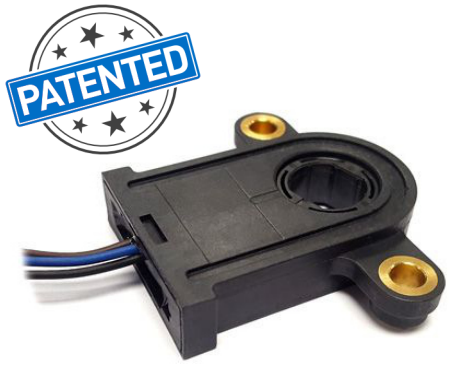
Enabling the Electronics Revolution

PIHER sensing systems
an Amphenol® company

PST-360

Hall-Effect Through-Shaft Rotary Position Sensor



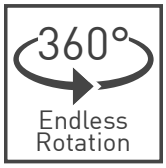
Available with
CAN SAE J1939

CE

KEY FEATURES

True, contactless operation
Without any gears or mechanical interfaces the sensor is easily assembled and calibrated and subject to limited wear and tear over lifetime.

Through-hole design
Allows shaft insertion from top or bottom, simple assembly and makes it even more suitable in applications where space is limited.



360 degree absolute position feedback
Endless mechanical rotational angle without dead band, keeps the position on power loss with programmable electrical angles from 15 to 360 degrees.

Made for harsh environments
The rugged package protects the sensor from dust, moisture, vibration and extreme temperatures for usage in the most demanding environments.

Durable and robust design
The non-contacting design allows for an extra-long product lifetime of up to 50 million cycles.

Adaptable to your requirements
Programmable transfer function and switch outputs as well as different output protocols and redundancy levels available.

DESCRIPTION

The PST-360 position sensor combines a through-shaft design with accurate absolute position feedback and a true non-contacting sensing element that does not rely on gears or other rotating parts.

This innovative and unique patented design complements the attributes of the target application and maintains the mechanical integrity of the application by design. As the sensor is mounted directly at the pivot point no levers, connecting rods or other mechanical interfaces are needed. Furthermore it adapts to shaft's eccentricity, mounting tolerances and mechanical wear over the life of the application.

The endless rotation sensor is highly configurable with a programmable angular range between 15 and 360 degrees, different signal output options and support for low and high-voltage power supply. Multi-turn configurations are available on request.

APPLICATIONS

Industrial
- ▶ Autonomous warehouse robotics
- ▶ Robotics and automation feedback
- ▶ Robot arm position
- ▶ Valve monitoring
- ▶ Conveyor operation

Transportation
- ▶ Steering angle
- ▶ Pedal position
- ▶ Fork height and mast tilt
- ▶ Bucket position
- ▶ Hitch position
- ▶ Boom angle
- ▶ Joystick controls

Marine
- ▶ Steering and shifter sensor
- ▶ Engine throttle

Home and Building Automation
- ▶ HVAC systems

Medical
- ▶ Electric hospital bed
- ▶ Mobility chair steering and throttle

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MECHANICAL SPECIFICATIONS

Rotational life	Up to 50.000.000 cycles
Mechanical angular range	360° (endless rotation)
Rotor diameter[1]	14mm 17mm

[1] Other rotors on request

ELECTRICAL SPECIFICATIONS

Linearity[1]		±1% absolute (±0.5% upon request)
Electrical angular range[2]		Programmable from 15° to 360°
Output		Analog (Ratiometric), PWM Serial Protocol (SPI) CAN SAE J1939 or SENT upon request
Switch output		Programmable upon request
Resolution	Analog, PWM SPI	Up to 12 bit Up to 14 bit
Supply voltage[3]		5V ±10% 7V to 15V
Supply current	Single version Redundant version	Typ 8.5 mA Typ 17 mA
Voltage protection		±10 V
Self-diagnostic features		yes

[1] Ferromagnetic materials close to the sensor (i.e. shaft, mounting surface) may affect the sensor's linearity.
[2] For information on multi-turn sensors please contact Piher
[3] Voltages up to 25 V possible on request.

ENVIRONMENTAL SPECIFICATIONS

Operating and storage temperature[1]	-40°C to +125°C
Shock	50g
Vibration	5-2000 Hz; 20g; Amax 0,75 mm
Sealing[2]	IP67, IP69K
Approval	CE[3]

[1] Other specifications available
[2] IP rating on electronics
[3] EMC-testing according to standards EN 61000-6-2 and EN 6100-6-3. CE-approval applies to analogic-simple and analogic-redundant models.

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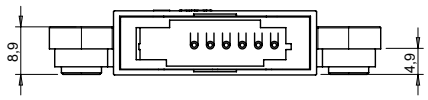
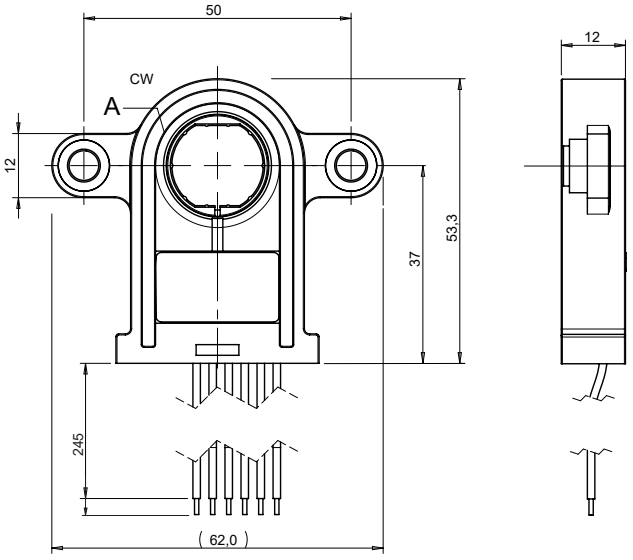
DIMENSIONS (MM)

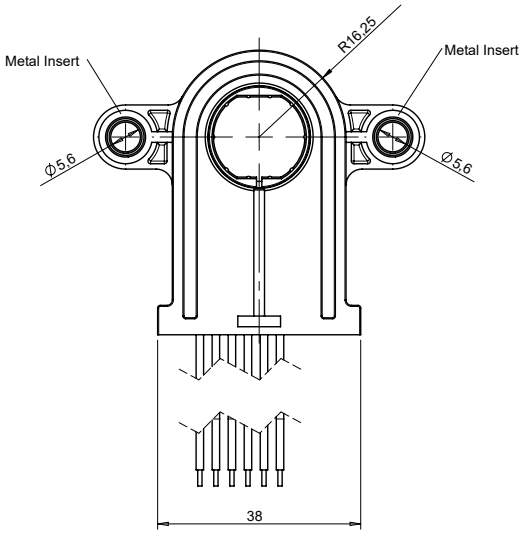
Outer Dimensions



Download the STEP file here:
https://piher.net/piher/?p=838

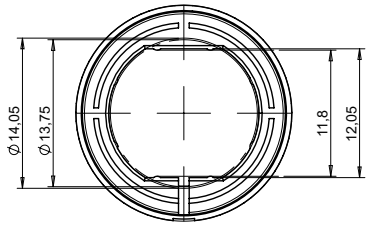
Shaft should be non-ferromagnetic material. If you want to use a ferromagnetic shaft please contact Piher.



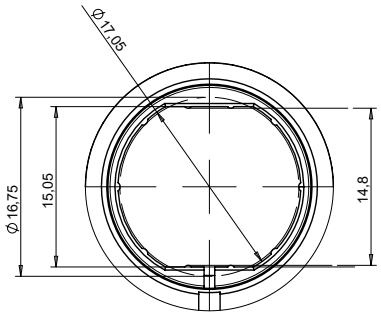


Sensor shown above is the 17mm version with the rotor at zero position. Sensor is delivered at random position. Wires: 0.35mm² TXL SAE J1128

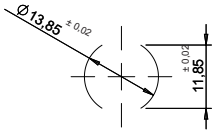
14mm rotor

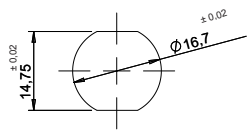


17mm rotor



Recommended shaft dimensions





CONNECTION SCHEME

Color	Simple output	Redundant output	Full-redundant output
Brown	Power supply	Power supply	Power supply 1
Blue	Ground	Ground	Ground 1
Black	Signal output	Signal output 1	Ground 2
White	n/a	Signal output 2	Signal output 2
Red	n/a	n/a	Power supply 2
Yellow	n/a	n/a	Signal output 1

More instructions of use on www.piher.net. Connector assembly available on request.

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HOW TO ORDER (Example: PST360G2-1A-C0001-ERA190-05K)

Simple Output - Analogic and PWM

PST360G2 - _ 1 _ - C_____ - ERA___ - __ K - _____

Series	Rotor[1]	Type	Output[2]	Output function[3]	Electric rotational angle[4]	Voltage supply[5]	Temp. range	PWM Frequency Hz[6]
	[empty] = 14mm B = 17mm	1 = simple	A = analogic P = PWM	C0000 C0001	ERA040 ERA041 ... ERA360	05 = 5V ±10% RE = 7V-15V	K = -40°C to +125°C	[empty] = 200Hz F100 = 100Hz F101 = 101Hz ... F999 = 999Hz

Simple output - SPI

PST360G2 - _ 1 S - C_____ - ERA___ - __ K

Series	Rotor[1]	Type	Output[2]	Output function[3]	Electric rotational angle[4]	Voltage supply[5]	Temp. range
	[empty] = 14mm B = 17mm	1 = simple	S = SPI	C0000 C0001	ERA040 ERA041 ... ERA360	05 = 5V ±10% RE = 7V-15V	K = -40°C to +125°C

Redundant output - Analogic and PWM

PST360G2 - _ 2 __ - C_____ - ERA___ - __ K - _____ _____

Series	Rotor[1]	Type	Output[2]	Output function[3]	Electric rotational angle[4]	Voltage supply[5]	Temp. range	PWM Frequency Hz. (1)[6]	PWM Frequency Hz. (2)[6]
	[empty] = 14mm B = 17mm	2 = redundant	AA= analogic PP = PWM	C0002 C0003	ERA040 ERA041 ... ERA360	05 = 5V ±10% RE = 7V-15V	K = -40°C to +125°C	F100 F101 ... F999	F100 F101 ... F999

Full-redundant output - Analogic and PWM

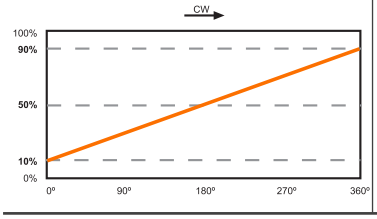
PST360G2 - _ 3 __ - C_____ - ERA___ - 05 K - _____ _____

Series	Rotor[1]	Type	Output[2]	Output function[3]	Electric rotational angle[4]	Voltage supply	Temp. range	PWM Frequency Hz. (1)[5]	PWM Frequency Hz. (2)[5]
	[empty] = 14mm B = 17mm	3 = full-redundant	AA= analogic PP = PWM	C0002 C0003	ERA040 ERA041 ... ERA360	05 = 5V ±10%	K = -40°C to +125°C	F100 F101 ... F999	F100 F101 ... F999

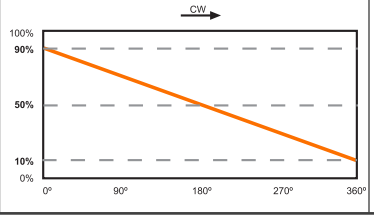
1 Other rotors available on request.
2 The analog output is ratiometric, proportional: - for supply voltage "5V" to input voltage; -for supply voltage "RE" to 5V.
3 Other output functions available, please check availability. Enter CXXXX as long as the new output function is not defined.
4 Models with ERA ‹ 40° available on request
5 Voltages up to 25V possible on request.
6 Leave empty if not applicable. Default frequency is 200 Hz

EXAMPLE OUTPUT FUNCTIONS

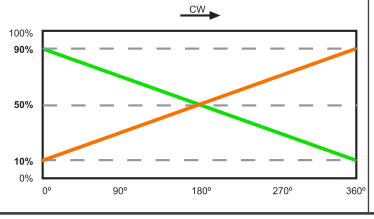
C0000 (simple)



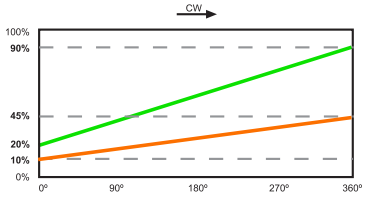
C0001 (simple)



C0002 (redundant)



C0003 (redundant)



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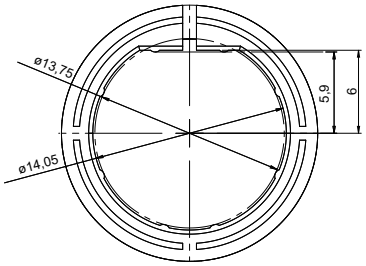
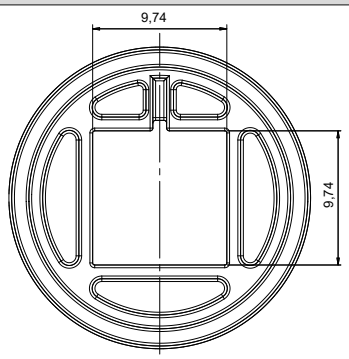
SPECIAL ROTORS

Ref. 3457	Ref. 3458
	

For more information visit: www.piher.net

MOUNTING INSTRUCTIONS

1. Place the component on a flat surface.
2. Fit the shaft of the application (see recommended shaft dimensions) through the sensor's rotor avoiding any mechanical play/wobble.
3. Fasten the two M5 screws (M5 washers are recommended).

OUR ADVANTAGE

- Leading-edge innovative position sensing solutions
  - Contactless (Hall-effect and Inductive Technology)
  - Contacting (Potentiometers, Printed Electronics)
- Engineering design-in support
- All our products can be customized to fit target application and customer requirement
- Capability to move seamlessly from development to true high-volume production
- A global footprint with global engineering and commercial support
- One-stop shop not limited to position sensors (temperature, pressure, gas,...) through group collaboration
- Flexibility and entrepreneurship of a medium-sized company with the backing of Amphenol Corporation

IATF 16949 Automotive Quality Management CERTIFIED · ISO 9001 Quality Management Systems CERTIFIED · ISO 14001 BUREAU VERITAS Certification · RoHS REACH compliant

Please always use the latest updated datasheets and 3D models published on our website.

CONTACT

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