

## Introduction

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(<https://www.dfrobot.com/product-1029.html>)

Multiplexer is a multi protocol converter which is composed by multiple interfaces for using controller communication. Multiplexer supports conversion interfaces among USB, TTL, RS232, RS485, and allows to have one input and multiple outputs. It's more convenient for many kinds of controllers to communication.

## Specification

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### Power Supply

Supply Voltage is 5V , and is divided into two way.

- 1.via Micro USB data wire.
- 2.Any pin 5V .
- *Note\**: please do not plug two or more 5V to avoid to burn the chip. And, do not connect 5V if already connected from Micro USB.

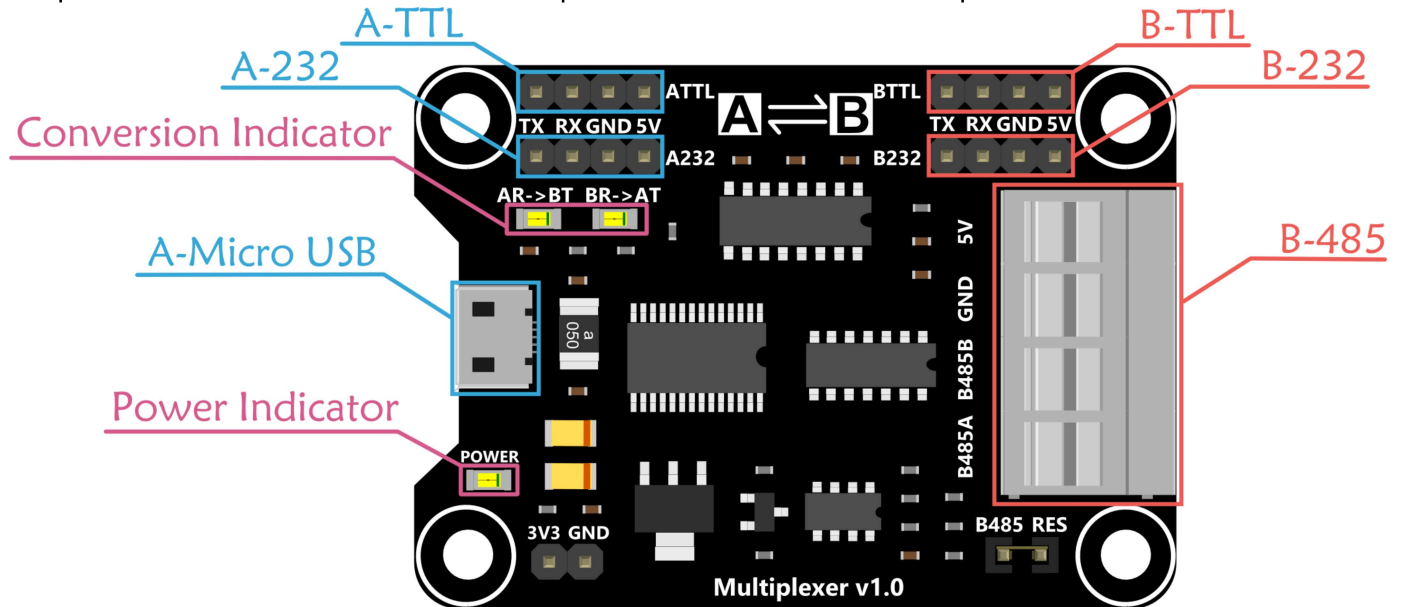
### PIN Function Description

#### Points to note:

- Multiplexer board is divided into Area A and Area B. Area A includes Micro USB、 ATTL and A232 interfaces. Area B includes BTTL、 B232、 B485 interfaces. The signal can be converted between A and B.

- The signal in the same area can't be converted. For example, A-TTL can't be converted to A232, but it can be converted to B232.
- Only one input in the same area, but it allows to have multiple outputs. For example, if micro USB interface in A is input, multiplexer can be allowed to have 232, 485 and TTL as outputs.

Indicator: **POWER**: power indicator **AR->BT**: The interface in A as input, the interface in B as output **BR->AT**: The interface in B as input, the interface in A as output



## Tutorial

### Requirements

Sample description: The multiplexer board achieves USB to TTL, micro USB interface in A as input and the TTL interface in B as output. The operation is the same for USB to 232 and 485. Similarly, the reverse converter B to A is also feasible, such as 232 to USB, 485 to USB, TTL to USB.

- **Hardware**
  - DFRduino UNO R3 (<https://www.dfrobot.com/product-838.html>) x 1
  - USB Cable A-B for Arduino (<https://www.dfrobot.com/product-134.html>) x 1
  - Micro USB Cable (<https://www.dfrobot.com/product-770.html>) x 1
  - Arduino Jumper Cables x 1
- **Software**
  - Arduino IDE (<https://www.arduino.cc/en/Main/Software>)
  - Download and install the Library installation (<https://www.arduino.cc/en/Guide/Libraries#.UxU8mdzF9H0>)

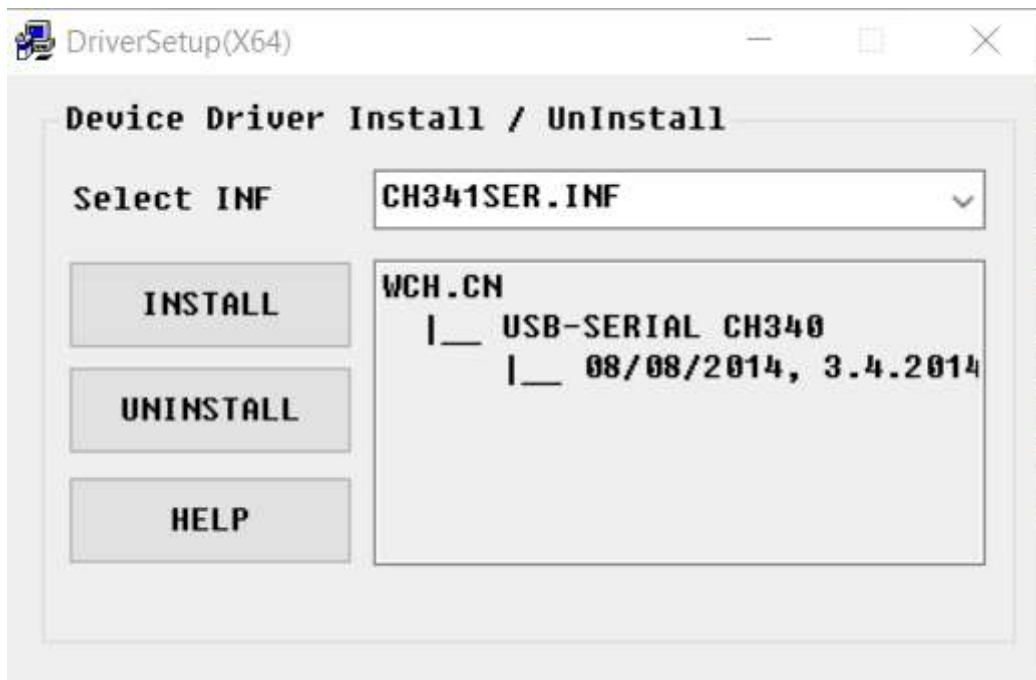
### Connection Diagram

1. Plug in Micro USB cable to multiplexer board. The "POWER" LED turns on at the same time.

2. Driver Installation: V1.0 uses FT232RL USB to TTL chip, please click here to download Driver

- 2. Driver installation. V1.0 uses FT232R USB to TTL chip, please click here to download Driver (<http://www.ftdichip.com/Drivers/VCP.htm>). V2.0 uses CH340 USB to TTL chip, please [click here to download Driver] ([https://github.com/Arduinolibary/DFRobot\\_FireBeetle\\_ESP8266\\_DFR0489/raw/master/CH340](https://github.com/Arduinolibary/DFRobot_FireBeetle_ESP8266_DFR0489/raw/master/CH340))
- 0 ([https://github.com/Arduinolibary/DFRobot\\_FireBeetle\\_ESP8266\\_DFR0489/raw/master/CH340](https://github.com/Arduinolibary/DFRobot_FireBeetle_ESP8266_DFR0489/raw/master/CH340)) Driver.zip)

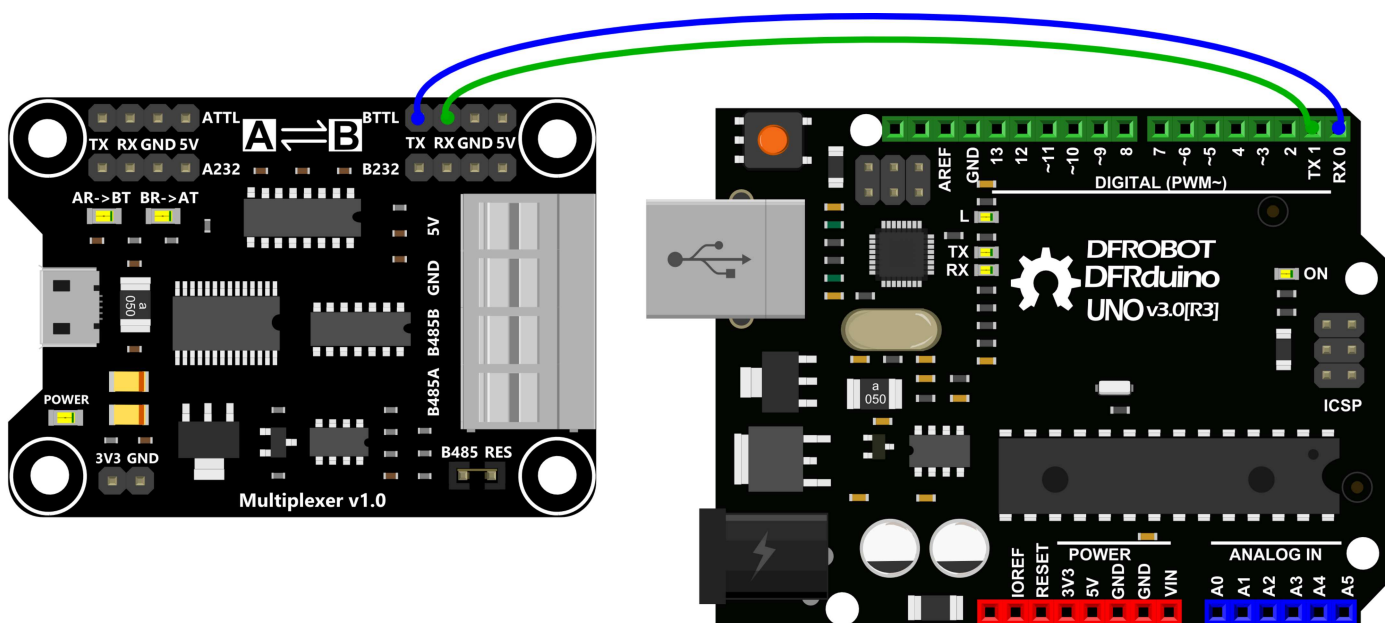
**Note:** CH340 driver is free to install for most of Windows OS, if you find there is no COM Port in Device Manager, please download the driver and install it.



After the driver

installed completed, please open *Control Panel -- Device Manager* in your PC. You will see a new port.

- 3. According to the following connection diagram, connect it.
- 4. Plugin the A to B USB to UNO



## Sample Code

```

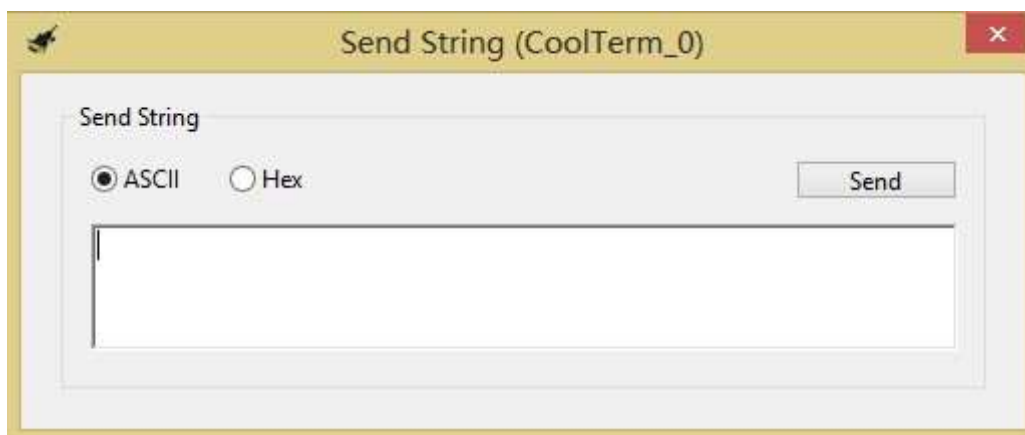
void setup()
{
  Serial.begin(115200);
}
void loop()
{
  if(Serial.available()){
    Serial.write(Serial.read());
  }
}

```

## Expected Results

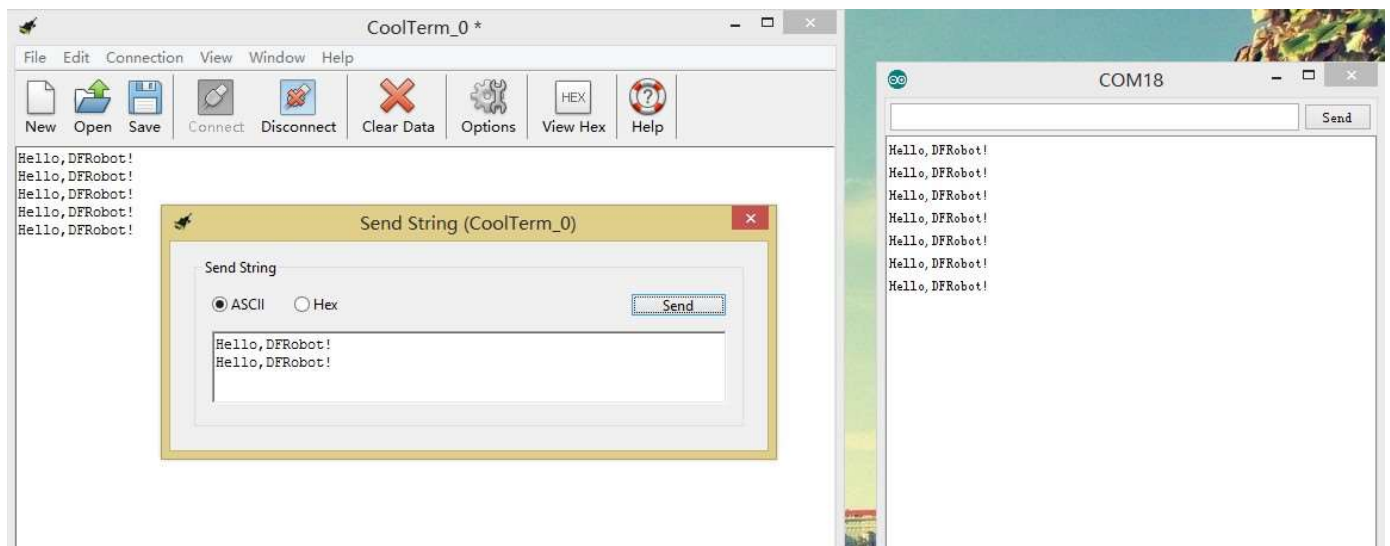
We need a serial monitor for monitoring data. There're lots of good tools like putty, CoolTerm and so on. In this case, we choose CoolTerm (<http://freeware.the-meiers.org/>) to do this.

Please set the baud rate to 115200 bps and com port. Back to the main interface, click **Connection--Send String**, the following dialog will open.



You can send the string

in this dialog. The string received can be showed in the other port(UNO port).





Thus far, you achieve the function USB to TTL. However, you can test reversed converter based on this function, being B to A converter. You only need to change the UNO code. You will see the change that coolterm will receive data from UNO.

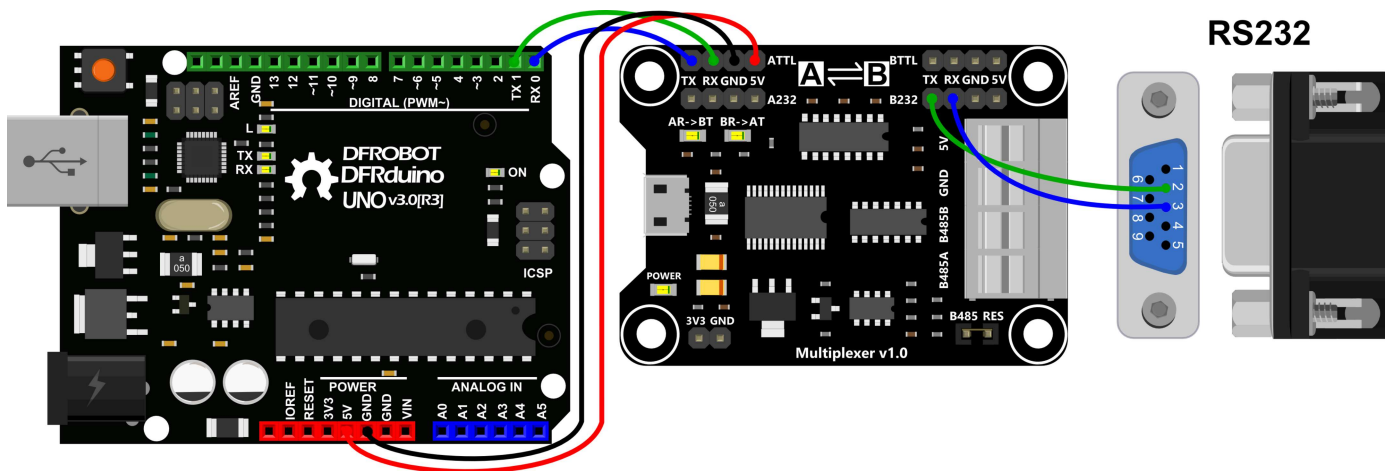
**Refer to the test code:**

```

void setup()
{
  Serial.begin(115200);
}
void loop()
{
  Serial.print("Hello,DFRobot! ");
  Serial.println();
  delay(500);
}
    
```

**Other Reference Connection**

**1.TTL to 232 converter**

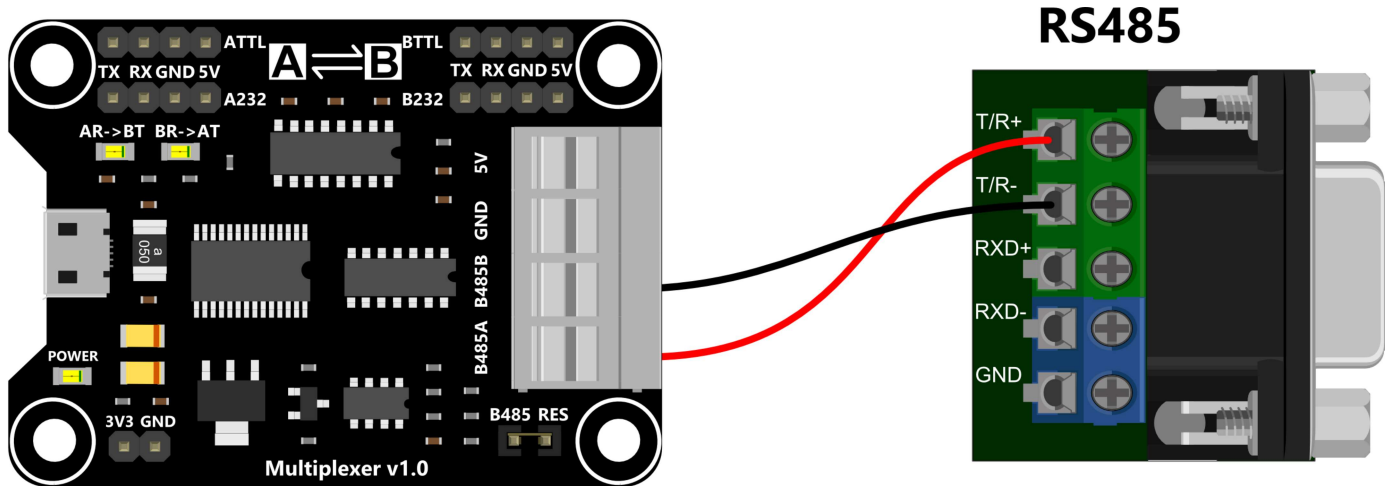


PIN	RS-232
1	DCD
2	RXD
3	TXD
4	DTR
5	GND
6	DSR

6	DSK
PIN	RS-232
7	RTS
8	CTS

9	RI

## 2.USB to 485 converter




## FAQ

Q&A	Some general Arduino Problems/FAQ/Tips
A	For any questions, advice or cool ideas to share, please visit the <b>DFRobot Forum</b> ( <a href="https://www.dfrobot.com/forum/">https://www.dfrobot.com/forum/</a> ).

## More Documents

Schematic V3.0 ([https://github.com/DFRobot/Wiki/blob/master/En-wiki-images/%5BTTEL0070%5DMultiplexer\(V3.0\).pdf](https://github.com/DFRobot/Wiki/blob/master/En-wiki-images/%5BTTEL0070%5DMultiplexer(V3.0).pdf))

 Get **Multi USB/RS232/RS485/TTL Converter V2.0** (<https://www.dfrobot.com/product-1029.html>) from DFRobot Store or **DFRobot Distributor**. (<https://www.dfrobot.com/index.php?route=information/distributorslogo>)

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