Features

- 2-channel signal conditioner
- 24 V DC supply
- PNP/push-pull, dry contacts or NAMUR inputs
- Selectable frequency trip values
- 2 relay contact outputs
- Start-up override
- Selectable mode of operation
- Up to SIL2 acc. to IEC 61508

Function

This signal conditioner is a zero speed/standstill monitor that accepts input frequency pulses and triggers an output when the frequency drops below a selected value.

Two startup override values are available. This unit can also be used to determine rotation direction.

During an error condition, relays revert to their de-energized state and LEDs indicate the fault according to NAMUR NE44.

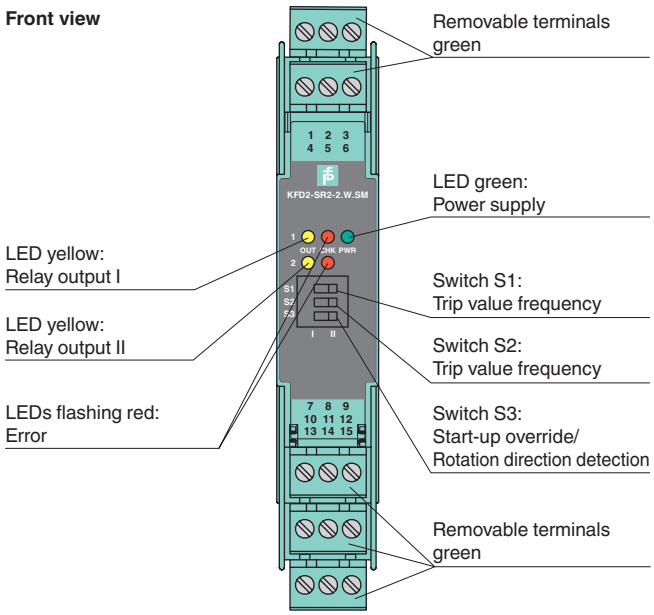
The available diagnostic LEDs show rotation detection, limit trip indicator, power on, and hardware error indication.

The unit is easily programmed via switches mounted on the front of the unit.

For additional information, refer to www.pepperl-fuchs.com.

Assembly

Front view



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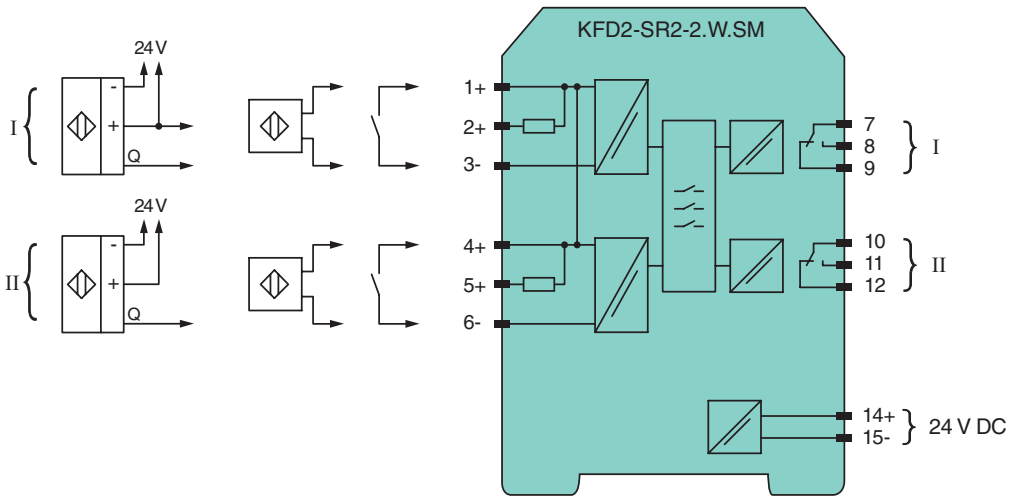
Connection



Release date 2013-02-21 17:17 Date of issue 2015-02-16 132965_eng.xml

General specifications		
Signal type		Digital Input
Programming		via DIP switch and programmable
Supply		
Connection		terminals 14+, 15-
Rated voltage	U_n	20 ... 30 V DC
Power consumption		≤ 1.5 W
Indicators/operating means		
LED yellow		switching state
Input		
Connection		Input I: terminals 1+, 2+, 3- ; Input II: terminals 4+, 5+, 6-
Rated values		acc. to EN 60947-5-6 (NAMUR)
Open circuit voltage/short-circuit current		approx. 8 V DC / approx. 8 mA
Switching point/switching hysteresis		1.2 ... 2.1 mA / approx. 0.2 mA
Line fault detection		not available
Control input		sensor power supply approx. 8.2 V, impedance 1.2 kΩ
Pulse duration		> 200 µs for standstill monitoring, > 250 µs for rotation direction detecion
Output		
Connection		output I: terminals 7, 8, 9 ; output II: terminals 10, 11, 12
Relay		2 changeover contacts
Contact loading		253 V AC/2 A/cos ϕ > 0.7; 126.5 V AC/4 A/cos ϕ > 0.7; 40 V DC/2 A resistive load
Minimum switch current		2 mA / 24 V DC
Energized/De-energized delay		approx. 20 ms / approx. 20 ms
Mechanical life		10^7 switching cycles
Trip value	f_{max}	for standstill monitoring: 0.1 Hz; 0.5 Hz; 2 Hz; 10 Hz adjustable via DIP switch (S1 and S2)
Transfer characteristics		
Accuracy		5 % (S3 = I), 30 % (S3 = II)
Start-up override		5 seconds or 20 seconds, programmable
Frequency range		≤ 2 kHz
Rotation direction detection		90° phase difference between pulse input signal 1 and 2, overlapping ≥ 125 µs
Electrical isolation		
Input/Output		reinforced insulation according to IEC/EN 61010-1, rated insulation voltage 300 V_{eff}
Input/power supply		reinforced insulation according to IEC/EN 61010-1, rated insulation voltage 300 V_{eff}
Output/power supply		reinforced insulation according to IEC/EN 61010-1, rated insulation voltage 300 V_{eff}
Output/Output		reinforced insulation according to IEC/EN 61010-1, rated insulation voltage 300 V_{eff}
Directive conformity		
Electromagnetic compatibility		
Directive 2004/108/EC		EN 61326-1:2006
Low voltage		
Directive 2006/95/EC		EN 61010-1:2010
Conformity		
Electromagnetic compatibility		NE 21:2006
Degree of protection		IEC 60529:2001
Input		EN 60947-5-6:2000
Ambient conditions		
Ambient temperature		-20 ... 60 °C (-4 ... 140 °F)
Mechanical specifications		
Degree of protection		IP20
Mass		approx. 150 g
Dimensions		20 x 119 x 115 mm (0.8 x 4.7 x 4.5 in) , housing type B2
Mounting		on 35 mm DIN mounting rail acc. to EN 60715:2001
General information		
Supplementary information		Statement of Conformity, Declaration of Conformity, Attestation of Conformity and instructions have to be observed where applicable. For information see www.pepperl-fuchs.com.

Release date 2013-02-21 17:17 Date of issue 2015-02-16 132965_eng.xml

Operating principle

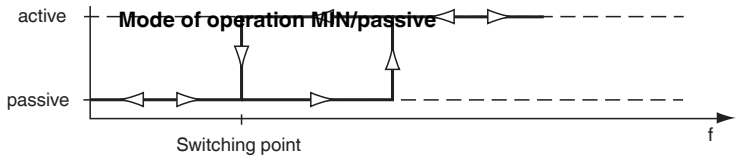
The function of standstill monitor with start-up override (S3 = I) or standstill monitor with rotation direction monitoring (S3 = II) can be selected by means of DIP switches.

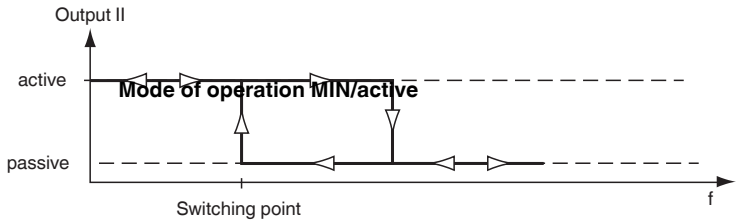
S3:	I	II
Function:	Standstill monitor with start-up override	Standstill monitor with rotation direction monitoring
Input I:	Pulse input 1: NAMUR contacts (bounce-free)	Pulse input 1: NAMUR contacts (bounce-free)
Input II:	Start-up override: contact terminal 4 + 6: 20 seconds contact terminal 5 + 6: 5 seconds	Pulse input 2: NAMUR contacts (bounce-free)
Output I:	MIN/passive	MIN/passive
Output II:	MIN/active	Direction of rotation/error

Standstill monitor with start-up override (S3 = I)

If the frequency falls below the trip value set with the DIP switches S1 and S2, the standstill monitor with start-up override switches the output I to passive and the output II to active. Input I is used to monitor the frequency of rising current edges. Signal transmitters can be sensors in accordance with EN 60947-5-6 (NAMUR) or contacts. A start-up override can be initiated via input II. The duration of the start-up override can be selected between 5 and 20 seconds by means of a bridge (starting trigger) or an external trigger signal. During the start-up override time the outputs assume the "no standstill" state.

Trip value	Hysteresis	Switch S2	Switch S1
0.1 Hz	**0.02 Hz**	**I**	**I**
0.5 Hz	**0.1 Hz**	**I**	**II**
2 Hz	**0.4 Hz**	**II**	**I**
10 Hz	**2 Hz**	**II**	**II**

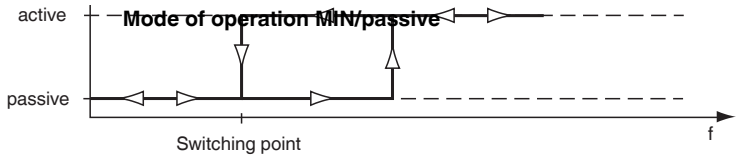


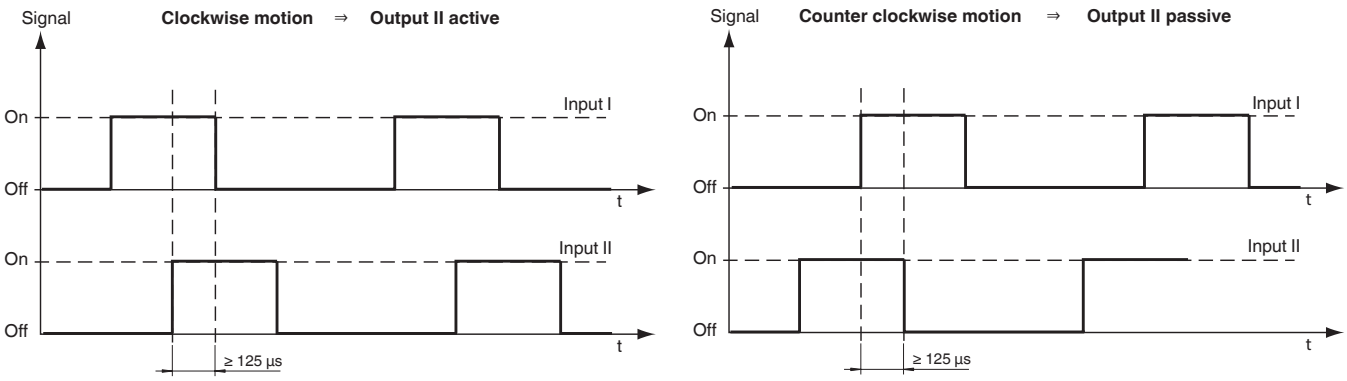


Release date 2013-02-21 17:17 Date of issue 2015-02-16 132965_eng.xml

Standstill monitor with rotation direction monitoring (S3 = II)

The device also offers stand still monitoring with direction of rotation monitoring as an alternative to stand still monitoring with start-up override. The trip values are identical to the standstill monitor with start-up override. At input II a signal that is offset by 90° to input I has to be applied; in this context minimum signal overlapping should be ensured. Signal transmitters at input I and input II can be sensors in accordance with DIN EN 60947-5-6 (NAMUR) or contacts. Output I is used for standstill signalling and switches to a de-energized state (passive) in the event of a standstill. Output II is switched to active when the direction of rotation is clockwise. If a reverse rotation is detected or if a signal overlap is missing, output II switches to a de-energized state (passive). In this case it can be concluded, that the sensor is misadjusted or defective. If the sensor at input I is misadjusted or defective, input II is used for standstill monitoring.





Behaviour during malfunction: continuous monitoring of the device for errors in internal memory

If an error occurs, both relays go into the secure state and the red LEDs indicate the error.

Advice on use in SIL2 applications (Functional safety)

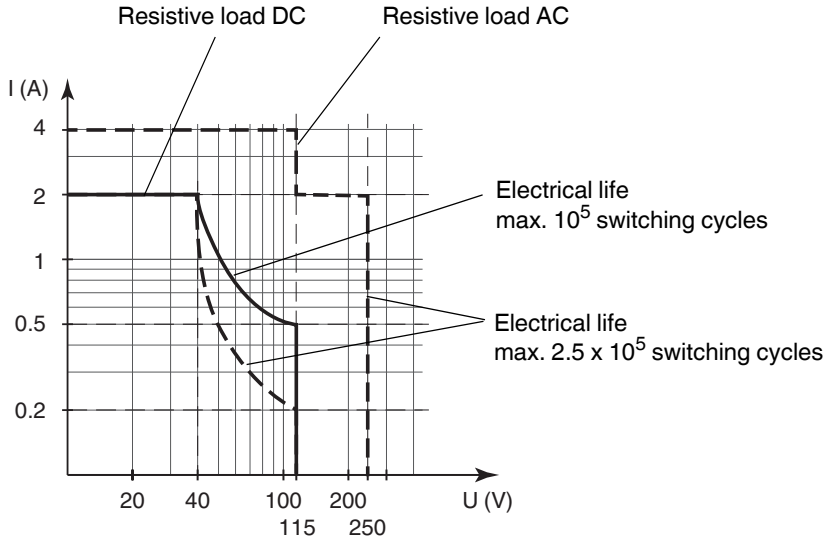
Care should be taken to ensure that the relays are de-energized (passive) in the critical condition of the application. Then, in the event of a power failure (de-energized, passive relay) the safety-critical state (energized) relay cannot be achieved.

Example 1:
The protective guard for a rotating shaft must remain locked in position until the shaft has stopped rotating. The safety-critical condition is the rotation of the shaft (risk of injury).For this reason, the locking of the protective guard should be achieved by means of a de-energized (passive) relay. The relay shall be energized (active) only when the shaft has stopped (safe condition). This device function is only achieved with "Standstill monitoring with start-up override" (S3 = I) and control of the protective guard with relay 2.

Example 2:
The cooling of a critical process by means of fans/coolant pumps has to be monitored. The safety-critical condition is the standstill of the fans/pumps (overheating). For this reason an alarm must be triggered when a relay has de-energized (passive). As long as the fans or the pumps are running (safety condition) the relay is energized (active). This device function can be achieved with "Standstill monitoring with start-up override" (S3 = I) and "Standstill monitoring with direction of rotation signalling" (S3 = II) with relay 1.

Release date 2013-02-21 17:17 Date of issue 2015-02-16 132965_eng.xml

Maximum switching power of output contacts



The maximum number of switching cycles is depending on the electrical load and may be higher when reduced currents and voltages are applied.

Accessories

Power feed module KFD2-EB2

The power feed module is used to supply the devices with 24 V DC via the Power Rail. The fuse-protected power feed module can supply up to 150 individual devices depending on the power consumption of the devices. Collective error messages received from the Power Rail activate a galvanically-isolated mechanical contact.

Power Rail UPR-03

The Power Rail UPR-03 is a complete unit consisting of the electrical insert and an aluminium profile rail 35 mm x 15 mm. To make electrical contact, the devices are simply engaged.

Profile Rail K-DUCT with Power Rail

The profile rail K-DUCT is an aluminum profile rail with Power Rail insert and two integral cable ducts for system and field cables. Due to this assembly no additional cable guides are necessary.

Power Rail and Profile Rail must not be fed via the device terminals of the individual devices!

Release date 2013-02-21 17:17 Date of issue 2015-02-16 132965_eng.xml