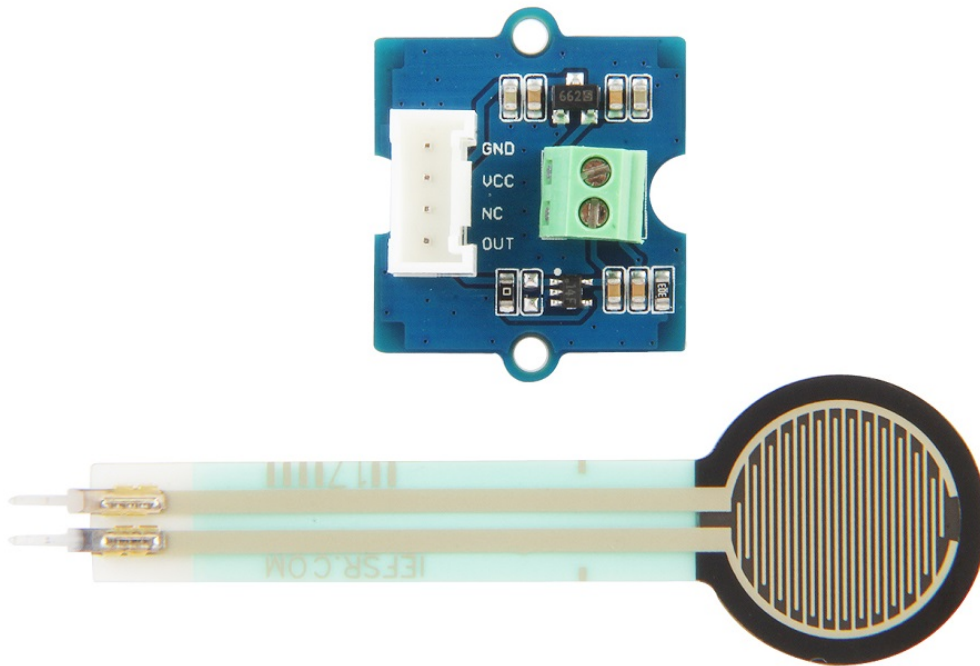


Grove - Round Force Sensor FSR402



The Grove-Round Force Sensor(FSR402) is a force sensitive module. At the end of the sensor there is a round force sensitive resistor, the resistance of which depends on pressure applied to this resistor. Simply say, the greater the pressure, the smaller the resistance. However, the output of this sensor is not strictly linear,

so we do not recommend it for accurate measurements. For more detail about the pressure-resistance diagram, please check the [FSR402 Datasheet](https://files.seeedstudio.com/wiki/Grove-Round_Force_Sensor_FSR402/res/FSR402.pdf) [https://files.seeedstudio.com/wiki/Grove-Round_Force_Sensor_FSR402/res/FSR402.pdf]

As the you can see, this module is based on FSR402, Interlink Electronics FSR® 400 Series is part of the single zone Force Sensing Resistor® family. Force Sensing Resistors, or FSR's, are robust polymer thick film (PTF) devices that exhibit a decrease in resistance with increase in force applied to the surface of the sensor. This force sensitivity is optimized for use in human machine interface devices including automotive electronics, medical systems, industrial controls and robotics.



[https://www.seeedstudio.com/Grove-Round-Force-Sensor-%28FSR402%29-p-3110.html]

Version

Product Version	Changes	Released Date
Grove-Round Force Sensor(FSR402)	Initial	Jun 2018

Features

- Analog output
- Reliable mechanical structure

- High durability:

Tested to 10 Million actuations, 1kg, 4Hz / -10% average resistance change

Specification

Item	Value
Working voltage	3.3V/5V
Force Sensitivity Range	0.2N--20N
Force Resolution	Continuous (analog)
Analog output	0-650
Non-Actuated Resistance	>10 MΩ
Minimum Resistance	1 KΩ
Device Rise Time	<3 Microseconds
Size	L: 75mm W: 20mm H: 11mm
Weight	2.5g
Package size	L: 140mm W: 90mm H: 10mm
Gross Weight	10g



Tip

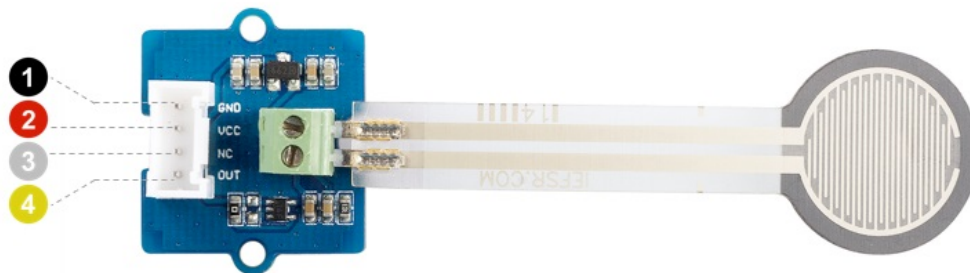
If you want to measure the Non-Actuated Resistance, please remove this thing from the sensor

Applications

- automotive electronics
- medical systems
- industrial controls
- robotics.

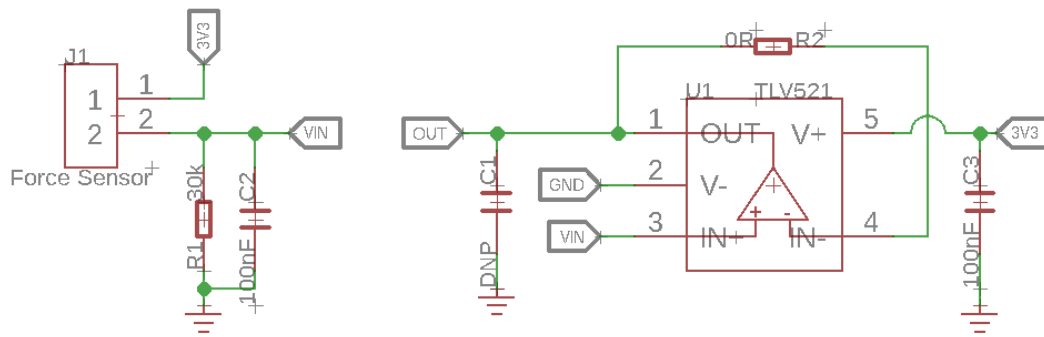
Hardware Overview

Pin Map



- ❶ GND: connect this module to the system GND
- ❷ VCC: you can use 5V or 3.3V for this module
- ❸ NC: none connected in this module
- ❹ OUT: output the Vout voltage signal

Schematic



This module use a DC-DC chip XC6206P332MR to provide a stable 3.3V, as you can see we called it 3V3. You can consider the Force Sensor **J1** as a variable resistance, let's say R_f . The greater the pressure, the smaller the R_f value.

There are two parts in the picture above, for the left part:

$$VIN = \frac{3.3 \cdot 30K}{30K + R_f}$$

For the right part, it's an Emitter follower, we use the amplifier **U1** to isolate the pre-stage and post-stage circuits.

$$V_{out} = VIN$$

So, the output is:

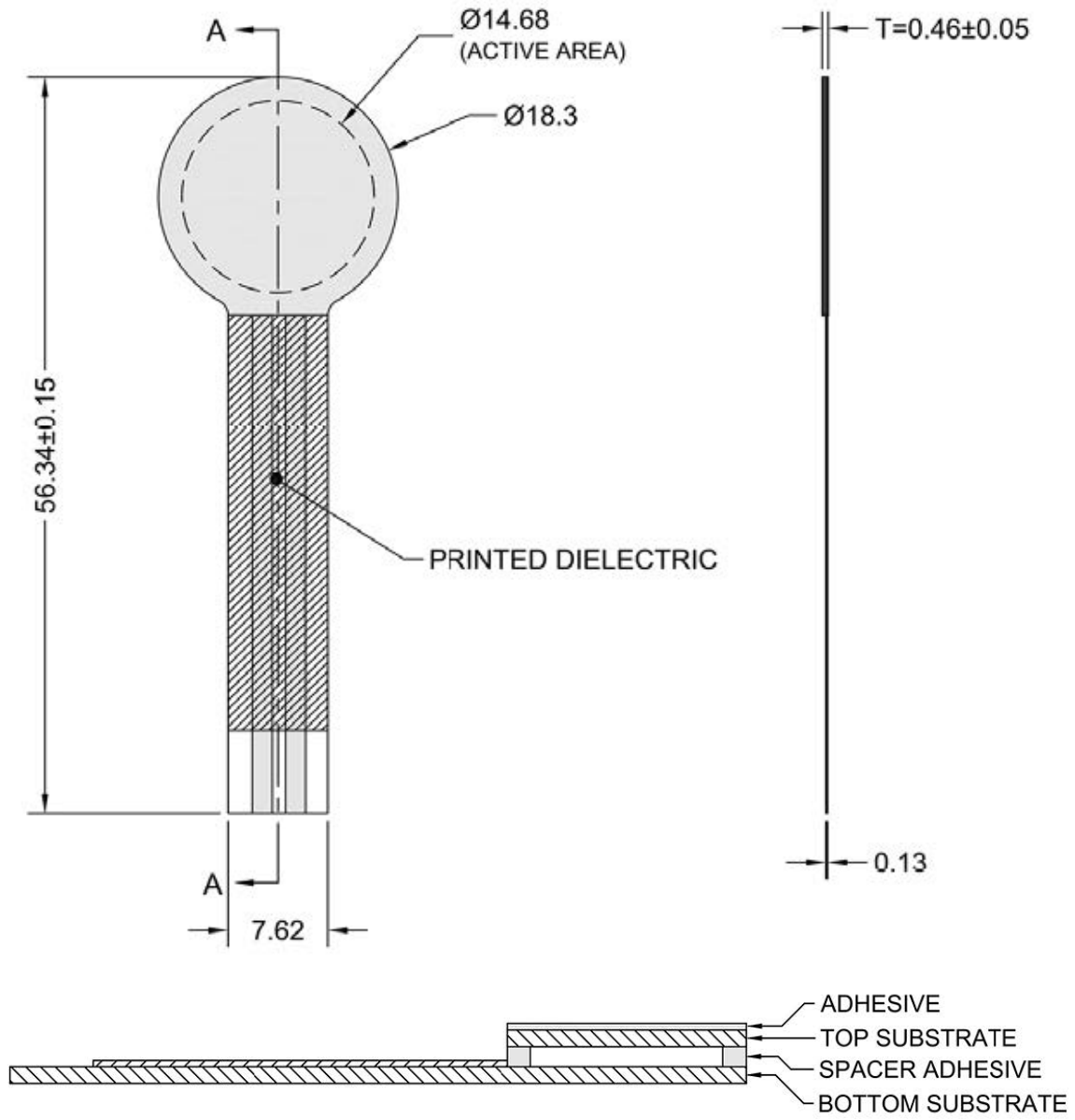
$$V_{out} = \frac{3.3 \cdot 30K}{30K + R_f}$$



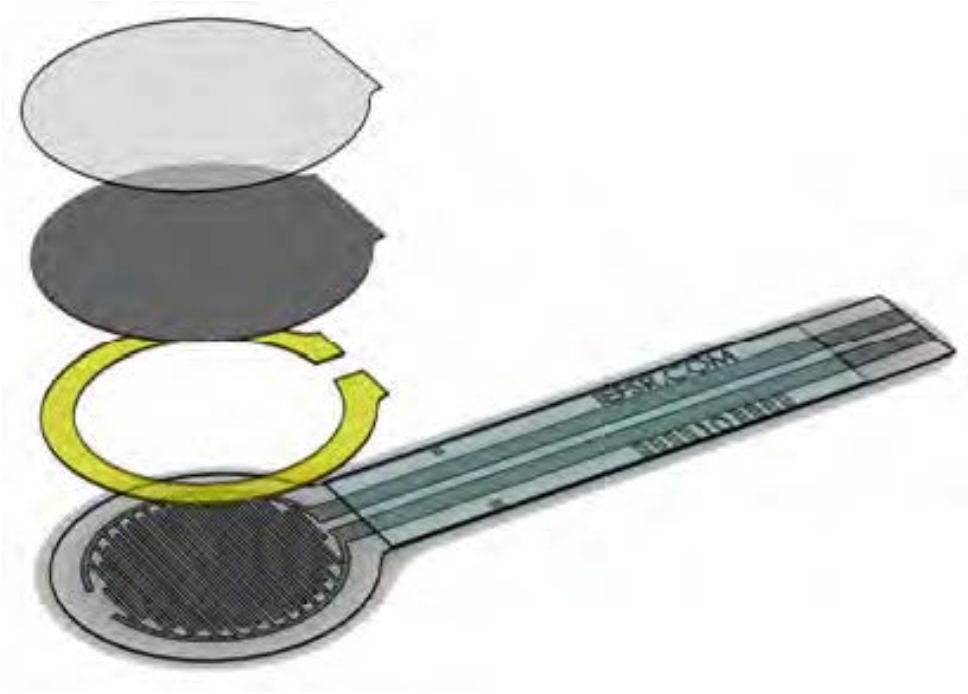
Tip

In this section we only show you part of the schematic, for the full document please refer to the [Resources](#) [#Resources]

Mechanical Drawing



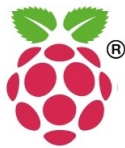
SECTION A-A
LAYER STACK-UP



Platforms Supported

Arduino

Raspberry
Pi



Caution

The platforms mentioned above as supported is/are an indication of the module's software or theoretical compatibility. We only provide software library or code examples for Arduino platform in most cases. It is not possible to provide software library / demo code for all possible MCU platforms. Hence, users have to write their own software library.

Getting Started

Play With Arduino

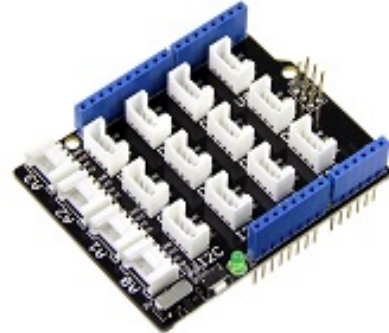
Hardware

Materials required

Seeeduino V4.2



Base Shield



[Get One Now](#)

[<https://www.seeedstudio.com/Seeeduino-V4.2-p-2517.html>]

[Get One Now](#)

[<https://www.seeedstudio.com/Base-Shield-V2-p-1378.html>]



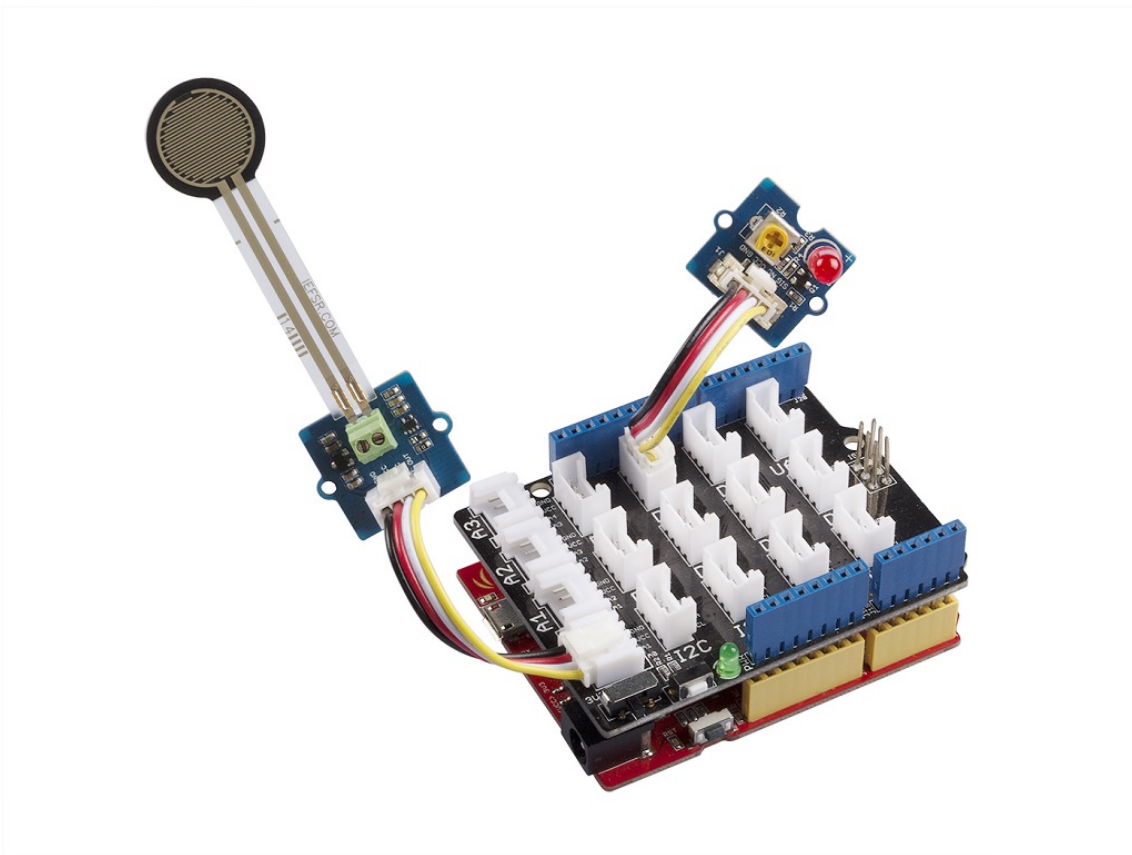
Note

1 Please plug the USB cable gently, otherwise you may damage the port. Please use the USB cable with 4 wires inside, the 2 wires cable can't transfer data. If you are not sure about the wire you have, you can click [here](https://www.seeedstudio.com/Micro-USB-Cable-48cm-p-1475.html) [<https://www.seeedstudio.com/Micro-USB-Cable-48cm-p-1475.html>] to buy

2 Each Grove module comes with a Grove cable when you buy. In case you lose the Grove cable, you can click [here](#)

[<https://www.seeedstudio.com/Grove-Universal-4-Pin-Buckled-20cm-Cable-%285-PCs-pack%29-p-936.html>] to buy.

- **Step 1.** Connect Grove-Round Force Sensor(FSR402) to port **A0** of Grove-Base Shield.
- **Step 2.** Plug the Grove-LED to port **D3** of Grove-Base Shield.
- **Step 3.** Plug Grove - Base Shield into Seeduino.
- **Step 4.** Connect Seeduino to PC via a USB cable.



Note

If we don't have Grove Base Shield, We also can directly connect this module to Seeduino as below.

Seeeduino	Grove-Round Force Sensor(FSR402)
5V	Red
GND	Black
Not Conencted	White
A0	Yellow

Seeeduino	Grove-LED
5V	Red
GND	Black
Not Conencted	White
D3	Yellow

Software



Note

If this is the first time you work with Arduino, we strongly recommend you to see [Getting Started with Arduino](https://wiki.seeedstudio.com/Getting_Started_with_Arduino/) [https://wiki.seeedstudio.com/Getting_Started_with_Arduino/] before the start.

- **Step 1.** Open the Arduino IDE and create a new file, then copy the following code into the new file.



```

1  /* How to use a Force sensitive resistor to fade an LED
2     More info: http://www.ardumotive.com/how-to-use-a-for
3     Dev: Michalis Vasilakis // Date: 22/9/2015 // www.ard
4
5     //Constants:
6     const int ledPin = 3;      //pin 3 has PWM funtion
7     const int sensorPin = A0; //pin A0 to read analog input
8
9     //Variables:
10    int value; //save analog value
11
12
13    void setup(){
14
15        pinMode(ledPin, OUTPUT); //Set pin 3 as 'output'
16        Serial.begin(9600);      //Begin serial communication
17
18    }
19
20    void loop(){
21
22        value = analogRead(sensorPin); //Read and save a
23        Serial.println(value);        //Print value
24        value = map(value, 0, 1023, 0, 255); //Map value 0-102.
25        analogWrite(ledPin,255-value); //Send PWM val
26        delay(100);                  //Small delay
27
28    }

```

- **Step 2.** Upload the demo. If you do not know how to upload the code, please check [How to upload code](#) [https://wiki.seeedstudio.com/Upload_Code/].
- **Step 3.** Open the **Serial Monitor** of Arduino IDE by click **Tool->Serial Monitor**. Or tap the **Ctrl + Shift + M** key at the same time. if every thing goes well, you will get the output of A0. Also, you will see the LED become lighter when you press the Round Force Sensor harder.

Schematic Online Viewer



Resources

- **[Zip]** [Grove-Round Force Sensor\(FSR402\) eagle file](https://files.seeedstudio.com/wiki/Grove-Round_Force_Sensor_FSR402/res/Grove-Round_Force_Sensor_FSR402.zip)
[https://files.seeedstudio.com/wiki/Grove-Round_Force_Sensor_FSR402/res/Grove-Round_Force_Sensor_FSR402.zip]

- **[Zip]** [Adafruit_NeoPixel-master](https://files.seeedstudio.com/wiki/Grove-Mech_Keycap/res/Adafruit_NeoPixel-master.zip)
[https://files.seeedstudio.com/wiki/Grove-Mech_Keycap/res/Adafruit_NeoPixel-master.zip]
- **[PDF]** [Datasheet of FSR402](https://files.seeedstudio.com/wiki/Grove-Round_Force_Sensor_FSR402/res/FSR402.pdf)
[https://files.seeedstudio.com/wiki/Grove-Round_Force_Sensor_FSR402/res/FSR402.pdf]

Project

This is the introduction Video of this product, simple demos, you can have a try.



Tech Support

Please do not hesitate to submit the issue into our [forum](https://forum.seeedstudio.com/)
[https://forum.seeedstudio.com/].



[https://www.seeedstudio.com/act-4.html?utm_source=wiki&utm_medium=wikibanner&utm_campaign=newproducts]

