

# CE

#### **Model Number**

#### PCV100-F200-R4-V19

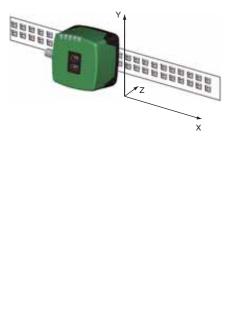
Read head for incident light positioning system

#### **Features**

- **RS 485 interface** ٠
- Non-contact positioning on Data • Matrix code tape
- Travel ranges up to 10 km, in X and Y direction
- Mechanically rugged: no wearing parts, long operating life, mainte-٠ nance-free
- High resolution and precise positioning, especially for facilities with curves and switch points as well as inclines and declines.

#### Diagrams

#### Coordinates



| Technical data                       |
|--------------------------------------|
| General specifications               |
| Passage speed v                      |
| Measuring range                      |
| Light type                           |
| Read distance                        |
| Depth of focus                       |
| Reading field                        |
| Ambient light limit                  |
| Resolution                           |
| Nominal ratings                      |
| Camera                               |
| Туре                                 |
| Processor                            |
| Clock pulse frequency                |
| Speed of computation                 |
| Functional safety related parameters |
| MTTF <sub>d</sub>                    |
| Mission Time (T <sub>M</sub> )       |
| Diagnostic Coverage (DC)             |
| Indicators/operating means           |
| LED indicator                        |
| Electrical specifications            |
| Operating voltage U <sub>B</sub>     |
| No-load supply current I0            |
| Power consumption P <sub>0</sub>     |
| Interface                            |
| Interface type                       |
| Data output code                     |
| Transfer rate                        |
| Termination                          |
| Query cycle time                     |
| Input                                |
| Input type                           |
| Input impedance                      |
| Output                               |
| Output type                          |
| Switching voltage                    |
| Switching current                    |
| Standard conformity                  |
| Emitted interference                 |
| Noise immunity                       |
| Shock resistance                     |
| Vibration resistance                 |
| Ambient conditions                   |

- Operating temperature
- Storage temperature Relative humidity Mechanical specifications
- Connection type Protection degree Material Housing
- Mass

## Approvals and certificates

- UL approval
- CCC approval

≤ 8 m/s max. 10000 m Integrated LED lightning (red) 100 mm ± 20 mm 50 mm x 30 mm 100000 Lux ± 0.1 mm CMOS, Global shutter 600 MHz 4800 MIPS 20 a 10 a 0% 7 LEDs (communication, alignment aid, status information) 15 ... 30 V DC , PELV max. 200 mA 3 W RS 485 interface binary code 38400 ... 230400 Bit/s Switchable terminal resistor ≥ 10 ms 1 to 3 functional inputs , programmable  $\ge$  27 k $\Omega$ 1 to 3 switch outputs , PNP , programmable , short-circuit protected Operating voltage 150 mA each output EN 61000-6-4:2007 + A1:2011 EN 61000-6-2:2005 EN 60068-2-27:2009 EN 60068-2-6:2008

0 ... 60 °C (32 ... 140 °F) , -20 ... 60 °C (-4 ... 140 °F) (noncondensing; prevent icing on the lens!) -20 ... 85 °C (-4 ... 185 °F) 90 %, noncondensing

8-pin, M12 x 1 connector IP67

PC/ABS approx. 160 g

cULus Listed, General Purpose, Class 2 Power Source, Type 1 enclosure CCC approval / marking not required for products rated  $\leq$ 36

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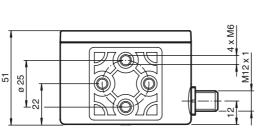
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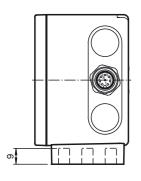


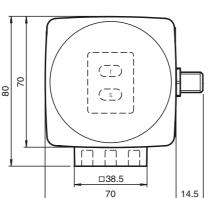
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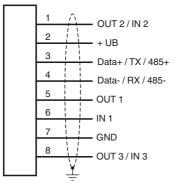
#### Dimensions







#### **Electrical Connection**



#### **Pinout**



#### General

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The PCV... reading head is part of the positioning system in the method for measurement by Pepperl+Fuchs. It consists of a camera module and an integrated illumination unit among other things. The reading head detects position marks, which are put on an adhesive code band in the form of Data Matrix code. The mounting of the code band is as a rule stationary on a firm part of the plant (elevator shaft, overhead conveyor mounting rails...); that of the reading head is parallel on the moving "vehicle" (elevator car, overhead conveyor chassis...).

#### Mounting and commissioning

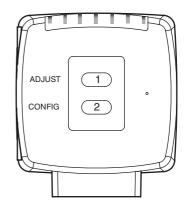
Mount the reading head such that its optical surface captures the optimal read distance to the code band (see Tech-

| Refer to "General Notes Relati | ing to Pepperl+Fuchs Product Inform | atio |
|--------------------------------|-------------------------------------|------|
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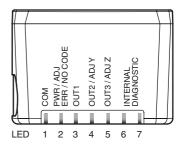
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**Additional Information** 



#### Accessories

PCV-USB-RS485-Converter Set USB to RS 485 interface converter

PCV-KBL-V19-STR-RS485 Cable unit with power supply for USB / RS 485 interface converter

V19-G-ABG-PG9 Female connector, M12, 8-pin, shielded, field attachable

V19-G-ABG-PG9-FE Female connector, M12, 8-pin, shielded, field attachable

PCV-SC12 Grounding clip for PCV system

**PCV Parameterization Tool** Configuration software for PCV Data Matrix positioning system

PCV-LM25 Marker head for 25 mm code tape

PCV-MB1 Mounting bracket for PCV\* read head

PCV-AG100 Alignment guide for PCV100-\* read head

nical Data). The stability of the mounting and the guidance of the vehicle must be provided such that the depth of field of the reading head is not closed during operation. All reading heads can be optimally customized by parameterization for specific requirements. The parameterization of reading heads with a bi-directional interface (all except SSI-interface) can take place via the interface itself (internal parameterization) or via an optical parameterization code (external parameterization). The reading heads with SSI interface only have the possibility of external parameterization via optical parameterization codes.

#### **Displays and Controls**

The PCV... reading head allows visual function check and fast diagnosis with 7 indicator LEDs. The reading head has 2 buttons on the reverse of the device to activate the alignment aid and parameterization mode.

#### LEDs

| LED | Color            | Label                   | Meaning                               |
|-----|------------------|-------------------------|---------------------------------------|
| 1   | Yellow           | COM                     | Communication active                  |
| 2   | Green/red        | PWR/ADJ                 | Code recognized/not recognized, Error |
|     |                  | ERR/NO CODE             |                                       |
| 3   | Yellow           | OUT1                    | Output 1                              |
| 4   | Yellow           | OUT2/ADJ Y              | Output 2, Alignment aid Y             |
| 5   | Yellow           | OUT3/ADJ Z              | Output 3, Alignment aid Z             |
| 6,7 | red/green/yellow | INTERNAL<br>DIAGNOSTICS | Internal diagnostics                  |

#### **External parameterization**

For external parameterization you require the parameterization code as Data Matrix with the desired reading head parameters. Data Matrix code cards for step-by-step external parameterization are printed in the reading heads operating instructions.

Parameterization is only possible within 10 minutes of switching on the reading head. If a button is pressed after 10 minutes subsequent to switching on, there is visual signaling via the LEDs (LED1, yellow/LED2, red/LED3, yellow/LED4, yellow/LED5, yellow flash for 2 seconds)

The switchover from normal operation to parameterization mode is via button 2 on the reverse of the reading head. Button 2 must be pressed for more than 2 seconds. I FD3 now flashes

Note:Parameterization mode automatically ends after 1 minute of inactivity. The reading head returns to normal operation and works with unchanged settings.

- Place the parameterization code in the view of the camera module. After recognition of the parameterization code, the green LED2 lights up for 1s. In the event of an invalid parameterization code, the red LED2 lights up for 2 s.
- A short press on button 2 ends the parameterization mode and the changed parameters are not stored volatile in the reading head.

#### Alignment aid for the Y and Z coordinates

The activation of the alignment aid is only possible within 10 minutes of switching on the reading head. The switchover from normal operation to "alignment aid operating mode is via button 1 on the reverse of the reading head.

- Press the button 1 for longer than 2 s. LED2 flashes green for a recognized code band. LED2 flashes red for an unrecognized code band.
- Z coordinate: If the distance of the camera to the code band too small, the yellow LED5 lights up. If the distance of the camera to the code band too large, the yellow LED5 lights up. Within the target range, the yellow LED5 flashes at the same time as the green LED2.
- Y coordinate: If the optical axis of the camera is too deep in relation to the middle of the code band, the yellow LED4 lights up. If the optical axis is too high, the yellow LED4 extinguishes. Within the target range, the vellow LED4 flashes at the same time as the green LED2.
- A short press on button 1 ends the alignment aid and the reading head changes to normal operation.

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