

# 4/3-way servo solenoid directional control valves, pilot operated, with electrical position feedback (Lvdt DC/DC $\pm 10V$ )

**RE 29086/01.09**

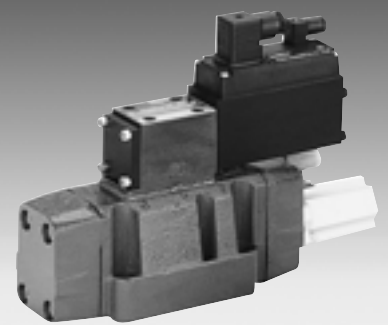
Replaces: 01.05

**Type 4WRL 10...35, symbols V/V1**

Sizes (NG) 10, 16, 25, 27, 35

Unit series 3X

Maximum working pressure P, A, B 350 bar (NG27: 280 bar)

Nominal flow rate 55...1000 l/min ( $\Delta p = 10$  bar)

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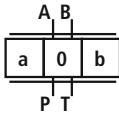
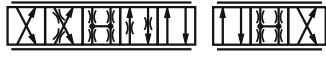
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## Features

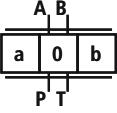

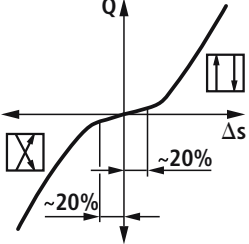
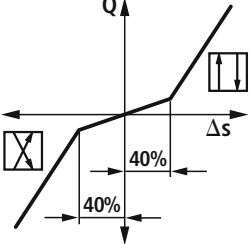
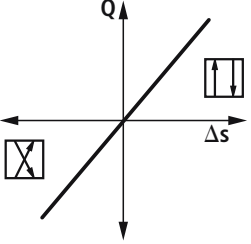
- Pilot operated 4/3-way servo solenoid directional control valves NG10 to NG35
- Pilot valve NG6, with control piston and sleeve in servo quality, actuated on one side, 4/4 fail-safe position when switched off
- Control solenoid with electrical position feedback and electronics for position transducer (Lvdt DC/DC)
- Main stage in servo quality with position feedback
- Flow characteristic
  - M = Progressive with fine metering notch
  - P = Non-linear curve
  - L = Linear
- For subplate attachment, mounting hole configuration NG10 to ISO 4401-05-05-0-05, NG16 to ISO 4401-07-07-0-05, NG25/27 to ISO 4401-08-08-0-05 and NG35 to ISO 4401-10-09-0-05
- Subplates as per Technical Data Sheet, NG10 RE 45055, NG16 RE 45057, NG25/27 RE 45059 and NG35 RE 45060 (order separately)
- Plug-in connectors to DIN 43560-AM2  
Solenoid 2P+PE/M16 x 1.5, position transducer 4P/Pg7 included in delivery, see Technical Data Sheet RE 08008
- External trigger electronics (order separately)
  - Electric amplifier for standard curve “M” and “L”
  - Electric amplifier for non-linear curve “P”

For information regarding the available spare parts see:  
[www.boschrexroth.com/spc](http://www.boschrexroth.com/spc)

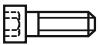


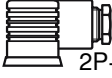
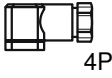
## Ordering data

4WRL						-3X/G24		Z4/M		*
For external trigger electronics	= no desig.									Further information in plain text
NG10	= 10									M = NBR seals, suitable for mineral oils (HL, HLP) to DIN 51524
NG16	= 16									<b>Electrical connection</b> Z4 = with plug-in connector, with plug to DIN 43560-AM2 Plug-in connector included in delivery
NG25	= 25									
NG27 <sup>1)</sup>	= 27									
NG35 <sup>2)</sup>	= 35									
<b>Control spool symbols</b>										<b>Control oil inlet "x"</b> <b>control oil return "y"</b> no desig. = "x" = external, "y" = external E = "x" = internal, "y" = external ET = "x" = internal, "y" = internal T = "x" = external, "y" = internal
4/3-way version										
										<b>Power supply of trigger electronics</b> G24 = +24 V DC 3X = Unit series 30 to 39 (installation and connection dimensions unchanged)
With symbol V1:										
P → A: $q_v$	B → T: $q_v/2$									<b>Flow characteristic</b> M = Progressive with linear fine metering P = Non-linear curve, linear (kink at 40%) L = Linear
P → B: $q_v/2$	A → T: $q_v$									
<b>Nominal flow rate</b>										<sup>1)</sup> NG27 is a high-flow version of NG25, ports P, A, B and T have $\varnothing$ 32 mm in the main stage. Contrary to standard ISO 4401-08-08-0-05, ports P, A, B and T may be drilled to max. $\varnothing$ 30 mm in the control block. These valves therefore offer higher flow rates $Q_A : Q_B$ <sup>2)</sup> NG35 is a high-flow version of NG32, ports P, A, B and T have $\varnothing$ 50 mm in the main stage. Contrary to standard ISO 4401-10-09-0-05, ports P, A, B and T may be drilled to max. $\varnothing$ 48 mm in the control block. These valves therefore offer higher flow rates $Q_A : Q_B$ <sup>3)</sup> $Q_N$ : Flow characteristic "P" <sup>4)</sup> $Q_N$ : Flow characteristic "M" or "L"
at 10 bar valve pressure difference (5 bar per metering notch)										
<b>NG10</b>										
55 l/min <sup>4)</sup>	= 55									
70 l/min <sup>3)</sup>	= 70									
85 l/min <sup>4)</sup>	= 85									
<b>NG16</b>										
100 l/min <sup>3)</sup>	= 55									
120 l/min <sup>4)</sup>	= 70									
150 l/min <sup>3)</sup>	= 85									
200 l/min <sup>4)</sup>	= 200									
<b>NG25</b>										
300 l/min <sup>3)</sup>	= 300									
370 l/min <sup>4)</sup>	= 370									
<b>NG27</b>										
430 l/min <sup>1)4)</sup>	= 430									
<b>NG35</b>										
1000 l/min <sup>2)4)</sup>	= 1000									

## Symbols

	M: Progressive with fine metering	P: Non-linear, linear (40%)	L: Linear
			

## Accessories, not included in delivery

Valve fastening bolts	NG10	4 x ISO 4762-M6 x 40-10.9-N67F821 70	<b>2 910 151 209</b>
	NG16	2 x ISO 4762-M6 x 45-10.9-N67F821 70	<b>2 910 151 211</b>
		4 x ISO 4762-M10 x 50-10.9-N67F821 70	<b>2 910 151 301</b>
	NG25/27	6 x ISO 4762-M12 x 60-10.9-N67F821 70	<b>2 910 151 354</b>
	NG35	6 x ISO 4762-M20 x 90-10.9-N67F821 70	<b>2 910 151 532</b>
 	VT-VVRA1-527-20/V0/2STV, see RE 30045	<b>0 811 405 063</b>	
	VT-VVRA1-527-20/V0/K40-AGC-2STV, see RE30043	<b>0 811 405 068</b>	
 	2P+PE (M16 x 1.5) and 4P (Pg7) included in delivery, also see RE 08008		

## Testing and service equipment

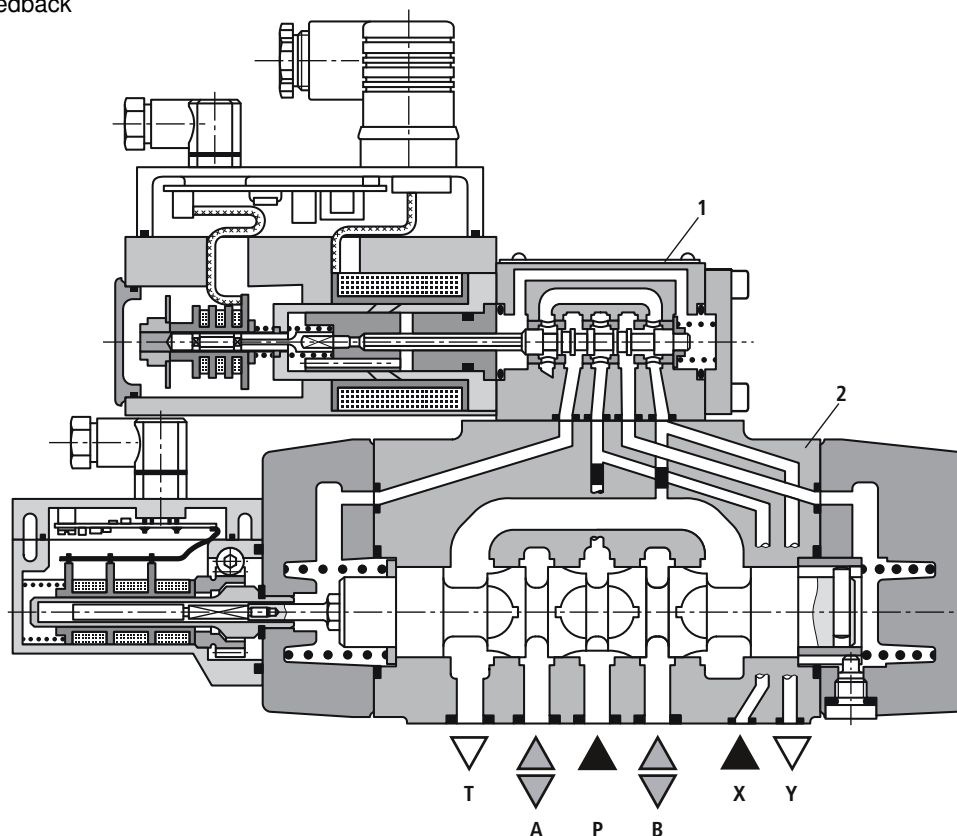
- Test box type VT-PE-TB2, see RE 30064
- Test adapter type VT-PA-3, see RE 30070

## Function, sectional diagram

### Construction

The valve consists of two main assemblies:

- Pilot valve (1) with control spool and sleeve, return springs, control solenoid and inductive position transducer
- Main stage (2) with centering springs and position feedback



### Functional description

When the control solenoid is not actuated, the control spool is held by springs in the fail-safe position, and the main stage spool remains in spring-centered mid position at 1...6% of the stroke in the direction P-B/A-T. In the on-board electronics, the pre-defined setpoint is compared with the actual value for the position of the main stage control spool. In the event of an error signal, the control solenoid is actuated, and the pilot spool is moved as the magnetic force changes. The flow released through the control cross-sections causes the main control spool to move. The stroke/control cross-section of the main control spool is controlled proportionately to the setpoint. If the input setpoint is 0 V, the electronics move the main stage control spool to mid position. The control oil is conveyed to the pilot valve either internally via port P or externally via port X. The oil returns to the tank internally via port T or externally via port Y.

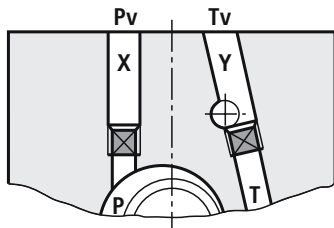
### Power failure

In the event of a power failure or an open circuit, the on-board electronics cut off the electricity to the control solenoid and the pilot spool moves to the fail-safe position, relieving the control oil chambers of the main stage. The main stage control spool is held by springs in mid position.

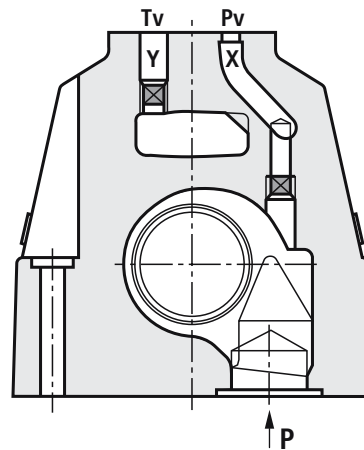
## Control oil supply

The pilot valve can be supplied both via ports X and Y (externally) and via the main flow channels P and T.

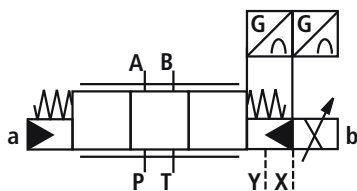
NG10, 25, 27, 35



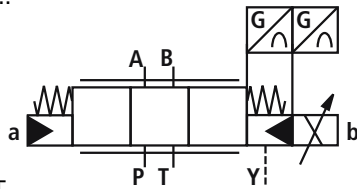
NG16



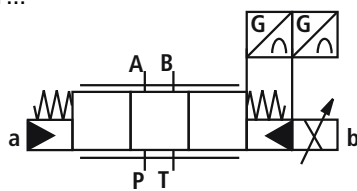
Type...-3X...



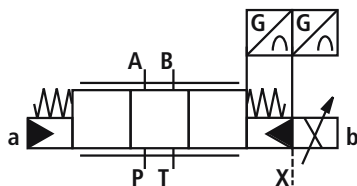
Type...-3X...E...



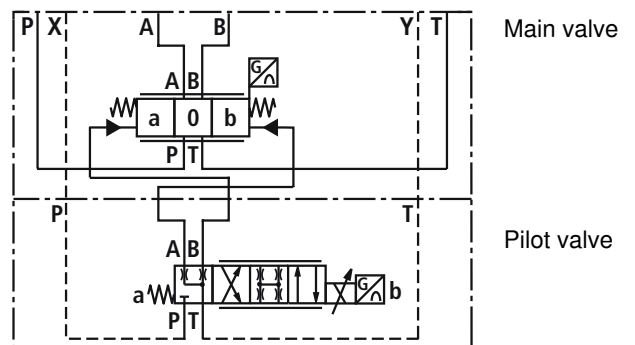
Type...-3X...ET...



Type...-3X...T...



Symbol in detail  
(external control oil inlet and outlet)



**No designation =**

**E =**

**ET =**

**T =**

“x” = external

“x” = internal

“x” = internal

“x” = external

“y” = external

“y” = external

“y” = internal

“y” = internal

### Important

Hydraulic symbols are largely derived from the symbols of the switching valves. 4/3-way servo solenoid directional control valves (pilot operated) do not have a closed mid position when switched off! They only perform their function in an active, closed control loop, even if the pilot valve features a fail-safe 4th position. See technical data for details on “switch-off behavior”.

## Technical data

General						
Construction	Spool type valve, pilot operated					
Actuation	Servo solenoid directional control valve NG6, with position controller for pilot valve and main stage, external electric amplifier					
Type of mounting	Subplate, mounting hole configuration NG10...35 to ISO 4401-...					
Installation position	Optional					
Ambient temperature range	°C	-20...+50				
Weight	kg	<b>NG10</b> 8.35	<b>NG16</b> 10	<b>NG25</b> 18	<b>NG27</b> 18	<b>NG35</b> 80
Vibration resistance, test condition	Max. 25 g, shaken in 3 dimensions (24 h)					

### Hydraulic (measured with HLP 46, $\vartheta_{oil} = 40\text{ °C} \pm 5\text{ °C}$ )

Pressure fluid	Hydraulic oil to DIN 51524...535, other fluids after prior consultation												
Viscosity range	recommended	mm <sup>2</sup> /s	20...100										
	max. permitted	mm <sup>2</sup> /s	10...800										
Pressure fluid temperature range	°C	-20...+80											
Maximum permissible degree of contamination of pressure fluid Purity class to ISO 4406 (c)	Class 18/16/13 <sup>1)</sup>												
Flow direction	See symbol												
Nominal flow at $\Delta p = 5\text{ bar per notch}^2)$	l/min	<b>NG10</b>			<b>NG16</b>				<b>NG25</b>		<b>NG27</b>	<b>NG35</b>	
		55	70	85	100	120	150	200	300	370	430	1000	
Max. working pressure	Ports P, A, B External control oil inlet	bar	350			350				350		280	350
	Ports P, A, B Internal control oil inlet	bar	250										
	Ports T, X, Y	bar	250										
Min. control oil pressure in "pilot stage"	bar	10											
$Q_{max}$	l/min	170			450				900		1000	3500	
$Q_N$ pilot valve	l/min	4			12				24		24	40	
Leakage of pilot valve at 100 bar	cm <sup>3</sup> /min	< 180			< 300				< 500		< 500	< 900	
Leakage of main stage at 100 bar	cm <sup>3</sup> /min	< 400	< 600	< 1000				< 1000		< 1000	< 6000		

### Static/Dynamic

Hysteresis	%	< 0.1, scarcely measurable										
Manufacturing tolerance for $Q_{max}$	%	$\leq 10$										
Response time for signal change (at X = 100 bar)	0...100%	25			40				45		45	130
	0...10%	15			18				20		20	60
Response time for signal change (at X = 10 bar)	0...100%	85			90				150		150	500
	0...10%	50			40				80		80	200
Switch-off behavior	After electrical switch-off: pilot valve in fail-safe Main stage moves to spring-centered "mid position": 1...6% P-B/A-T											
Thermal drift	Zero point displacement < 1% at $\Delta T = 40\text{ °C}$											
Zero adjustment	Adjustable $\pm 5\%$ via valve amplifier											

<sup>1)</sup> The purity classes stated for the components must be complied with in hydraulic systems. Effective filtration prevents problems and also extends the service life of components. For a selection of filters, see Technical Data Sheets RE 50070, RE 50076 and RE 50081.

<sup>2)</sup> Flow rate at a different  $\Delta p$   $Q_x = Q_{nom} \cdot \sqrt{\frac{\Delta p_x}{5}}$

## Technical data

Electrical		
Cyclic duration factor	%	100 ED
Power supply		24 V DC <sub>nom</sub> (external electric amplifier)
Degree of protection		IP 65 to DIN 40050
Solenoid connector		Connector DIN 43560/ISO 4400 M16x1.5 (2P+PE)
Position transducer connector		Connector Pg7 (4P)
Max. solenoid current	A	2.7
Coil resistance $R_{20}$	$\Omega$	2.5
Max. power consumption at 100% load and operating temperature	VA	40
Position transducer DC/DC technology		Supply: +15 V/35 mA -15 V/25 mA
		Signal: 0...±10 V ( $R_L \geq 10 \text{ k}\Omega$ )

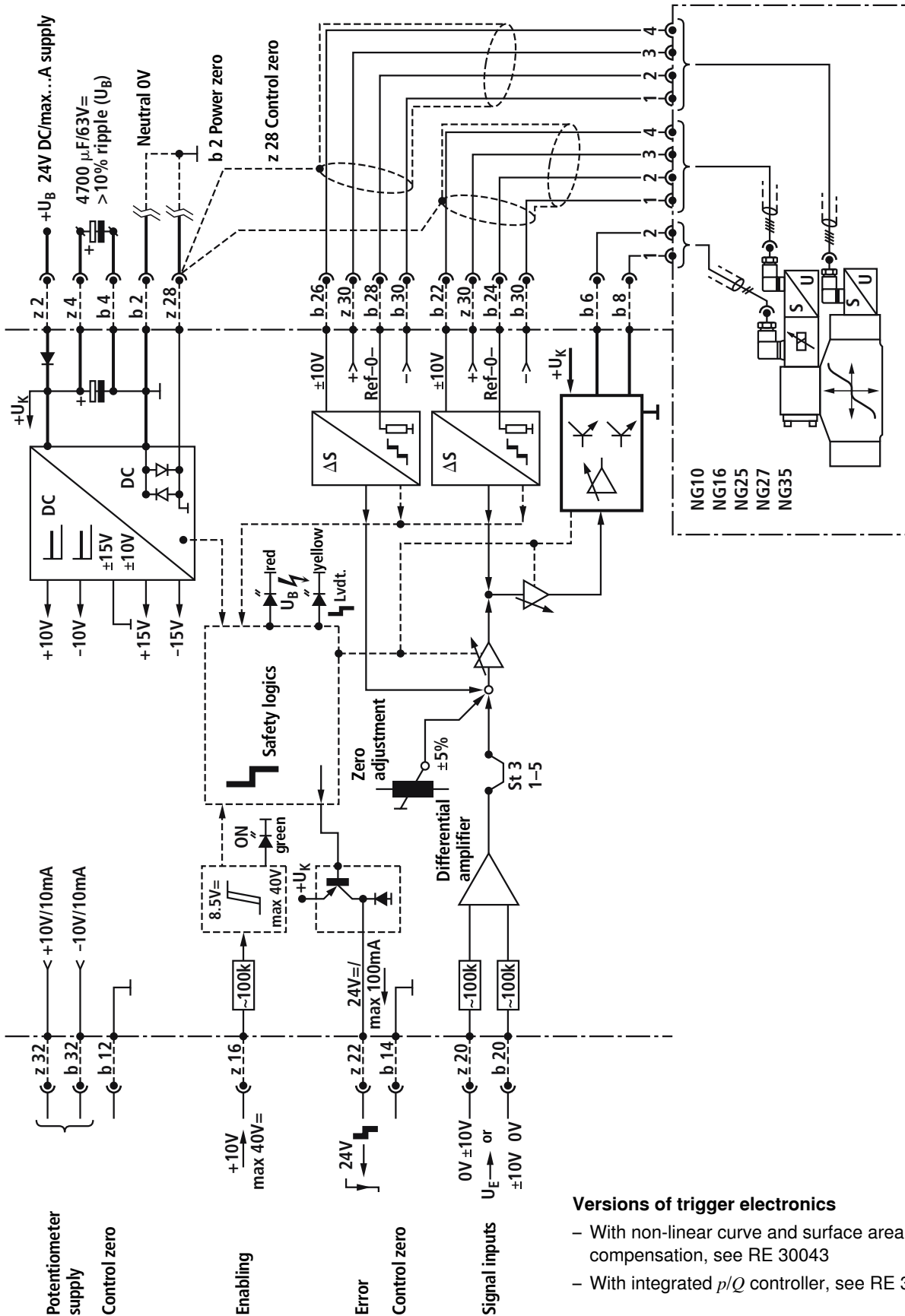
All characteristics only in connection with valve amplifier 0 811 405 063

### Important

Pilot operated 4/3-way servo solenoid directional control valves only perform their function in an active closed control loop and do not have a fail-safe position when switched off. For this reason, many applications require the use of "external check valves", which must be taken into account during the On/Off switching sequence.

# Valve with external trigger electronics (standard linear curve: M, L)

## Block diagram/pin assignment



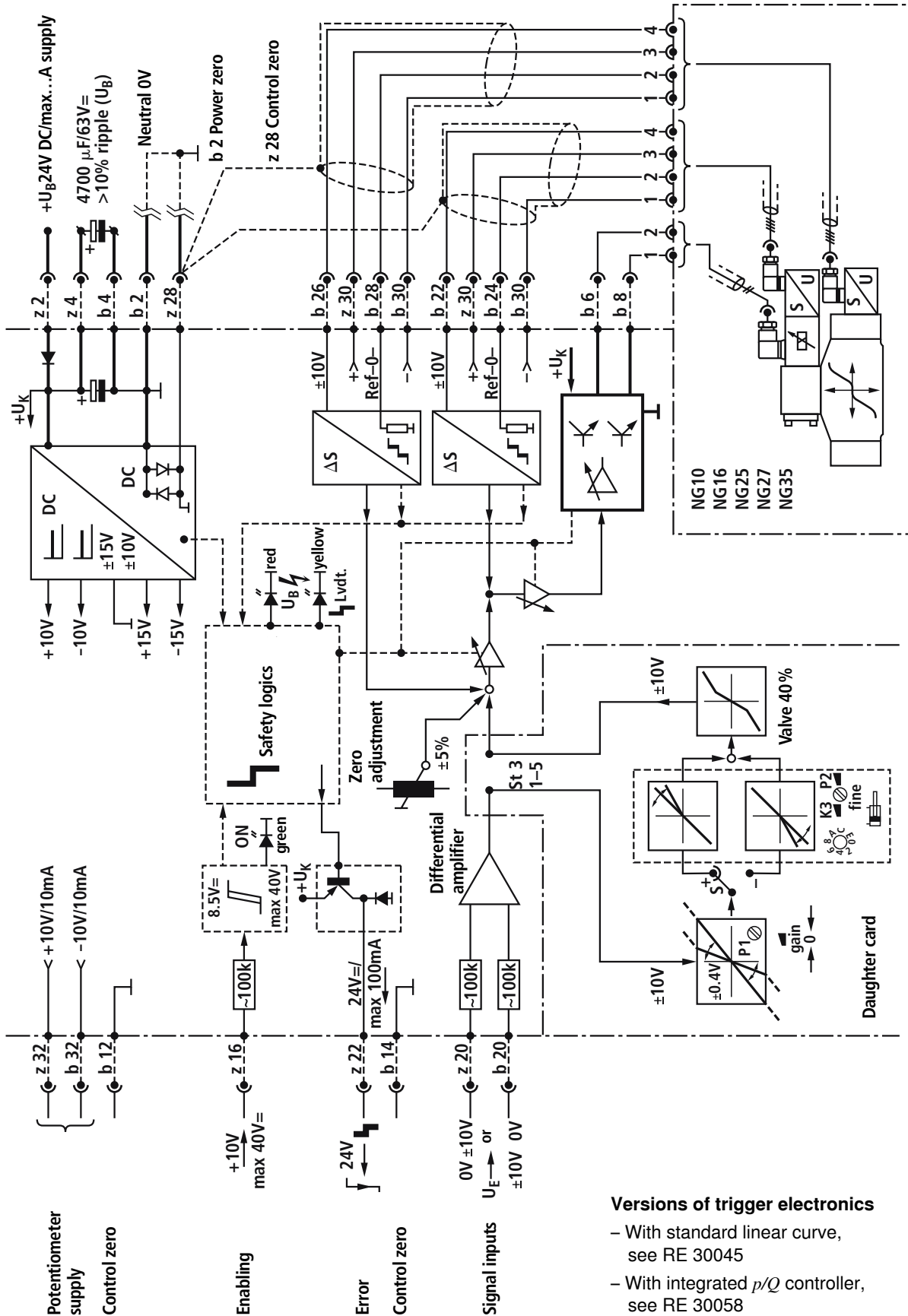
### Versions of trigger electronics

- With non-linear curve and surface area compensation, see RE 30043
- With integrated p/Q controller, see RE 30058



# Valve with external trigger electronics (non-linear curve: P)

## Block diagram/pin assignment



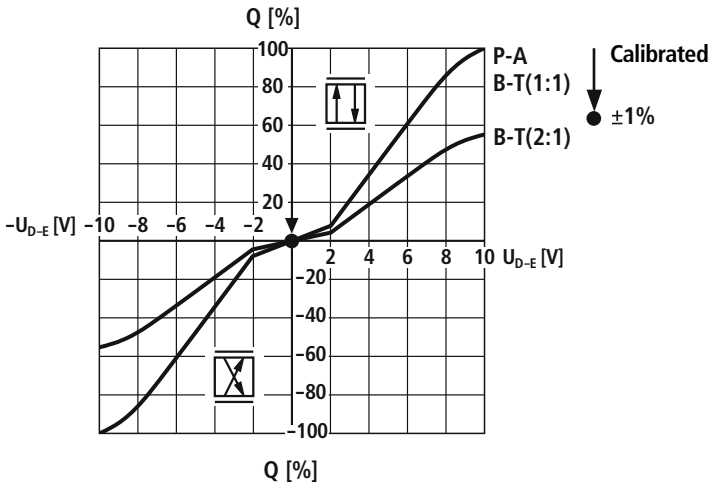
**Versions of trigger electronics**

- With standard linear curve, see RE 30045
- With integrated p/Q controller, see RE 30058

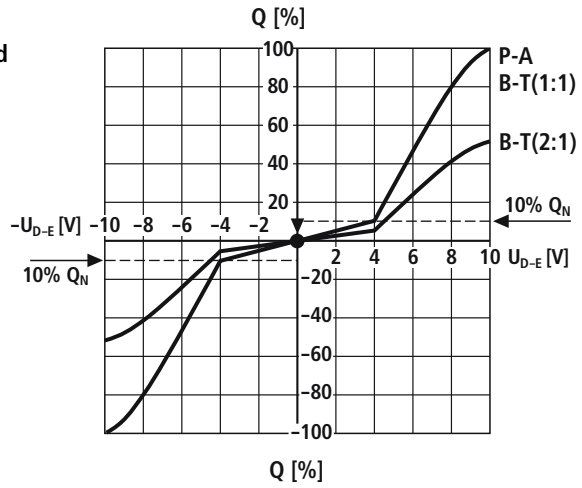
### Characteristic curves (measured with HLP 46, $\vartheta_{oil} = 40 \text{ }^\circ\text{C} \pm 5 \text{ }^\circ\text{C}$ )

Flow rate – signal function  $Q = f(U_E)$

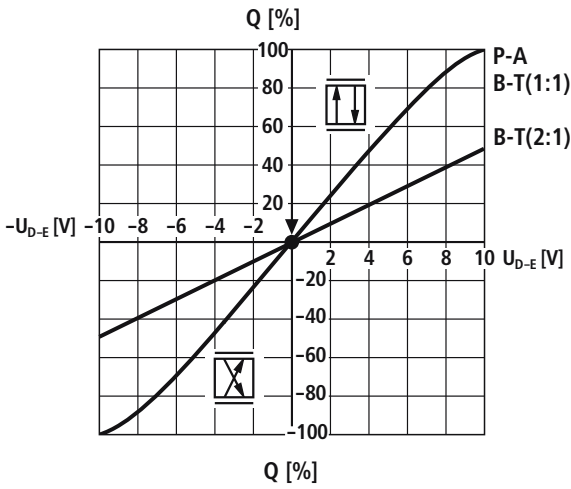
Flow characteristic M



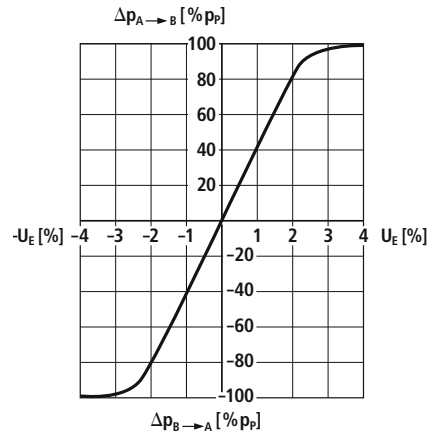
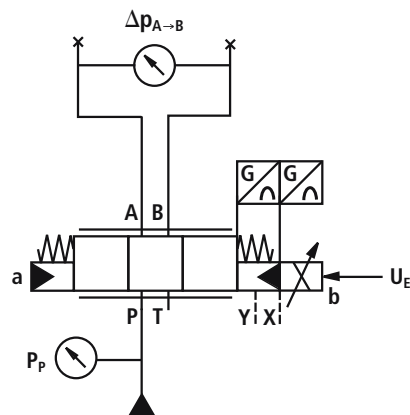
Flow characteristic P



Flow characteristic L



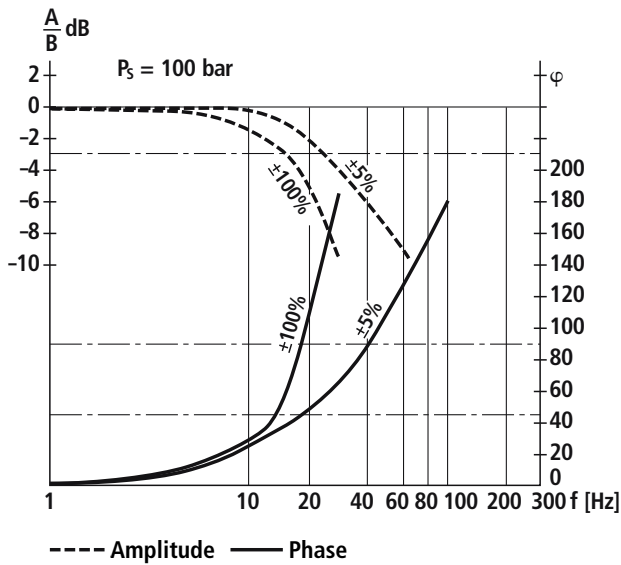
### Pressure gain



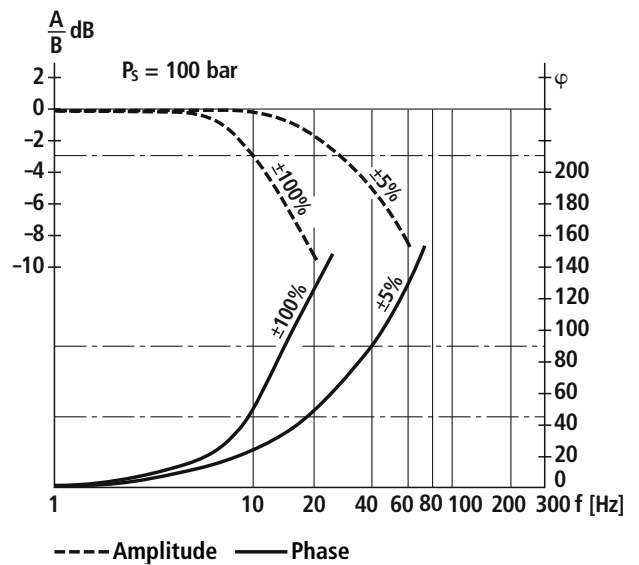
**Characteristic curves** (measured with HLP 46,  $\vartheta_{oil} = 40 \text{ }^\circ\text{C} \pm 5 \text{ }^\circ\text{C}$ )

**Bode diagram**

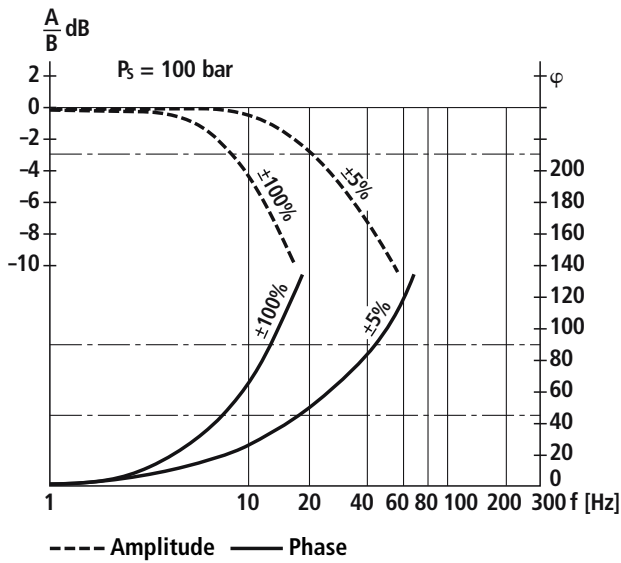
**NG10**



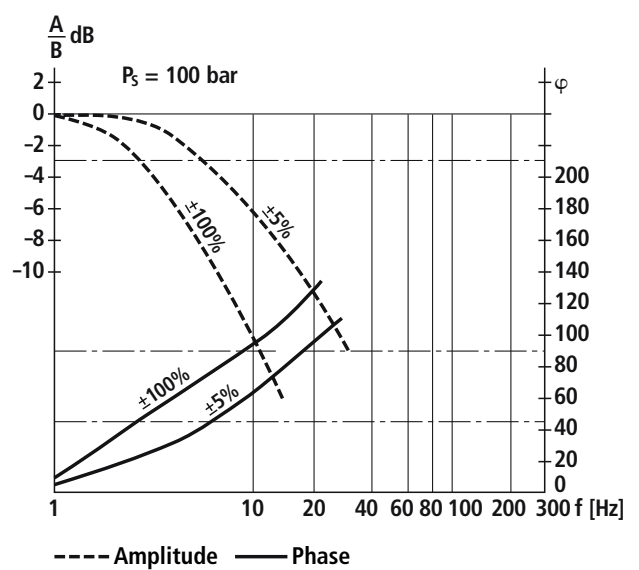
**NG16**



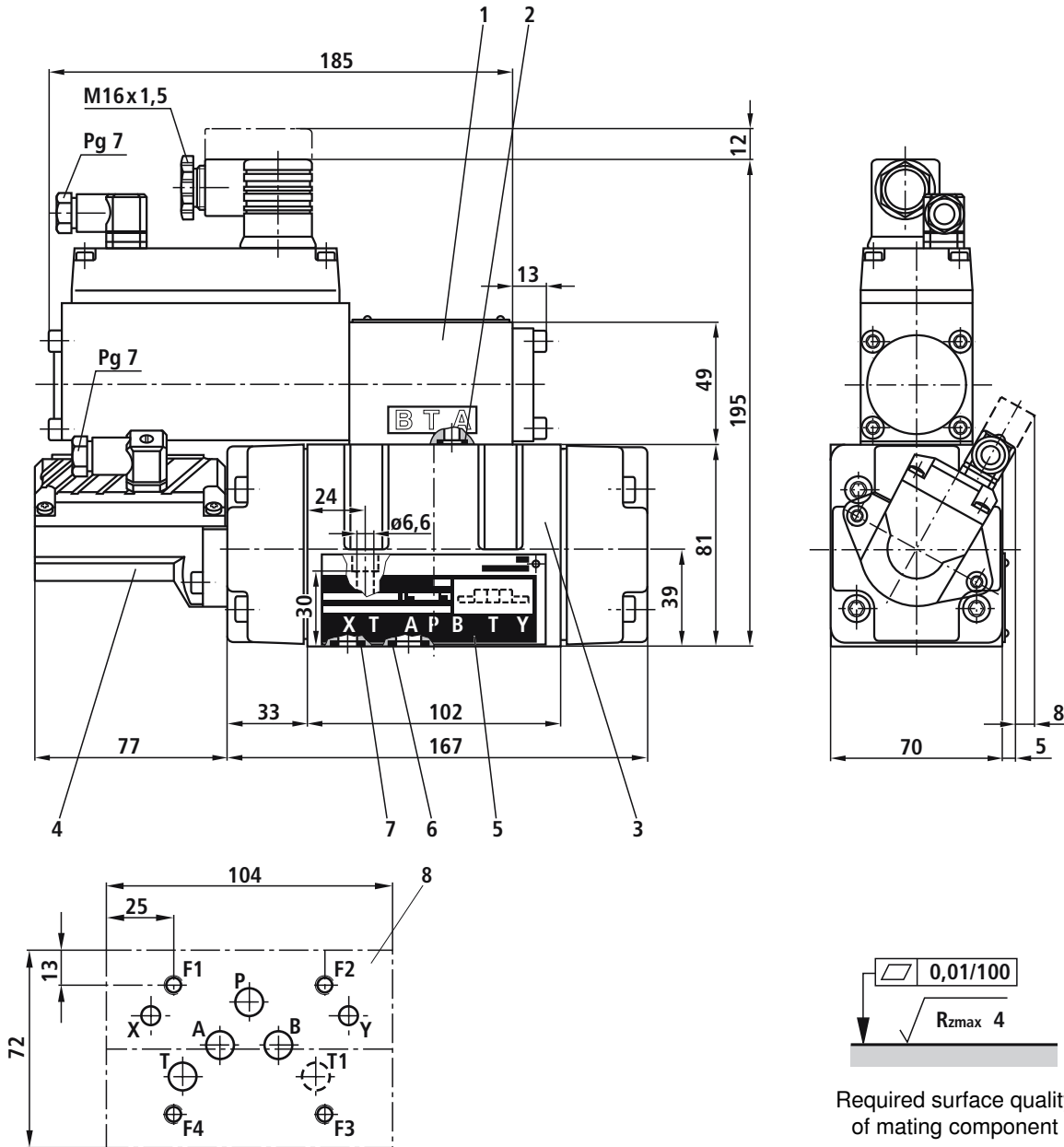
**NG25/27**



**NG35**



## Unit dimensions NG10 (nominal dimensions in mm)



- 1 Pilot valve
- 2 O-ring 9.25 x 1.78 (ports P, A, B, T)
- 3 Main valve
- 4 Inductive position transducer (main valve)
- 5 Nameplate
- 6 O-ring 12 x 2 (ports P, A, B, T, T1)
- 7 O-ring 10 x 2 (ports X, Y)

- 8 Machined valve contact surface, mounting hole configuration according to ISO 4401-05-05-0-05

Deviates from standard:

Ports P, A, B, T, T1  $\varnothing$  10.5 mm

Minimum thread depth: Ferrous metal 1.5 x  $\varnothing$

Non-ferrous 2 x  $\varnothing$

**Subplates**, see Technical Data Sheet RE 45055

**Valve fastening bolts** (order separately)

The following valve fastening bolts are recommended:

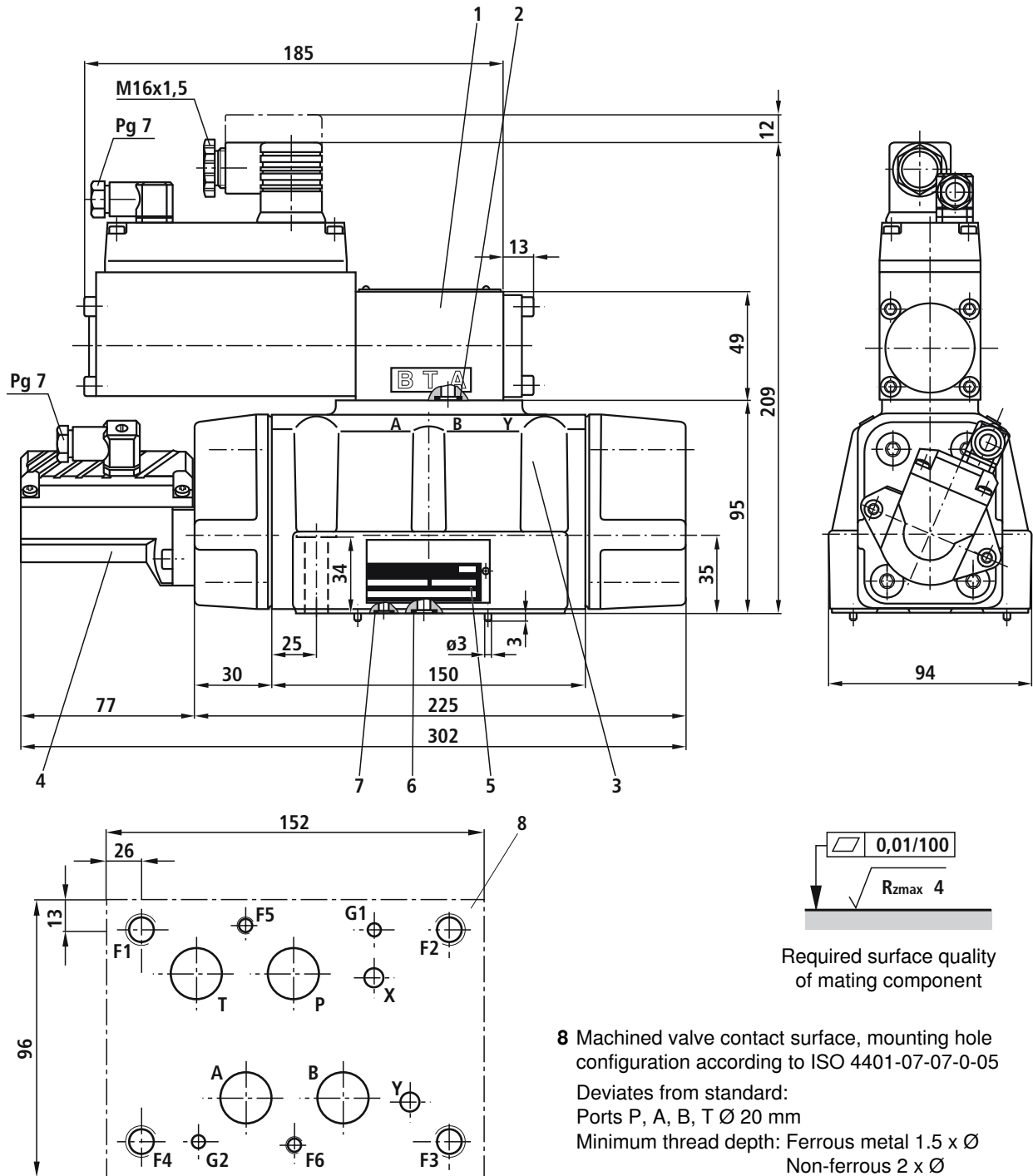
**4 cheese-head bolts ISO 4762-M6x40-10.9-N67F821 70**

(galvanized in accordance with Bosch standard N67F821 70)

Tightening torque  $M_A = 11+3$  Nm

Material no. **2910151209**

## Unit dimensions NG16 (nominal dimensions in mm)



- 1 Pilot valve
- 2 O-ring 9.25 x 1.78 (ports P, A, B, T)
- 3 Main valve
- 4 Inductive position transducer (main valve)
- 5 Nameplate
- 6 O-ring 23 x 2.5 (ports P, A, B, T)
- 7 O-ring 9 x 2 (ports X, Y)

8 Machined valve contact surface, mounting hole configuration according to ISO 4401-07-07-0-05

Deviates from standard:

Ports P, A, B, T  $\varnothing$  20 mm

Minimum thread depth: Ferrous metal 1.5 x  $\varnothing$

Non-ferrous 2 x  $\varnothing$

Subplates, see Technical Data Sheet RE 45057

Valve fastening bolts (order separately)

The following valve fastening bolts are recommended:

**2 cheese-head bolts ISO 4762-M6x45-10.9-N67F821 70**

(galvanized in accordance with Bosch standard N67F821 70)

Tightening torque  $M_A = 11+3$  Nm

Material no. 2910151211

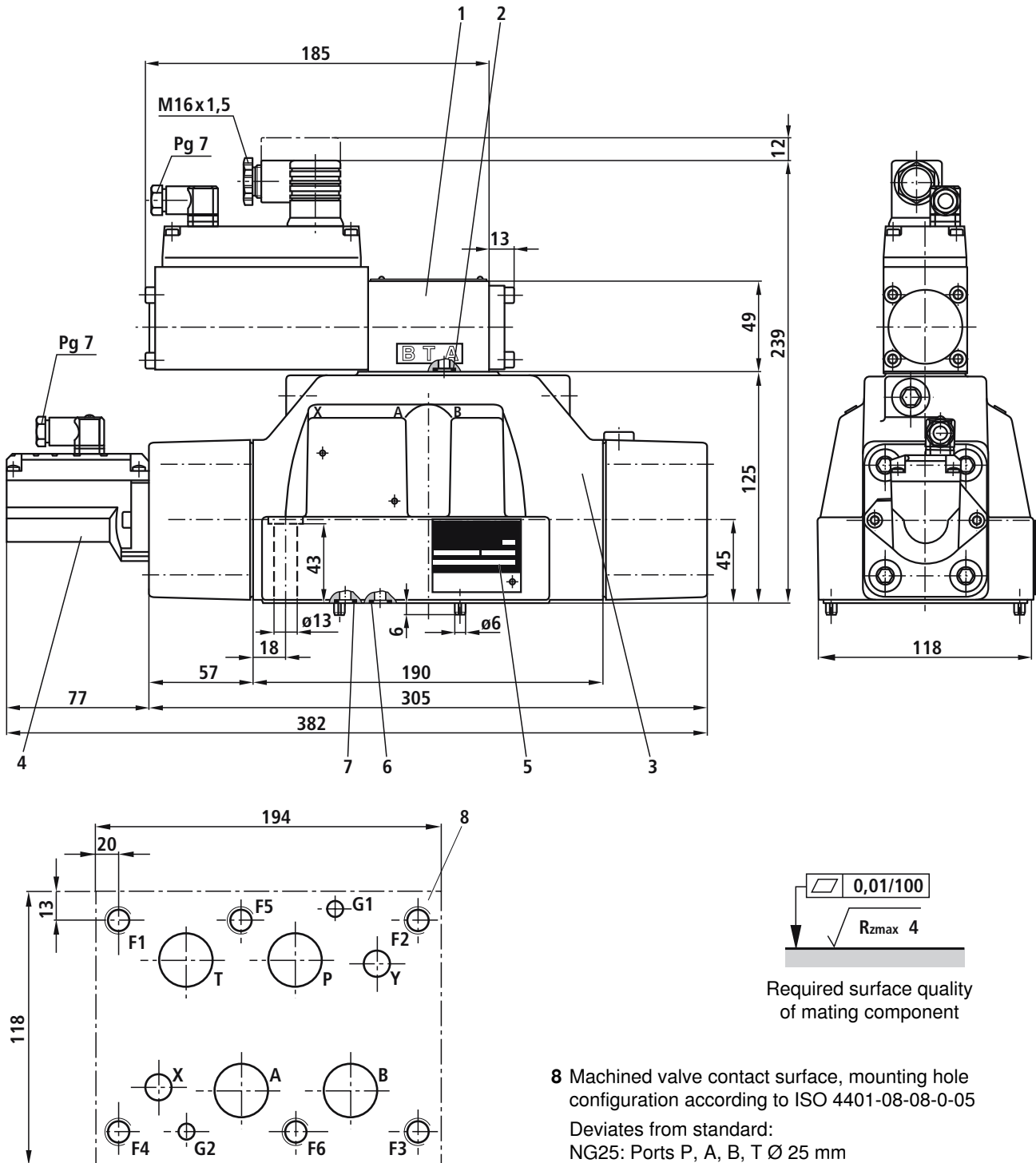
**4 cheese-head bolts ISO 4762-M10x50-10.9-N67F821 70**

(galvanized in accordance with Bosch standard N67F821 70)

Tightening torque  $M_A = 50+10$  Nm

Material no. 2910151301

## Unit dimensions NG25/27 (nominal dimensions in mm)



- 1 Pilot valve
- 2 O-ring 9.25 x 1.78 (ports P, A, B, T)
- 3 Main valve
- 4 Inductive position transducer (main valve)
- 5 Nameplate
- 6 O-ring (ports P, A, B, T)  
NG25: 28 x 3  
NG27: 34.6 x 2.62
- 7 O-ring 15 x 2.5 (ports X, Y)

8 Machined valve contact surface, mounting hole configuration according to ISO 4401-08-08-0-05

Deviates from standard:

NG25: Ports P, A, B, T  $\varnothing$  25 mm

NG27: Ports P, A, B, T  $\varnothing$  32 mm

Minimum thread depth: Ferrous metal 1.5 x  $\varnothing$

Non-ferrous 2 x  $\varnothing$

**Subplates**, see Technical Data Sheet RE 45059

**Valve fastening bolts** (order separately)

The following valve fastening bolts are recommended:

**6 cheese-head bolts ISO 4762-M12x60-10.9-N67F821 70**

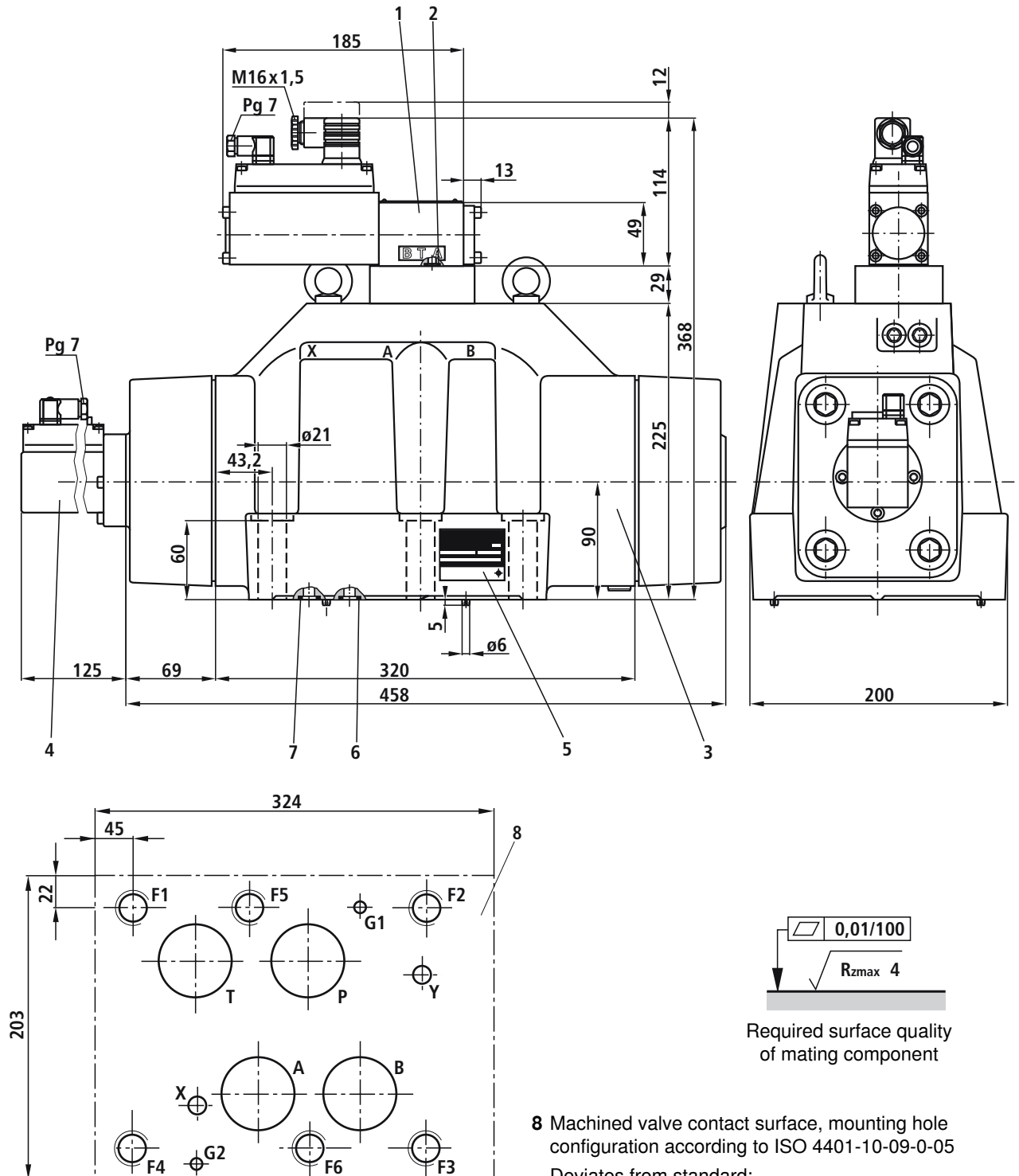
(galvanized in accordance with Bosch standard N67F821 70)

Tightening torque NG25  $M_A = 90+30$  Nm,

NG27  $M_A = 90\pm 15$  Nm

Material no. **2910151354**

## Unit dimensions NG35 (nominal dimensions in mm)



- 1 Pilot valve
- 2 O-ring 9.25 x 1.78 (ports P, A, B, T)
- 3 Main valve
- 4 Inductive position transducer (main valve)
- 5 Nameplate
- 6 O-ring 53.57 x 3.53 (ports P, A, B, T)
- 7 O-ring 15 x 2.5 (ports X, Y)

**8** Machined valve contact surface, mounting hole configuration according to ISO 4401-10-09-0-05

Deviates from standard:  
Ports P, A, B, T  $\varnothing$  48 mm

Minimum thread depth: Ferrous metal 1.5 x  $\varnothing$   
Non-ferrous 2 x  $\varnothing$

**Subplates**, see Technical Data Sheet RE 45060

**Valve fastening bolts** (order separately)

The following valve fastening bolts are recommended:

**6 cheese-head bolts ISO 4762-M20x90-10.9-N67F821 70**  
(galvanized in accordance with Bosch standard N67F821 70)  
Tightening torque  $M_A = 450 + 110 \text{ Nm}$

Material no. **2910151532**

## Notes

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