



Model Number

PHA500-F200A-B17-V1D

Precision positioning on hole in the 70 mm x 70 mm housing

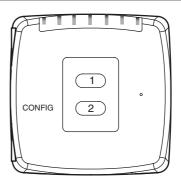
Features

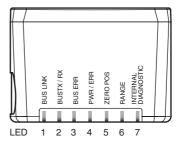
- Detects the position of an index hole
- Large capture range
- High operating range
- Integrated contrast compensation
- Compact design
- **PROFINET** interface
- Integrated illumination

Function

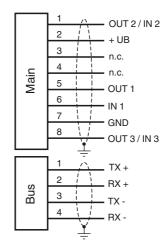
The sensor has been developed for the precision positioning of high-bay racking operating equipment. It detects circular holes in the racking structure and their positional deviation from the nominal position. The sensor operates in two dimensions.

Indicating / Operating means

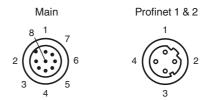




Electrical connection



Pinout



Technical data

Indicators/operating means

General specifications Light type Integrated LED lightning (infrared) Object size Hole diameter 13 mm Response delay 100 ms Read distance 500 mm Depth of focus ± 50 mm Capture range max 90 mm x 90 mm **Nominal ratings** Camera CMOS, Global shutter Type 752 x 480 pixels Number of pixels Gray scale 256 Functional safety related parameters MTTF_d 20 a Mission Time (T_M) 10 a Diagnostic Coverage (DC) 0 %

Operation indicator LED green: Ready for operation Function indicator 7 LEDs (communication, alignment aid, status information) Control elements Button for parameterization **Electrical specifications** 24 V DC +/- 15 %. PELV Operating voltage U_{B} max. 400 mA No-load supply current I_0 6 W Power consumption P_0 Interface

Interface type 100 BASE-TX PROFINET
Protocol PROFINET IO Real-Time (RT) Conformance class A
Transfer rate 100 MBit/s
Standard conformity

Noise immunity EN 61000-6-2:2005

Ambient conditions

Operating temperature 0 ... 60 °C (32 ... 140 °F) , -20 ... 60 °C (-4 ... 140 °F) (noncondensing; prevent icing on the lens!)

Storage temperature -30 ... 85 °C (-22 ... 185 °F)

Storage temperature
-30 ... 85 °C (-22 ... 185 °F)

Relative humidity
90 % , noncondensing

Mechanical specifications

Degree of protection
Material
Housing
PC/ABS
Optical face
Installation
4 x M6 threading
Mass
approx. 200 g

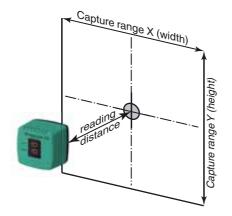
Approvals and certificates

UL approval cULus Listed, General Purpose, Class 2 Power Source

CCC approval CCC approval / marking not required for products rated ≤36 V

Approvals CE

Curves / Diagrams



Accessories

V19-G-5M-PUR-ABG

Female cordset, M12, 8-pin, shielded, PUR cable

V1SD-G-2M-PUR-ABG-V1SD-G

Ethernet bus cable, M12 to M12, PUR cable 4-pin, CAT5e

V1SD-G-5M-PUR-ABG-V1SD-G

Ethernet bus cable, M12 to M12, PUR cable 4-pin, CAT5e

PCV-MB1

Mounting bracket for PCV* read head

PCV-SC12A

Grounding clip for PCV system

PCV-SC12

Grounding clip for PCV system

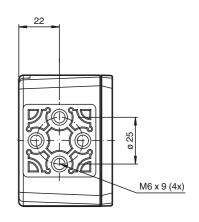
V19-G-10M-PUR-ABG

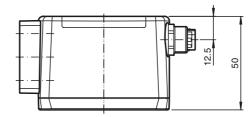
Female cordset, M12, 8-pin, shielded, PUR cable

V19-G-2M-PUR-ABG

Female cordset, M12, 8-pin, shielded, PUR cable

Other suitable accessories can be found at www.pepperl-fuchs.com





General

The PHA... Vision Sensor has been developed for the rack fine positioning of stock feeders. This device detects circular holes in the rack structure and determines the position deviation of these holes in relation to the target position. The Vision Sensor operates in two dimensions.

Mounting and Commissioning

Mount the PHA... Vision Sensor in such a way that the optical surface of the device captures the optimum distance to the carrier/hole (see "Technical Data"). The stability of the Vision Sensor mounting and the manner in which the vehicle is guided must ensure that the device is not operated outside of its depth of focus range.

All Vision Sensors can be adapted to optimally meet specific requirements by means of parameterization.

Indicators and Controls

The PHA... Vision Sensor is equipped with seven indicator LEDs for carrying out visual function checks and rapid diagnostics. The read head is equipped with two buttons at the back for activating the parameterization mode.

LEDs

| LED | Color | Labeling | Meaning |
|-----|------------------|---------------------|---------------------------------------|
| 1 | yellow | BUS LINK | PROFINET communication active |
| 2 | yellow | BUS TX / RX | Data transfer |
| 3 | red | BUS ERR | PROFINET communication error |
| 4 | green/red | PWR/ERR | Fault with power supply/general error |
| 5 | yellow | ZERO POS | Zero position reached |
| 6 | yellow | RANGE | Within detection/capture range |
| 7 | red/green/yellow | INTERNAL DIAGNOSTIC | Internal diagnostics |

External Parameterization

In order to parameterize the device externally, the parameterization code is required in the form of a data matrix containing the desired parameters. Data matrix code cards detailing the step-by-step process for externally parameterizing the device are printed in the operating instructions for the Vision Sensor.

- The Vision Sensor is switched over from normal operation to parameterization mode using button 2 on the back of the device. To switch the device over, button 2 must be pressed and held for more than two seconds. LED5 then flashes.
 - **Note:** Parameterization mode is exited automatically if the device is inactive for one minute. In this case, the Vision Sensor reverts to normal mode and operates without the settings having been changed.
- Place the parameterization code in the field of vision of the camera module. After the parameterization code is detected, the green LED4 lights up for one second. In the event of an invalid parameterization code, LED4 lights up red for two seconds.
- Briefly pressing button 2 will end parameterization mode. Unsaved changes will be lost.