6	10	10	16	16
Installation; commissioning guidelines		Optional, p	preferably ho	prizontal; to	data sheet (7700
Storage temperature range			-2	20 to +80		
Ambient temperature range	°C			+60 for WR +70 for WF	-	
Hydraulic (measured with HLP32, $\vartheta_{\rm oil} = 40$	°C ±5 °C)				
Nominal size	NS	63	80	100	125	160
Max. operating pressure						
– Main stage, ports A, B	bar			420		
- Pilot control valve, port X	bar			315		
- Pilot control valve, port Y	bar	r Pressure peaks <100, static <10				
Min. control pressure in % of the system pressure						
– For spool "K001"	%			15		
- For spools "D001" and "S001"	%			45		
Nominal flow q_{Vnom} -10 % at $\Delta p = 5$ bar						
– For spool "K001"	l/min	2600	4100	6300	10100	17000
– For spool "D001"	l/min	2300	3600	5800	9200	15000
– For spool "S001"	l/min	1800	3000	5200	7800	13300
Max. flow						
- For spools "K001" and "D001"	l/min	5500	9000	14000	22000	35000
– For spool "S001"	l/min	8000	13000	20000	30000	50000
Switching time at 200 bar (315 bar)						
– Stroke 50%	ms	37(30)	32(25)	45(35)	50(40)	70(60)
– Stroke 100%	ms	70(60)	50(40)	75(60)	90(70)	120(100)
Pilot oil flow at X and Y with a stepped form of input signal from 0 to 100 % (315 bar)	l/min	42	135	165	320	430
Zero flow of the servo pilot stage in relationship to pressure in line X		$\sqrt{\frac{p_x}{70 \text{ bar}} \cdot 0,5}$	$\sqrt{\frac{p}{70}}$	*• 1,5 5ar		*•3,5
Control flow	cm ³	36,3	67,9	132,5	313,4	565,5

Technical data: type 2WRC(E) (for applications outside these parameters, please consult us!)

Nominal size		NS	63	80	100	125	160
Pressure fluid			Mineral oil (HL, HLP) to DIN 51524, other pressure fluids on request				
Pressure fluid temp	perature range	°C	-2	0 to +80; p	oreferably +4	0 to +50	
Viscosity range		mm²/s	:	20 to 380;	preferably 30	0 to 45	
Max. permissible deg	ree of pressure fluid contamination						
Cleanliness class	 Pilot control valve 			Clas	s 18/16/13 ¹⁾		
to ISO 4406 (c) – Main valve				Clas	s 20/18/15 ¹⁾		
Hysteresis %			≤ 0.5				
Reversal error %			≤ 0.2				
Response sensitivi	ty	%	≤ 0.2				
Electrical							
Voltage type					DC		
Signal type			Analogue				
Opening point calil	oration, see page 8	%	≤ 1				
Zero point drift witl	n a change in:						
	- Pressure fluid temperature	%/10 K			\leq 0.3		
	- Control pressure in X	%/100 bar			≤ 0.7		
	- Return pressure in Y 0 to 10 % from p	, %/bar	≤ 0.3				
Valve protection to	EN 60529		IP65 wit	h mounted	and fixed plu	ıg-in connec	tor

 The cleanliness classes stated for the components need to be maintained in hydraulic systems. Effective filtration prevents faults and simultaneously increases the life cycle of the components.
 For the selection of the filters see

www.boschrexroth.com/filter

Control electronics

Control electronics – 2WRCE	Integrated in the valve, see page 11
– 2WRC	External control electronics, see data sheet 29931

Nominal command value range for 2WRCE: 0 to +10 V \triangleq 0 to 100 % In the command value range 0 to 0.2 V the actual value stays constant at 0.2 V. With a slow command value change from 0.2 V to 10 V, the actual value follows the command value within ±0.1 V. With command value jumps greater than 10 V, then the actual value can briefly reach valves of approx. 10.5 V.



Technical data: type 3WRC(E) ¹⁾ (for applications outside these parameters, please consult us!)

General				
Nominal size	NS	63	80	100
Weight	kg	57	116	200
Pilot control valve nominal size (pilot)	NS	6	10	10
nstallation; commissioning guidelines		Optional, prefe	rably horizontal; to da	ta sheet 07700
Storage temperature range			-20 to +80	
Ambient temperature range	°C		-20 to +60 to WRCE -20 to +70 to WRC	
Hydraulic (measured with HLP32, $\vartheta_{oil} = 40$	°C ±5 °C	;)		
Nominal size	NS	63	80	100
Max. operating pressure				
– Main stage, ports P, A, T	bar		315	
 Pilot control valve, port X 	bar		315	
 Pilot control valve, port Y 	bar	Press	ure peaks <100, stati	c <10
Nominal flow q_{Vnom} +10 % at $\Delta p = 5$ bar				
– For spool "L006"	l/min	1200	1850	2800
– For spool "V001"	l/min	1250	1900	2700
– For spool "E001"	l/min	1180	1820	2750
Max. flow				
– For spool L…, V…, E…,	l/min	3500	5600	8500
Switching time at 200 bar (315 bar)				
– Stroke 50%	ms	20(17)	18(13)	25(20)
– Stroke 100%	ms	37(30)	32(25)	40(35)
Pilot oil flow at X and Y with a stepped form of input signal from 0 to 100 % (315 bar)	l/min	42	130	170
Zero flow of the servo pilot stage in relationship to pressure in line X		$\sqrt{\frac{p_x}{70 \text{ bar}}} \cdot 0,5$	$\sqrt{\frac{\rho_x}{70 \text{ bar}} \cdot 1,5}$	
Control flow	cm ³	±18,1	±33,9	±66,2
Pressure fluid			l oil (HL, HLP) to DIN pressure fluids on red	
Pressure fluid temperature range	°C	-20 to +80; preferably +40 to +50		
Viscosity range mm ² /s		20 to 380; preferably 30 to 45		
Max. permissible degree of pressure fluid contamination				
Cleanliness class - Pilot control valve			Class 18/16/13 2)	
to ISO 4406 (c) – Main valve			Class 20/18/15 2)	
Hysteresis	%		≤ 0.5	
Reversal error	%		≤ 0.2	
Response sensitivity	%		≤ 0.2	

¹⁾ Not for new applications!

the components.

²⁾ The cleanliness classes stated for the components need to be maintained in hydraulic systems. Effective filtration prevents faults and simultaneously increases the life cycle of
For the set www.bos

For the selection of the filters see

www.boschrexroth.com/filter

Technical data: type 3WRC(E)¹⁾ (for applications outside these parameters, please consult us!)

Electrical		
Voltage type		DC
Signal type		Analogue
Zero calibration	%	≤ 1
Zero point drift wi	th change in:	
	– Pressure fluid temperature %/10 K	≤ 0.3
	- Control pressure in X %/100 bar	≤ 0.7
	- Return pressure in Y 0 to 10 % from p_x %/bar	≤ 0.3
Valve protection to	D EN 60529	IP65 with mounted and fixed plug-in connector

Control electronics

Control electronics	– 3WRCE	Integrated in the valve, see page 11
	– 3WRC	External control electronics, see data sheet 29931

¹⁾ Not for new applications!

Nominal command value range for 3WRCE: 0 to $\pm 10 \text{ V} \triangleq 0$ to $\pm 100 \%$ With a slow command value change from 0 V to $\pm 10 \text{ V}$, the actual value follows the command value within $\pm 0.1 \text{ V}$. With command value greater than $\pm 10 \text{ V}$, then the actual value can briefly reach values of approx. $\pm 10.5 \text{ V}$.



Electrical connections

Supply voltage:

The plug-in connectors are included within the scope of supply.

Component plug allocation with integrated electronics (OBE)

Component plug allocation	Pin	Allocation with a G24 supply voltage		Allocation with a 0	G15 supply voltage
		2WRCE	3WRCE	2WRCE	3WRCE
Supply voltage	A	+ 24	+ 24 VDC		VDC
	В	0 V	'DC	- 15	VDC
	С	Enable (+ 24 V) ²⁾		Reference to A, B	
Differential com. value input	D	0 +10 V	0 ±10 V	0 +10 V	0 ±10 V
	E	$R_{\rm e} = >100 \ \rm k\Omega$	$R_{\rm e} = >100 \ \rm k\Omega$	$R_{\rm e} = >100 \ \rm k\Omega$	$R_{\rm e} = >100 \ \rm k\Omega$
Actual valve	F	+0,2 +10 V	0 ±10 V	+0,2 +10 V	0 ±10 V
		Reference is pin B	Reference is pin B	Reference is pin C	Reference is pin C
Earth	PE	Connected with the valve housing Connected with the valve h		the valve housing	

²⁾ Without enable = SO37 (-37 attached to the type code)

Do not connect PE when the valve is already earthed via the system.

+24 VDC ±6 V; full bridge rectification with a smoothing capaciter 2200 μ F; I_{max} = 230 mA

 \pm 15 VDC \pm 0,45 V; stabilised and smoothed; I_{max} = 180 mA

The command and actual values have the same polarity

D positive against $E \rightarrow$ main spool for the 2WRCE opens

D positive against E \rightarrow main spool for the 3WRCE moves in direction P to A open

Note: Electrical signals generated via control electronics (e.g. actual valve) must not be used for switching safety-relevant machine functions!

(Also see the European Standard "Safety requirement for fluid power systems and components – Hydraulics", EN 982!)

Electrical connection, plug-in connector for the integrated electronics or main stage of the external control electronics

Plug-in connector (within the scope of supply) Plug-in connector to DIN EN 175201-804 Separate order under Material No. **R900021267** (plastic version)





Plug-in connector (separat order)

Plug-in connector to DIN EN 175201-804 Separate order under Material No. **R9000223890** (metal version)



Plug-in connector for pilot control valve NS6 (NS63)

Plug-in connector to VG 95 328 Separate order under Material No. **R900005414**

Connection cable: 4 or 6 core, 0,75 mm², screened (e.g. cable type LiYCY 4 or 6 x 0.75 mm²), to DIN VDE 0812 Outer diameter 5 to 8.5 mm



Plug-in connector for pilot control valves NS10 and 16 (NS80, 100, 125, 160)

Plug-in connector version **K8** (external control electronics) to VG 095 342 – separate order under Material No. **R900002460**





Integrated electronics (OBE) type VT13037 for valve type .WRCE

Interface Integrated electronics (OBE) Valve **Dither generator** = Servo valve 2 WRCE: 1 Coil 1 1 Current Output 2 2 Coil 2 Com. value 0 ... +10 V $\sum_{r=1}^{D}$ Controller controller stage U(I) 3 WRCE: E ับ I Com. value ±10 V U 3 3 4 4 Oscillator Position transducer 2 WRCE: 1 **∖**Red Act. value +0.2 V ... 10 V 3 WRCE: Act. value ±10 V (measurement output F Demodulator has a positive potential **F** 4 | Blue U(I) 3 Brown against \perp with a flow U $P \rightarrow A$) 2 Black Supply voltage 24 V 15 V ±15 V 18 to 30 V Flow direction: – 15 V 0 V M0 18 to 30 V A positive signal at pin D and reference potential at pin E results in ΡF opening P \rightarrow A for 3WRCE łII opening A \rightarrow B or B \rightarrow A for 2WRCE

Block circuit diagram / pin allocation

External control electronics

Pin alloction



Characteristic curves (measured with HLP32 $\mathcal{B}_{oil} = 40 \text{ °C} \pm 5 \text{ °C}$)

A $\Delta p = 5$ bar relates to a 100% flow value of the nominal flow of the associated table.

For other valve pressure differentials, the following applies: $q = q_{vnom} \cdot \int \Delta p$



Unit dimensions: 2WRC(E) and 3WRC(E) 1), NS63 (nominal dimensions in mm)



¹⁾ Not for new applications!

Unit dimensions: 2WRC(E) and 3WRC(E) 1), NS80 (nominal dimensions in mm)



Unit dimensions: 2WRC(E) and 3WRC(E)¹⁾, NS100 (nominal dimensions in mm)



Unit dimensions: 2WRC(E), NS125 (nominal dimensions in mm)





Required surface finish of the valve mounting surface

- 1 Pilot control valve (servo directional valve NS16)
- 2 Bush
- **3** Plug-in connector (Material No. **R900021267**) included within the scope of supply
- 4 Plug-in connector (Material No. **R900002460**) included within the scope of supply
- 5 Space required to remove the plug-in connector
- 6 Cabling (only for WRCE)
- 7 Valve fixing screws (are included within the scope of supply)
 8 S.H.C.S. ISO 4762 - M36 x 300-10.9; Tightening torque for a tightening factor of 1.6 : 3300 Nm
- 8 Locating pin hole
- 9 Identical seal rings for ports X and Y
- 10 Name plate

12 Transport aid

- 11 Test points for control pressures, G1/4 screwed coupling
- ¹⁾ Not for new applications!

Unit dimensions: 2WRC(E), NS160 (nominal dimensions in mm)



Installation dimensions to DIN ISO 7368 – except for NS125 and 160 (nom. dimensions in mm)

NS63



NS80, 100





NS160



Tolerances to: - General tolerances ISO 2768-mK

NS	63	80	100
D8	M30	M24	M30
max. ØD9	12	16	20
ØD10	8	10	10
L1	180	250	300
L2	125	200	245
L3	62,5	-	-
L4	75	-	_
L5	38	-	-

1 Locating pin hole

Counterbore for ports X and Y in the manifold, only for NS160



Installation dimensions to DIN ISO 7368 - except for NS125 and 160 (nom. dimensions in mm)

Cavity for type 2WRC... to DIN ISO 7368



$$\sqrt[x]{} = \sqrt{\text{Rmax 4}}$$

$$\sqrt[y]{} = \sqrt{\text{Rmax 8}}$$

 $\sqrt[\mathbf{z}]{} = \sqrt{\text{Rz 10}}$

Cavity for type 3WRC...



- 1 Depth of fit, minimum dimensions
- 2 Ports P, T or B can be arranged about the centre axis of port A. However care must be taken to ensure that the fixing and control bores are not damaged.

Tolerances to:

- General tolerances ISO 2768-mK

NS	63	80	100	125	160
ØD1 ^{H7}	120	145	180	225	300
ØD2 ^{H7}	116	140	174	220	290
ØD3 ^{H7}	90	110	135	200	270
ØD4	63	80	100	max.150	max.200
ØD5	48	60	75	95	120
ØD6 ^{H7}	90	110	135	200	270
ØD7	63	80	100	125	200
H1	130	175	210	257	370
H2	155	205	245	300	425
H3	95	130	155	192	268
H4	40	40	50	40	50
H5	20	25	29	31	45
H7	85	125	155	195	245
H8	165	215	270	335	420
H9	195	245	305	380	480
H10	57	90	112	140	175
H11	137	180	225	280	350
H12	33	60	75	93	115
H13	28	25	32	37	45
H16	4	5	5	5,5	5,5
H17	4	5	5	7	8
H18	65	50	63	-	-
W	0,05	0,1	0,2	0,2	0,2

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